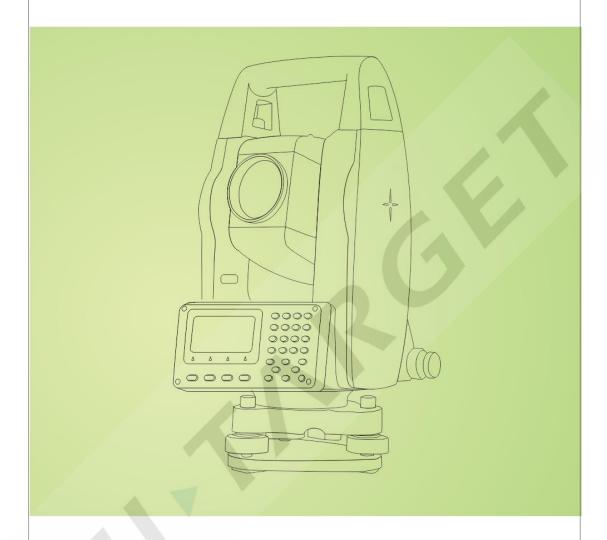
HI $\rightarrow T$ $\wedge RGET$



HTS-420R Total Station Manual

Preface

Thanks a lot for purchasing our total station!

This manual is your good helper, please read it carefully before using the instrument and keep it safely.

Product affirms:

In order to get the best service from our company, please feedback your instruments' version including number, purchasing date and your suggestions to us after the purchasing of the product.

We will attach great importance to any piece of advice from you,

We will be very concerned about any detail of our products,

We will make great efforts to provide better quality.

Notice: Our Company has the right to upgrade and improve the technical parameters of instruments, which may not be announced in advance. The pictures in the manual are only for reference and kind prevail.

• Features:

Rich Feature: Our Total Station is equipped with a wealth of measurement applications including data storage, parameter settings and other functions for a

1. Absolute coded dial

With absolute digital dial, instruments can be measured directly when it powers on. The measured azimuth angle result will not be lost even when the instrument shut off.

2. powerful memory management

Large-capacity EMS memory, easy to manage the file system, serving to add, delete and transfer data

3. No prism ranging

The series Total Station HTS-220R with laser ranging No-Prism is capable of surveying for long distance, fast and precise measurements with various materials and different colors of objects (such as building walls, poles, wires, cliff wall, mountain, mud, stakes, etc.). For those which are hard or impossible to be reached, the application of Prism features can be a good measurement tasks.

4. special measurement procedure

The series total station is equipped with the basic surveying function as well as special measurement procedures, undertaking REM, offset measuring, stakeout, Resection, area measurement and calculation, road design etc. to meet the needs of professional measurement.

5. eyepiece changeable

The instruments' eyepiece can be changed, and equipped with a diagonal eyepiece, serving to observe zenith and high buildings

6. An optional laster plumb

The site features is easy to instruct and set up stations

NOTE:

Avoid look directly into the sun with the eyepiece when measuring. Recommended to use solar filter to reduce the impact

- 1. Avoid extreme temperature when storing equipment and sudden changes in temperature when using the instrument.
- 2. The instrument should be loaded in box placed in dry and ventilated place and prevented from shock, dust and moisture when it is not in use.
- 3. In order to get good accuracy, you should leave the instrument in the box if the instrument temperature has large difference between working and storing you may unpack the box and employ the instrument until the instrument reaches the temperature at the working field.
- 4. If the instrument is not used for a long time, the battery should be unloaded and stored separately and charged once a month to prolong battery life.
- 5. The instrument should be installed in box when it is transported. Extrusion, collision and violent vibration need to be carefully avoided during the transport process. The soft mat May be placed around the box on the long-distance transportation.
- 6. It is better to use high quality wooden foot stool to make sure the stability of measurement and improve its accuracy, when setting up the instrument.
- 7. Only use absorbent cotton or lens paper to wipe the instrument gently If exposed optical device need to be cleaned.
- 8. Use flannelette or hairbrush to clean the instrument after using. Do not electrify and start up after the device got wet in a rain. Using clean soft cloth to wipe it dry and put it at ventilated place for a period of time to make the instrument fully dry before using or packing.
- 9. Inspect instrument carefully and comprehensively to ensure its indicators, function, power supply, initial setting and correction parameters meet the requirements before operating.
- 10. If the function is abnormal, non-professional maintenance persons are not allowed to dismantle the device without authorization in case of any unnecessary damage.
- 11. The emitted light of the no-prism total station HTS-220R is laser, do not direct to eyes.

Security Guide

Pay attention to the following safety matters when you use the laser ranging free of prism.

Warning:

Total station fit out laser level 3R/IIIa which is recognized by the loge, which is above:

the vertical locking screw saying: "3A laser product". This product belongs to Class 3R level laser . According to the following standards IEC 60825-1: 2001 Class 3R/IIIa laser product can reach five times of emission limits of the Class 2/II in the wavelength between 400nm-700nm.

Warning:

Continuous stare into the laser beam is harmful.

Prevention:

Do not stare at laser beam Or point to others The reflected beams is the effective signal of the instrument. It's safety to observe by eyepice.

Warning:

When the laser beam is irradiated reflected by prisms, plane mirrors, surface of metal and windows, it's dangerous to look straight into the reflected beams.

Prevention:

Don't stare at the reflected beams. When the laser is switched on (distance mode), do not obstruct optical path or stand near the prism. Target at a prism with total station telescope only.

Warning:

It's dangerous to use the Class 3R laser device inproperly.

Prevention:

To avoid injury, each user must carry safety prevention measures and operate the instrument within the safety scope according to standard IEC60825-1: 2001).

The following is the explanation of the main part of the standard:

Class 3R level raser products are used outdoors and in construction (surveying with No-Prism).

A: Only trained and certified personnels are allowed to install, adjust and operate the laser equipment.

B: set up appropriate laser warning sign within the operating field

C: To prevent anyone from looking into the laser beam use an optical instrument to observe.

D: in order to prevent laser damage to persons, the laser beams should be blocked at the end of the working route, and also should be cut off when people work in the restricted area (harmful distance) where laser beams crossing are harmful.

E: the route of the laser beam must set to be higher or lower than the human eye.

F: properly store and safekeep the laser products when they it is not used, unauthenticated personals are not allowed using it.

G: Do not point laser beams at surfaces such as plane mirror, metal surface, window, especially the surface of plane mirror and concave mirror.

Harmful Distance is the maximum distance from the starting point of the laser beams to where people are right safe. The built-in harmful idstance of the Class 3R/ IIIa laser is 1000m(3300ft) and the laser intensity will reduce to that of Class 1 products (which does not harm eyes) if people is out of this range.

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1. Name and function of each part

1. Name





2. Keys Functions and information display



Кеу	Function	
0	Power ON/ Power OFF.	
MEAS	Trigger key, depends on setting, maybe disting & save,	
	disting or none.	
ESC	Cancel or exit.	
ENT	Confirm or commit editing.	
	Switch pages	
FNC	Hot key to enter function menu in measuring interface.	
A 1	User defined function key 1.	
User defined function key 2		
▲ Move cursor up or goto previous.		
▼	Move cursor down or goto next.	
◀	Move cursor left or goto left.	
>	Move cursor right or goto right.	
STU GHI	Entering letters A-Z.	
1 ~ 9		
0~9	Entering number or choose menu item.	
F1 ~ F4	Soft keys to choose screen bottom function.	

2. Preparation before measurement

1. Unpack and store instrument

Unpack

Put down the box gently and turn up the cover then turn on the lock, open the cover and take out the instrument.

Deposit

Cover up the telescope mirror and make the vertical motion of alidade upwards then put the instrument horizontally (keep the objective upwards) into box. Then screw vertical motion gently. Cover up the box cover and lock the box. Loose horizontal and vertical axis as much as possible to reduce he shock damage to instrument.

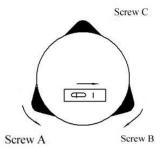
2. Setting up the instrument

If the battery is mounted after the instrument is set up, the instrument will tilt slightly. So, first mount the battery, then set the instrument up.

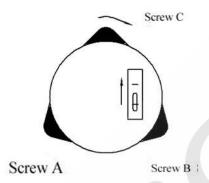
Operating reference

1. Centering and levelling

- 1) Setting up the tripod
 - ① Extend the tripod legs to provide a comfortable posture.
 - ② Setting up the tripod over the marked point on the ground, and center it.
- 2) Install the instrument on a tripod
 - ① Place the instrument on the tripod head.
 - ② Fix the instrument on the tripod.
- 3) Leveling instrument roughly by circular level
- ① Turn on the instrument and switch the laser plummet and the electronic level function on.
- ② Move the tripod legs and use the tirbrach screws to center the instrument over the ground point. Adjust the tripod legs to level the circular level.
- 4) Leveling instrument accurately by tube level
- ① Loosen the horizontal clamp, and turn the instrument until the plate level is parallel to the line between leveling foot screws A and B. Use leveling foot screws A and B to center the bubble.



② Rotate instrument 90° by vertical axis, then use foot screw C to center the bubble.



③ Repeat steps above until the bubble is at the same place in all directions.

2. Centering by centering tool (optional or laser)

1) Set up a tripod

Extend a tripod to the appropriate height make sure the legs are spaced at equal intervals and the head is approximately level .Set the tripod so that the head is positioned over the surveying point. Brace tripod on the ground and keep one leg fixed.

2) Set up instrument and spotting

Put instruments on a tripod carefully, and tighten the center connection screw. Adjust the optical centering tool to make reticule clear (open instrument and laser centering if it's a laser centering tool). Handle another two unfixed legs, and adjust their position through the observation of the optical plummet. Make the three legs of the tripod fixed on the ground when the optical plummet is aligned to the station approximately . Adjust three feet screws of total station and keep the optical centering tool (or laser centering) aiming at the station accurately.

- Leveling instrument roughly by circular level
 (Same as The section above that discusses centering and leveling with plumb bob)
- 4) Leveling instrument accurately by tube level (Same as The section above that discusses centering and leveling with plumb bob)
- 5) Centering and leveling accurately

Loosen center connection screw slightly and move instrument horizontally (Don't rotate instrument) through observation to optical plummet, making the

instrument aim at station accurately. Tighten the center connection screw and leveling instrument accurately again.

This operation should be repeated till the plumb aims at station accurately.

3. About the battery

Mounting the battery

- ☆ Fully charge the battery before measurement.
- ☆ Cut off the power before removing the battery.
- Step mounting the battery
 - 1. Insert the battery to the instrument.
 - 2. Press the top of the battery until you hear a click sound.
- ► Step Remove battery
 - 1. Press the button downward.
 - 2. Remove the battery by pulling it toward you.

Battery information

- — Power is adequate, operating available.
- The battery can be used for 4 hours when this symbol first appears. If you cannot master the consumed time, you should prepare a spare battery or charge the battery before using.
- — End of the operation as soon as possible and replace the battery and charge if running out of power.
- $oldsymbol{1}$ It takes several minutes for the instrument to shut down when this symbol first appears. The battery has few power now and should be replaced an recharged.

Notice:

- ① The operating time of battery depends on environmental conditions such as ambient temperature, time and times of charging and so on the battery is suggested to be prepared or charged ahead before operation to keep it safety.
- ② The battery symbol only indicates power capability undercurrent measurement mode. The remained capacity of the battery shown under current mode does not guarantee its capacity under other modes .Because consumption of power in distance measurement mode is more than that in angle measurement mode ,the instrument may end ranging sometimes due to insufficient capacity of battery (when switching between modes).

Notice in charging:

• Though overcharging protection is installed in the instrument, please plug off the battery immediately after finishing charging.

- Charging range from $0^{\sim}\pm45^{\circ}$ C. Abnormal responds of instrument occurs over this range.
- Rechargeable for 300—500 times, it may shorten Service time of the battery completely.
- Charge the battery once a month no matter if it is used to prolong its longevity.

4. Reflecting prism

When using a prism mode for measuring distance, reflection prism should be placed where the target is. A reflecting prism group includes one or three prisms that can connect prism group placed at the base of the tripod with the dock connector or by placing them in the stem directly. Prism group may need to be configured by users based on target.

5. Load or unload the base

Load

Put the three fixed feet in the corresponding bases, make the instrument in a triangular base, clockwise lock the button by 180° to lock the base, and then fix screw with a screwdriver to screw it out at a fixed lock knob.

Unload

If necessary, the triangle base can be removed from the instrument (including the same base of reflection prism base connector) by loosening the lock knob base fixed screw with a screwdriver, and anticlockwise locking button about 180° , then separate the instrument from base.

6. Adjust telescope objective and aiming target

Aiming method (reference)

- ① Rotate the telescope and point it to the bright sky and focus reticule clearly (by rotating eyepiece in own direction and focusing reticule slowly).
- ② Aim at the target with the crosswire in optical sight , and keep an appropriate distance when aiming (about 200mm).
 - ③ Use telescope focus screw to make target clear.

It means that focus or eyepiece diopter is not adjusted adjusted when there is a parallax with eye moving up and down ,thus focus carefully and adjust eyepiece to reduce parallax.

7. Input Mode

Total station keybord includes alpha/digit keys. User can input letters and numbers directly.

• Input box:

Each digit key defines 3 letters and 1 number. Depends on the properties of input box, input process varies.

Number input box:

In number input box, user can only input numbers, include "1-9", ".", "-+". Number will appear in box when user presses the key.

Text input box:

In text input box, user can input numbers and letters. Repeat pressing same key to get proper letter, such as A->B->C->7.

When right-bottom of screen display icon AB, user can input number/letter; when display icon 01, user can only input number. User can press soft-key [F4] to switch input mode between Number and Text when input box been active.

• Letters:

Letters that total station can input includes "A-Z/\$%_@&*?!+-.".

- ➤ Arrow key move inputing cursor.
- Pressing ENT enters editing; pressing ENT confirms input after editing.
- When editing distance, angle, temperature and pressure values that contain unit format, input box's text will convert into text without unit format. Such as angle 29° 32′ 56″ transforms into 29.3256; Distance 115.321 m transforms into

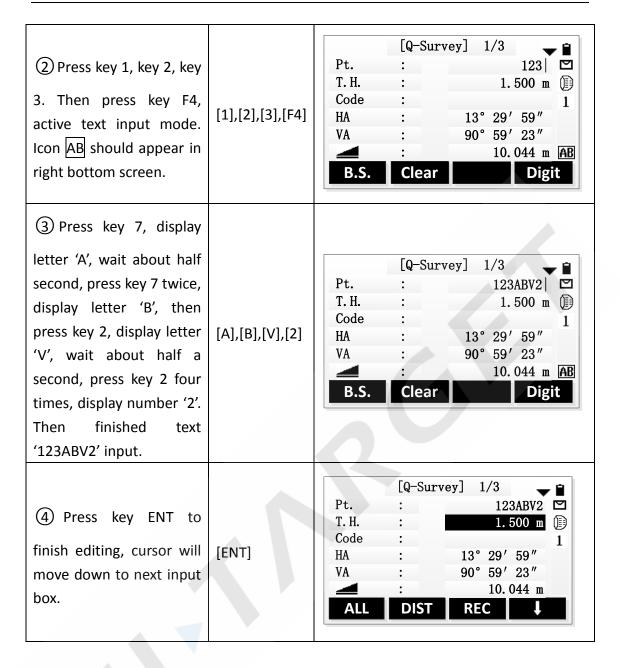
115.321. When finish editing, the text will automatic convert back.

7.1 Input characters

Each digit key defines 3 letters and 1 number. In text input mode, each time pressing the key, one character appears at cursor position. Number appears when pressing 4 times.

Example: input 123ABV2

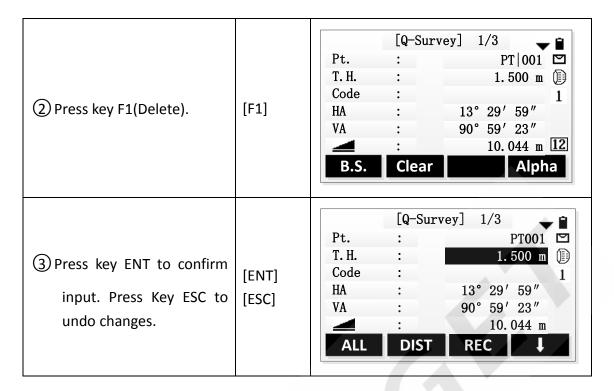
Step	Key	Display		
① Pressing key to start inputing. Right-bottom screen displaying icon 01 means in number input mode.		Pt. T. H. Code HA VA B.S.	[Q-Surv : : : : : Clear	1/3 1 2 1 500 m 1 1 1 1 1 1 1 1 1



7.2 Delete characters

Delete or clear input characters.

Step	Key	Display		
① Press key — to move cursor to right side of the character that to be deleted.	←	Pt. T. H. Code HA VA B.S.	[Q-Surv : : : : : Clear	ey] 1/3 PTT 001 PT 1.500 m 1 1 1 1 1 1 1 1 1



8. Point Search

Point search is a function used by applications to find measured or fixed points in the jobs.

Point search is limited to a particular job.

If several points meet the search criteria, then the results are ordered according to the date.

8.1 Direct search

By entering an actual point number (for example 'A1'), and pressing key SEARCH, all points within the selected job and with the corresponding point number are found.

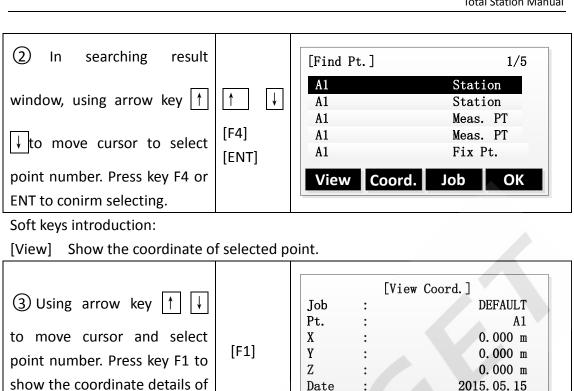
There are

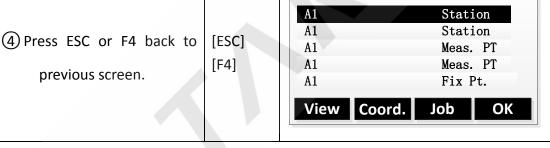
Here is an example for searching fix point in function 'Set STA'.

Step	Key	Display
(1) Choosing 'Survey' in application menu, then choose function 'Set STA'. Entering point number, for example 'A1', pressing ENT to finish input, then pressing F1 to search.	[F1]	[Set STA] Input STA PT! Station: A1 Find List Coord.

OK

1/5

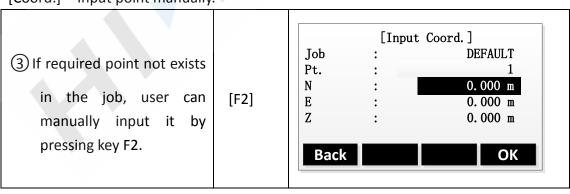


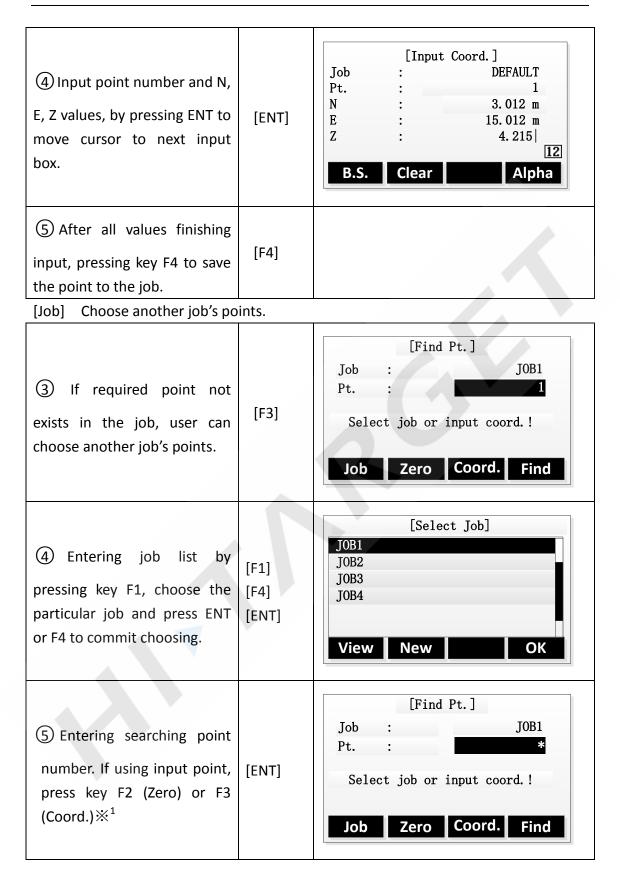


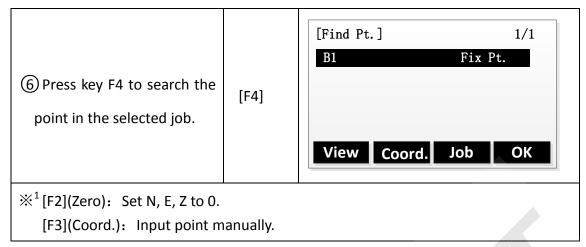
[Find Pt.]

[Coord.] Input point manually.

selected point.







[OK] Commit selected point.

8.2 Wildcard search

The wildcard search is indicated by a "*". The asterisk is a place holder for any following sequence of characters. Wildcards should be used if the point number is not fully known, or to search for a batch of points.

Examples:

- * All points are found.
- A All points with exactly the point number "A" are found.
- A* All points containing "A" are found, for example, A1, A2, 1A.

Steps: (For example "*")

Steps	Key	Display
① Choosing 'Survey' in application menu, then choose function 'Set STA'. Entering "*", pressing ENT to finish input, then pressing F1 to search.	[F1]	[Set STA] Input STA PT! Station: * Find List Coord.
② In searching result		[Find Pt.] 1/5 A1 Station
window, using arrow key 1	\uparrow	A2 Station A3 Meas. PT
to move cursor to select	[F4] [ENT]	B4 Meas. PT CO Fix Pt.
point number. Press key F4 or		View Coord. Job OK
ENT to conirm selecting.		

3. Q-Survey

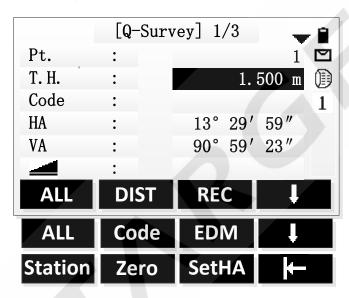
1. Notes in the distance measurement

After the placement of instrument and turned on the power, total station is ready, can start measuring.

In measurement display, user can call the function of set key, the function keys and hot key.

The show is an example. Localized version may be slightly different.

The example of Q-Survey show:



F1-F4 Start the corresponding functions

Notes:

Measurements to strongly reflecting targets such as to traffic lights in Reflector EDM mode without prism should be avoided. The measured distances may be wrong or inaccurate.

When a distance measurement is triggered, the EDM measures to the object which is in the beam path at that moment.

If e.g. people, cars, animals, swaying branches, etc. cross the laser beam while a measurement is being taken, a fraction of the laser beam is reflected and may lead to incorrect distance values.

Avoid interrupting the measuring beam while taking reflectorless measurements or measurements using reflective foils.

- No Prism Ranging
- Ensure that laster beam is not feflected by any object with high reflectivity and close to the light path.

- When start the distance measurement, EDM will measure distance for the object in the light path. If there are temporary obstacles in the light path (such as by car, or the heavy rain, snow, or filled with fog), the distance measured by EDM is the distance to the nearest obstacle.
- When a long distance measurement, laser beam deviation of collimation line will affect the accuracy of measurement. This is because the divergence of the laser beam reflection point may not be with the crosshair sighting points coincide. It is recommended that the user accurately adjust to ensure that is consistent with laser beam collimation. (Please refer to "20.10 NO Prism Ranging" in the Chapter 9)
- Don't use two instruments to measure the same target at the same time .
- ➤ Red light cooperates with reflective pieces to measure distance

 Laster can also be used to measure distance for eflective pieces. To guarantee the accuracy of measurement, the laser beam is perpendicular to the reflector plate, and through accurate adjustment. (Please refer to "3.10 NO Prism Ranging" in the Chapter 9)

Ensure proper additive constant of different reflection prism.

2. EDM Setting

2.1 Set the mode of EDM

Select the mode of distance measurement, there are 6 modes : Single, Repeat, Tracking, 3 Times, 4 Times, 5 Times.

Steps	Key	Display
① Press[F4](↓) and show the second soft key in the Q-Surveying. Press [F3] to enter the interface of EDM Setting.	[F4] [F3]	[Q-Survey] 1/3 Pt. : 1
② When the cursor is in EDM mode option,Press the direction key of ←→ to select the mode of measurement.Each time you press ←or→, the mode of measurement is switched.	←	[EDM Setting] EDM Mode: Single () Reflector: Non-Prism () P.C. : 0 mm
③ After finishing setting, press [F3](OK) to return the function of Q-Surveying.If you want to cancel the settings, press [ESC] to ignore the changes.	[F3]	Setting Saved!

Set the reflector type

Our series total station can be set up for the red laser (RL) range and invisible infrared light (IR) range and the total station has three reflectors to be selected, which are prism, non-prism (NP) and reflect board (Sheet). You can set by job, but the prism used should be matched with prism constants.

> About the parameters of various reflectors in distance measurement, please

refer to "Technical Parameters".

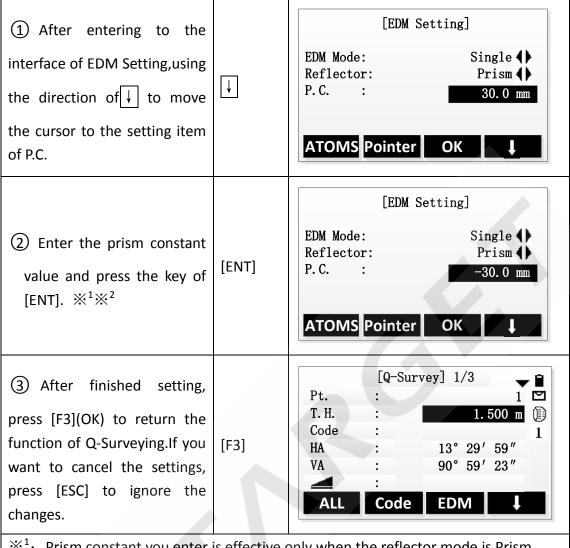
Steps	Key	Display
① After entering to the interface of EDM Setting, using the direction of ↓ to move the cursor to the setting item of Reflector.	→	[EDM Setting] EDM Mode: Single Reflector: Prism Decree P
② Press ←→ to select the types of reflector. Each time you press ←or→, the type of reflector is switched.	←	[EDM Setting] EDM Mode: Single Non-Prism Non-Prism ATOMS Pointer OK
(3) After finished setting, press [F3] (OK) to return the function of Q-Surveying.If you want to cancel the settings,press [ESC]to ignore the changes.	[F3]	[Q-Survey] 1/3 Pt. : 1 500 m T. H. : 1.500 m Code : 1 HA : 13° 29′ 59″ VA : 90° 59′ 23″ ALL Code EDM

Set up the Reflecting Prism Constant.

As a prism is selected as a reflector, a prism constant should be set before any measurement. If the constant is entered and set, it is saved and will not be erased after switching off the instrument.

Example: Prism Constant is -30mm

Operating Steps	Key	Display
-----------------	-----	---------



- ※¹: Prism constant you enter is effective only when the reflector mode is Prism.
- %2: The range of Prism constant value: -99mm \sim +99mm.

2.2 Atomosphere setting

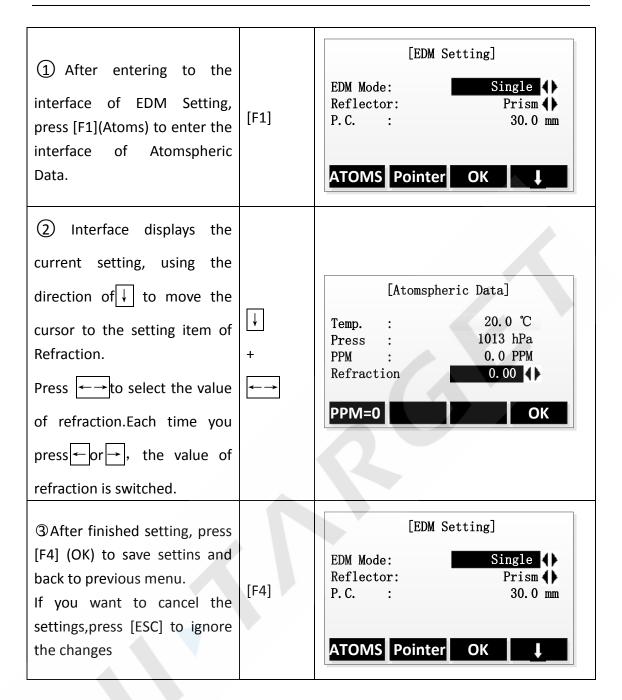
Refraction:

When measuring horizontal distance and elevation, our instrument corrects the atmospheric refraction and the earth curvature automatically.

The instrument supports of atmospheric refraction coefficient have three option, they are 0.00, 0.14, and 0.20.

Note: The refraction of instrument has been set for K=0.00 when left factory .It also can be set to other values

Operating	Key	Display
-----------	-----	---------



Atmospheric Correction:

When measuring distance, the measured value will be influenced by the atmosphere. In order to reduce the influence, a atmospheric correction parameter is needed. Correction value associated with the pressure and temperature in air.Calculated as follows:

$$PPM = 277.8 - \frac{0.2900 \times atmospheric pressure(hPa)}{1 + 0.00366 \times temperature \text{ (°C)}}$$

If the air pressure unit is mmHg, Make a conversion according to the formula: 1hPa=0.75mm Hg

> Standard meteorological conditions (atmospheric correction value =0):

press: 1013hPa temperature: 20° C

➤ If the atmospheric correction is not required, please set PPM to zero.

Operating Steps	Key	Display		
① After entering to the interface of EDM Setting. Press [F1](Atoms) to enter the interface of Atomspheric Data.	[F1]	[EDM Setting] EDM Mode: Single Reflector: Prism Prism And Single Prism And Single Reflector: Prism And Single Prism And Single Reflector: Pri		
② Interface displays the current settings.	↓	[Atomspheric Data] Temp. : 20 °C Press : 1013 hPa PPM : 5.6 PPM Refraction 0.00 ••• PPM=0 OK		
③ Input the value of temperature. example: Enter 26 °C and press the key of [ENT]. The cursor moves to the setting item of Press.	[ENT]	[Atomspheric Data] Temp. : 26 °C Press : 1013 hPa PPM : 5.6 PPM Refraction 0.00		
4 Enter the value of atmospheric pressure. example: Enter 1020 hPa and press the key of [ENT].Program calculates the value of PPM and the cursor moves to the setting item of PPM. **\frac{3}{2} \times \frac{3}{4} \times \frac{4}{3} \times \frac{4}{3}	[ENT]	[Atomspheric Data] Temp. : 26 °C Press : 1020 hPa PPM : 3.7 PPM Refraction 0.00		

After finishing setting, press [F4](OK) to save settins and back to previous menu. Then press the key of [F3](OK) to save the setting of EDM and back to the function of measurement.

%1: The range of enter: Temp. (-30°C \sim 60°C), Press. (500hPa \sim 1400hPa).

[F4]

[F3]

- **%2:** The instrument calculates the value of PPM according to the values of temperature and pressure you enter.
- ※3: Press [F1] (PPM=0) can set the value of PPM to 0.
- *4: If instrument supports temperature pressure sensor, you can press [F2] to receive the values of air pressure, temperature and calculate the correction value automatically.

2.3 Grid factor setting

When calculating the coordinates, the horizontal distance measured must multiply by the scale factor.

Computation formula

1. Altitude factor = R / (R + ELEV)

R: The average radius of earth

ELEV: mean sea level altitude

2. Scale factor

Scale factor: Scale factor of the station

3. Grid factor

Grid factor=altitude factor × scale factor

Distance calculation

1. Grid distance

HDg=HD×grid factor

HDg: Grid distance

HD: Ground distance

2. Ground distance

HD=HDg/(Grid factor)

Note:

- 1. The enter range of the scale factor: 0.99~1.01, the default value is 1.0.
- 2. The enter range of the average height above sea level: -9999.9999~9999.9999. The

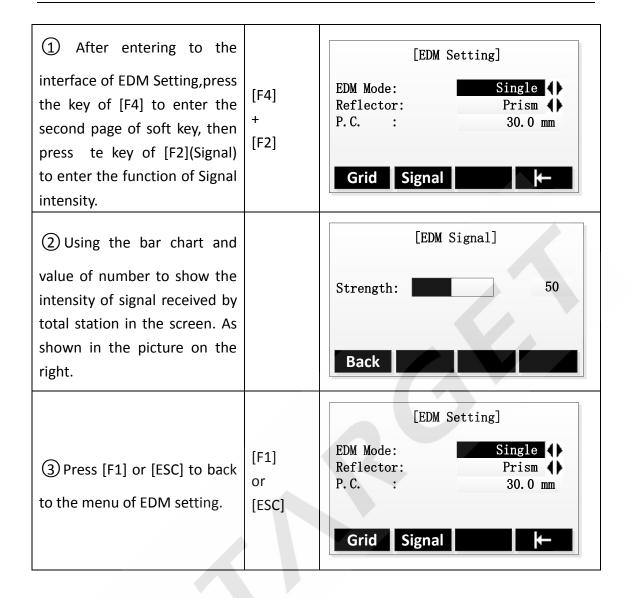
average altitude retained after the decimal point one, the default value is 0.

Operating Steps	Key	Display		
① After entering to the interface of EDM Setting,press the key of [F4] to enter the second page of soft key, then press te key of [F1](Grid) to set the Grid Scale.	[F4] [F1]	[EDM Setting] EDM Mode: Single () Reflector: Prism () P.C. : 30.0 mm		
2 Interface displays the current setting.Enter the values of Scale and Altitude then press the key of [ENT].Program calculates the Grid Scale and displays it in the interface.If you want to set all enter area to 0,you can set the key of [F1] (Reset).	[ENT]	[Grid Scale] Scale :		
3 After finished setting, press [F4](OK) to save settins and back to previous menu. Then press the key of [F3](OK) to save the setting of EDM and back to the function of measurement.	[F4]	[EDM Setting] EDM Mode: Reflector: P.C.: Single () Prism () 30.0 mm		

2.4 EDM signal

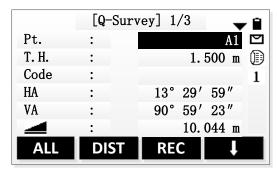
The function of signal is to display the intensity of signal received by total station. If the target is hard to be found or can't see, using the function can achieve the best sighting accuracy.

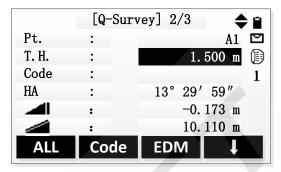
|--|

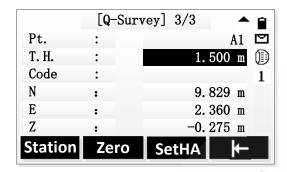


3. Start measurement

Q-Survey has 3 pages menu, including all measuring functions commonly used, such as angle measurement, distance measurement and coordinate measurement. As shown below:





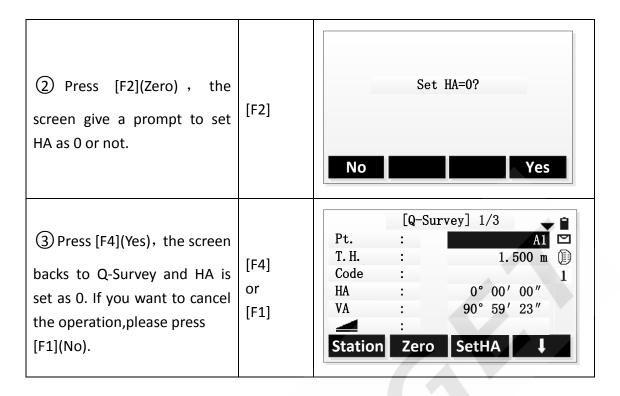


3.1 Set HA

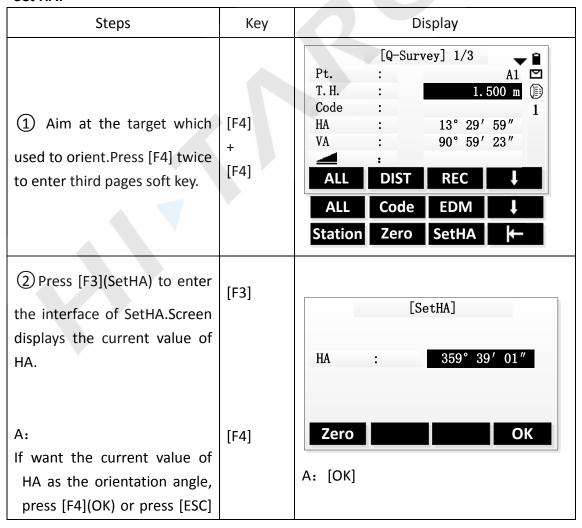
You can set the horizontal angle as 0 or set it as wanted angle.

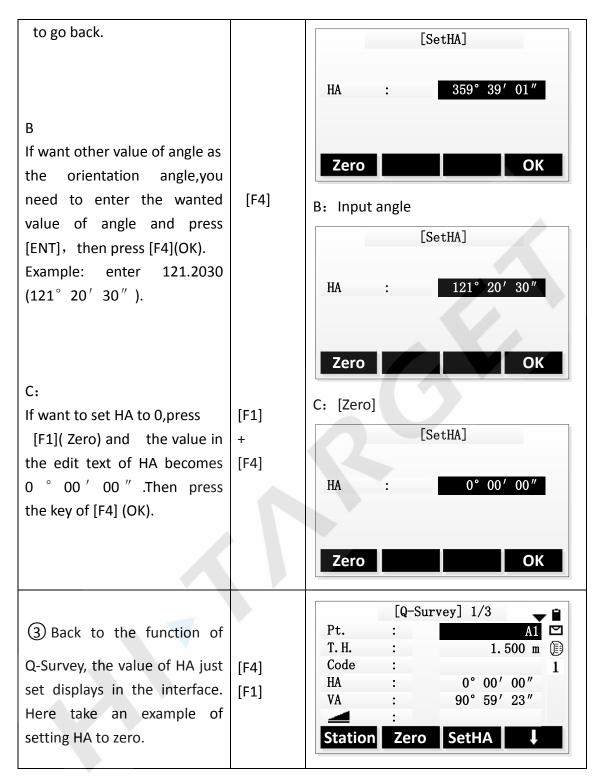
Set horizontal angle to 0.

Operating Steps	Key		Di	splay	
① Aim at the target which used to orient.Press [F4] twice to enter third pages soft key.	[F4] + [F4]	Pt. T. H. Code HA VA ALL Station	: : : : : : DIST	1. 13° 29′ 90° 59′ REC EDM SetHA	



Set HA.



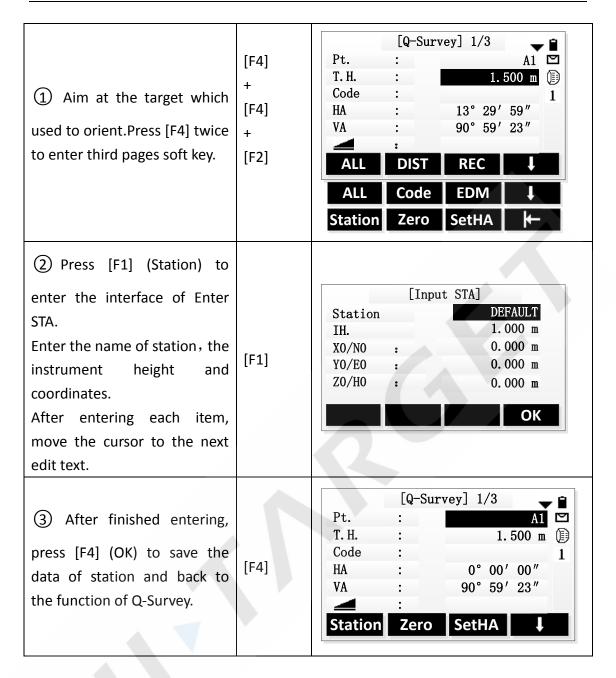


3.2 Set Station and instrument height

After set the coordinate of station (the site of instrument) relatives to the origin, the instrument can calculate the coordinate of the location to your position (the site of prism).

You can set station and the instrument height conveniently in the Q-Survey.

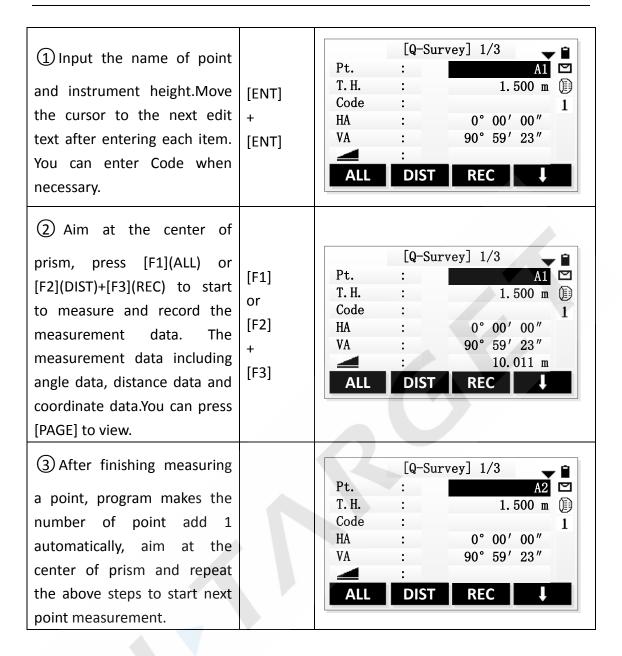
Steps	Key	Display
-------	-----	---------



3.3 Measurement

After all settings have been finished, you can start to measure. There are 3 pages to display the result of measurement, including all measurement data and you can press [PAGE] to view.

Steps Key Display



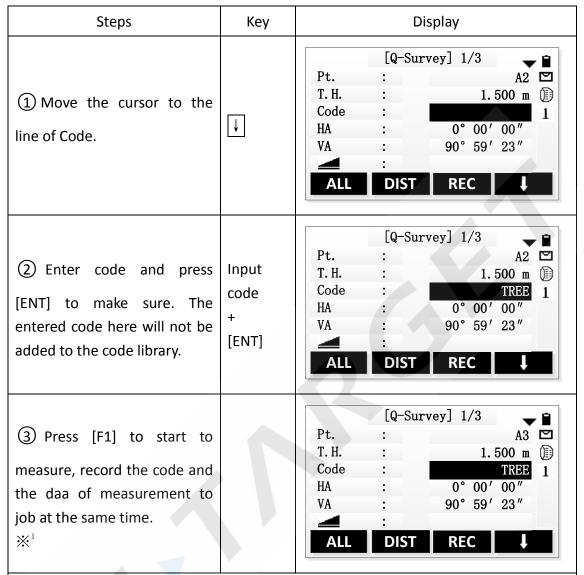
3.4 Code

The code contains the information about the recording points, in the process of post-processing, with the help of encoding function , you can process conveniently according to the specific group. The function of "File Manager" also contains the information of code.

Simple Oeration of Code

- 1. Move the cursor to the line of Code.
- 2. Enter the name of Code.
- 3. Press the key of [ALL] to start the distance measurement and record the data of code and measurement at the same time. If the name of code already exists in

the code library, it will extract the information of code in the code library to record at the same time.



 $\ensuremath{\mathbb{X}}^{\mbox{\tiny 1}}$:The order to save code and measurement data is set in the "Setting" function.

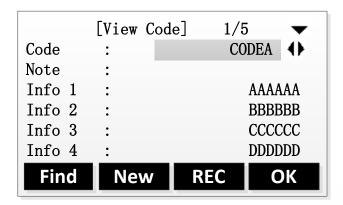
The set items of code record are Before REC and After REC.

Before REC: Record code data before recording the actual measurement data.

After REC: Record code data following after the actual measurement data.

Soft key of Code

After starting the function of soft key (Code), Screen displays the following:



GSI-the introduction of code properties:

Code: The name of code

Note: The additional note

Info1: The editable information of other contents

Info8: Other information

The introduction of soft key:

[Find]: Use the name of code or wildcard to find the needed code.

[New]: New a piece of editable information of code and use it.

[REC]: Record the current code data to the job and the code data not with any measurement point binding at this time.

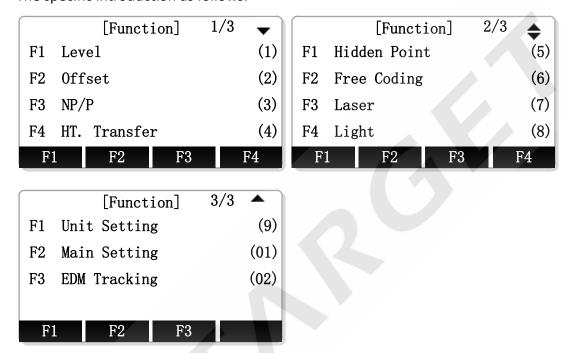
[OK]: Select the current code and use it.

Using the soft key of [Code] can select the code in the code library directly, it will back to the interface of Q-survey after selecting, the code in the edit text of Code is the selected code.

4. Funtions

Bring the total station's common functions and settings together, they can be used in the process of measurement conveniently. In the function of Q-Survey which in the Main menu or other interface of measuremen in the program, you can press [FNC] to enter the menu of Function

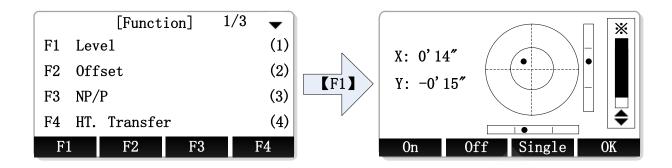
The menu of Function has 4 pages, you can press 【PAGE】 to view. The specific introduction as follows:



You can open Function menu to select the function you want to use, you can also define the function which on the Function menu to the key of [USER1] or [USER2], then press the key of [USER1] or [USER2] to use these functions.

1. Level

When the compensator is on, Compensator can compensate to the tilt caused by the instrument is not level. Manually level the instrument with the tribrach screws to make the compensation value of compensator tend to 0, by doing these can make the instrument tend to level. When the instrument is level, the laser plummet is in the direction vertical, the place of laser points is the place of instrument station.



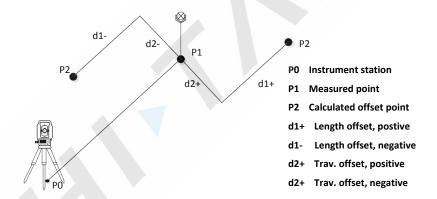
- Press [On] to open the compensator and press [Off] to close the compensator.
- ◆ Press [X Only] to open the compensator of X direction.
- ◆ Press [▲][▼] to adjust the laser plummet brightness.
- Press [OK] to closs the laser plummet and exit.

2. Offset

The Offset is used to measure the points which are not intervisible or intervisible but can not set up prism in the Station.

Offset contains Dist.Offset and two subprograms, the two subprograms are Cylinder Offset and Angle Offset.

2.1 Distance Offset



Using the external tools to measure the Offset values of the target point p2 and measurement point p1 along the line of station point and measurement point, the Offset values are Trav.OFS, LengthOFS and HeighOFS. Combining the information of measuring point (p1) can calculate the distance of station point (p0) to target point (p2), can also calculate the angel and coordinate.

When the measurement point is set on the left of target point or the right of target point, you should make the angle that between line of measurement point and target point and the line of measurement and station point about equals 90° . When the offset point is set on the front of target point or on the back of target point, you

should make it on the line of station point and target point.

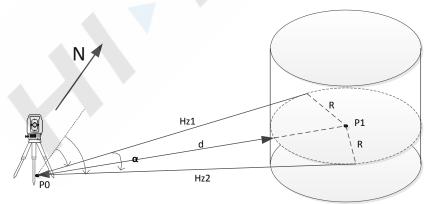
Steps	Key	Display
① In the program of Q-Survey, press [FNC] to open the menu of Function, next pressing [F2] to enter the program of Offset.	[F2]	[Function] 1/3 ↓ F1 Level (1) F2 Offset (2) F3 NP/P (3) F4 HT. Transfer (4) F1 F2 F3 F4
② Input the values of Trav.OFS, LengthOFS and HeightOFS, then select the mode of offset and press [F4] to save.※ ¹	[F4]	[Dist. Offset] Input offset data! Trav.OFS: LengthOFS: HeightOFS: Mode: Reset Cylinder Angle OK

 X^1 :

Rec/Reset: Make sure the inputed values of Offset and reset all the values of Offset to 0 after once measurement.

Permanent: The values of Offset are always working in the calculation of measurement point.

2.2 Cylinder Offset



- PO Instrument station
- P1 Center point of cylindrical object
- Hz1 Horizontal angle to a point on the left side of the object
- Hz2 Horizontal angle to a point on the right side of the object
- d Distance to the object in the middle between Hz1 and Hz2
- R Radius of cylinder
- α Azimuth from Hz1 to Hz2

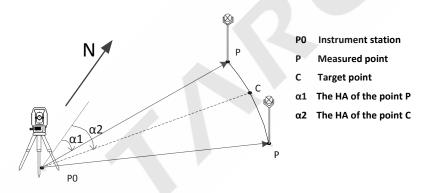
As for the not intervisible cylinders, you can measure the angles of station point with cylinder in Hz Left and Hz Right and the shortest distance of station point to cylinder firstly. Then calculate the coordinate of cylinder center and radius of cylinder

through the geometric relationships. The shortest distance between station point and cylinder is in the bisector of angle of station point with cylinder in Hz Left and Hz Right. Turning the instrument to make the collimation axis in the bisector of angle that station point with cylinder in Hz Left and Hz Right, thus can measure the distance between cylinder and station .

Steps	Key	Display
① In the program of Q-Survey, press [FNC] to enter the menu of Function, then pressing [F2] to enter the program of Offset.	[F2]	[Function] 1/3 ↓ F1 Level (1) F2 Offset (2) F3 NP/P (3) F4 HT. Transfer (4) F1 F2 F3 F4
② Press [F2] to enter the subprogram of Cylinder Offset.	[F2]	[Dist. Offset] Input offset data! Trav. OFS: LengthOFS: HeightOFS: Mode: Reset Cylinder Angle OK
③ Aim at the left edge of cylinder, press [F1] to make sure the angel of Hz Left, turn the instrument to aim at the right edge of cylinder and press [F2] to make sure the angle of Hz Right.	[F1]+[F2]	[Cylinder Offset] Hz Left : 125° 36' 25″ ☑ Hz Right : 88° 45' 46″ ☑ ∴ 0.000 m 1 △Hz : 1° 45' 46″ Prism OFS: 0.000 m Hz Left Hz Right ALL DIST REC EDM ←
$\textcircled{4}$ Turn the instrument to make \triangle Hz = 0, if use the prism, please input the thickness of prism in the edit text of PrismOFS, if don't use the prism, the default value is 0 in the edit of PrismOFS,	[F3] or [F4] + [F1]+[F2]	[Cylinder Offset] Hz Left : 125° 36'25″ ☑ Hz Right : 88° 45'46″ ⑤ ∴ 12.124 m 1 △Hz : 0° 0'0″ Prism OFS: 0.000 m Hz Left Hz Right ALL

then press [F3] to measure the shortest distance of the instrument to cylinder and enter the interface of Cylinder Offset-Result.	DIST REC EDM ←
⑤ Display the result of cylinder offset.	[Cylinder Offset-Result] Pt. :

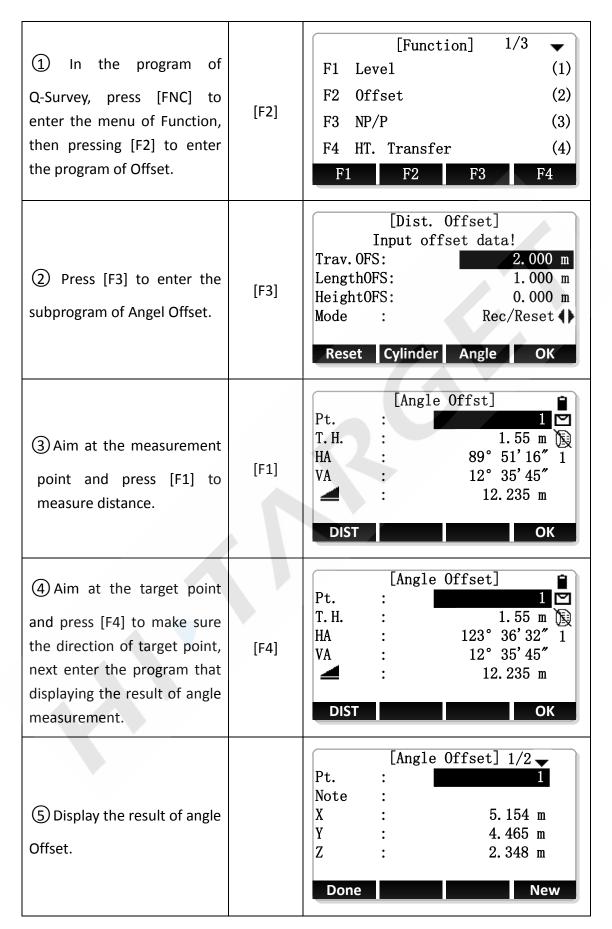
2.3 Angel Offset

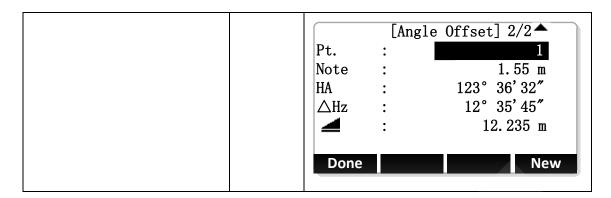


Angle Offset is used to measure the points which are intervisible but hava no reflector and can't set up the prism. The basic principle is making the target point and measurement point in the concentric circles whose center is station point, then measuren the position information of station point and measurement point and the angle offset of station to target point, thus can calculate the coordinate of target point.

Set the measurement point P in the place where is as far as possible to close the left or right of target point C, and make the distance between measurement point P and station point A and the distance between station point A and target point C are approximately equal.

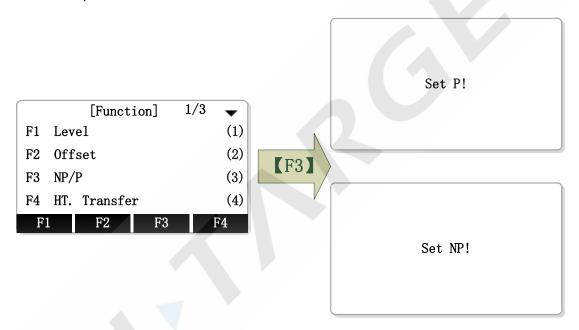
Steps Key	Display
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3. NP/P Toggle

Switch the mode of reflector quickly. (P is the mode of Prism and NP is the mode of Non-Prism)

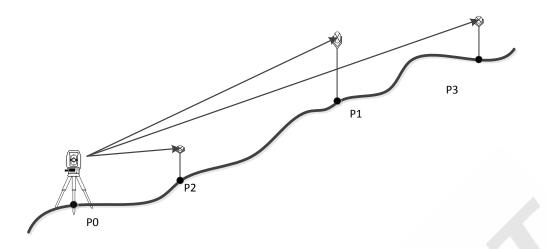


Open the first page of Function Menu and press [F3] to switch the mode of reflector.

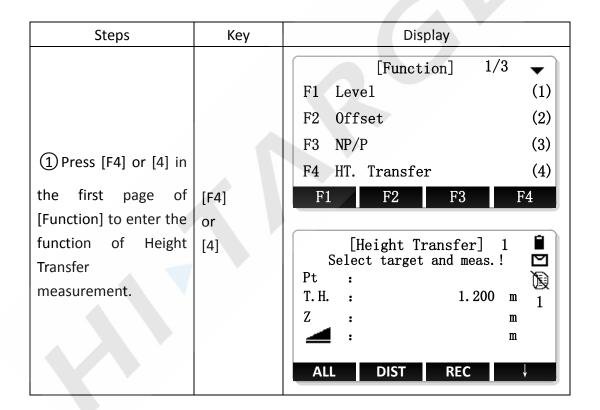
4. Height Transfer

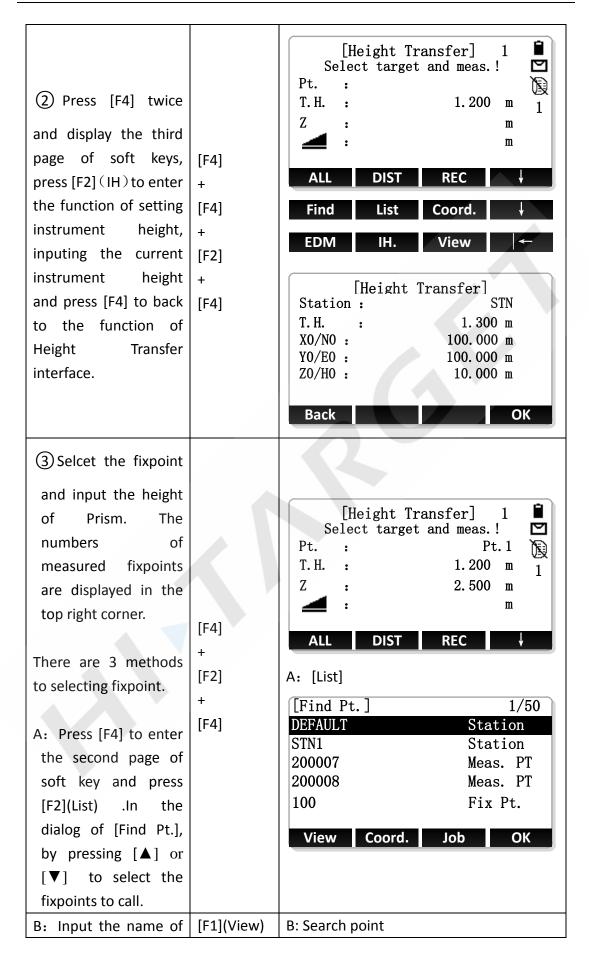
The functions of HT. Transfer as follows: Using the measurement data of target point, the fixpoints, fix measurement points and so on to calculate the height of current station point and set the height of station again. You can receive the coordinate of target point by calling the points in the file or through the keyboard to input, you can observe 5 fixpoints' height at most and to calculate.

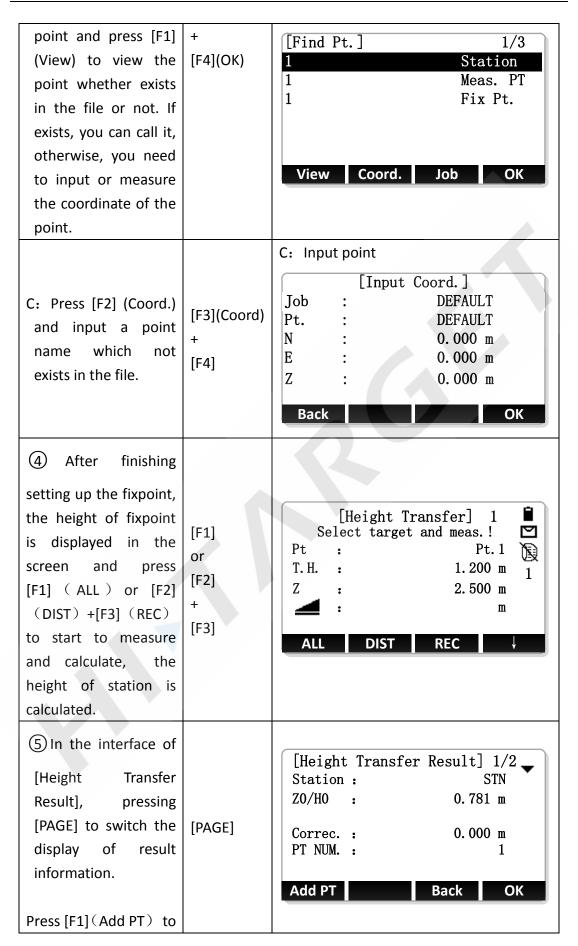
Th principle of Height Transfer:

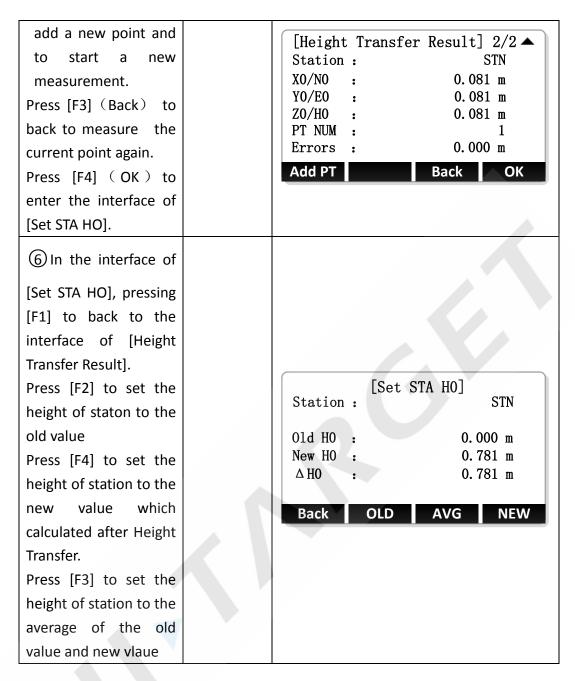


P0 Station point P1~P3 Target fixpoints height



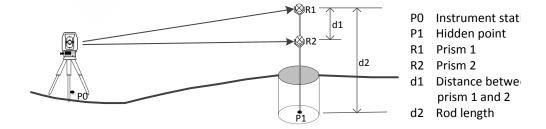






5. Hidden Point

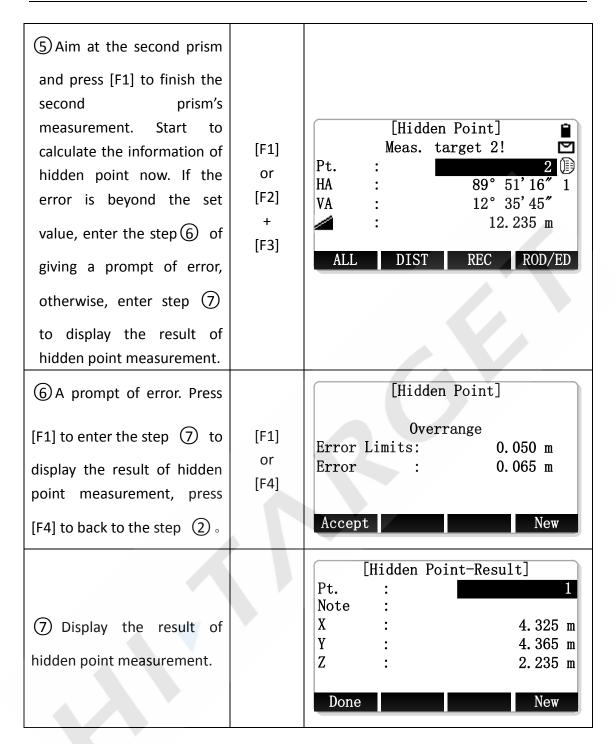
The function of Hidden Point is using a specia hidden point measuring rod to measure the points which are not intervisible.



The length of measuring rod is known, by measuring the position information of

prism 1 and prism 2 in the measuring rod and using mathematical methods to calculate the coordinate of hidden point on the other side of the measuring rod.

Steps	Key	Display
① In the program of Q-Survey, press [FNC] to enter the menu of Function, then pressing [PAGE] to open the second page of Function and then pressing [F1] to enter the function of hidden point measurement.	[F1]	[Function] 2/3 ← F1 Hidden Point (5) F2 Free Coding (6) F3 Laser (7) F4 Light (8) F1 F2 F3 F4
② In the interface of measuring the first prism point, pressing [F4] to enter the interface of Rod Length.	[F4]	[Hidden Point] Meas. target 1! Pt. :
③ Inputting the correct value of Rod length and pressing [F4] to back to measure the first prism point.	[F4]	[Rod Length] Rod length : 3.000 m R1-R2 : 1.000 m Error Limits: 0.001 m
4 The instrument aims at the prism on the top and pressing [F1] to finish measuring the first prism and enter the interface of measuring the second prism.	[F1] or [F2] + [F3]	[Hidden Point] Meas. target 1! Pt. :

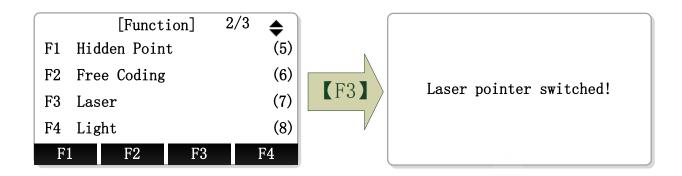


6. Free Coding

Please refer to "3. Q-Survey" → "3. Start Measurement" → "3.4 Code"

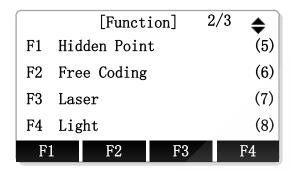
7. Laser Pointer

Open or close the laser fastly.



8. Light

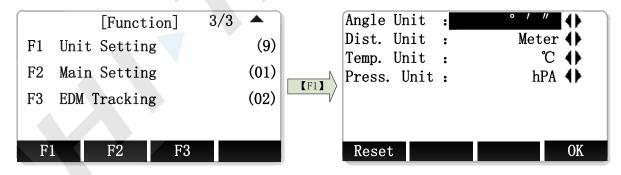
Turn on or off the light of instrument screen fastly.



Open the second page of Function Menu and press [F4] to turn on or off the Light.

9. Unit Setting

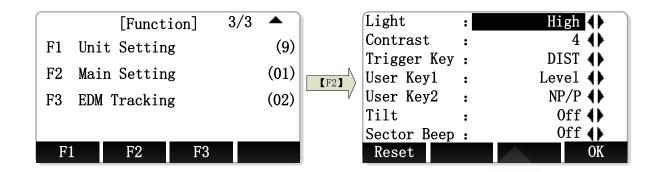
Set the common Unit fastly.



Open the third page of Function Menu and press [F1] to enter the interface of unit setting. After finishing setting the units in the interface of Unit Setting, press [F4] (OK) to save the settings, press [F1] (Reset) to restore all units to factory default.

10. Main Setting

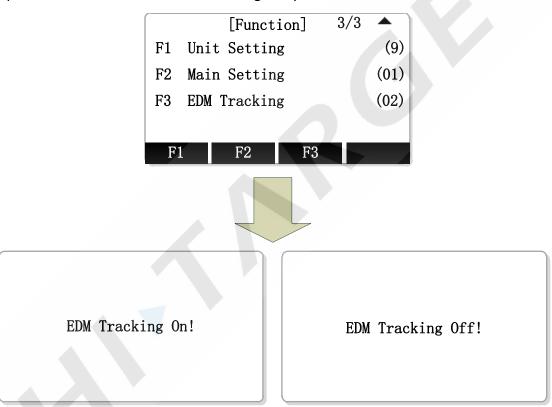
Open the settings about instrument's hardware, the specific items as follows:



As for the setting of specific items ,please refer to "General Setting".

11. EDM Tracking

Open or close the mode of EDM Tracking fastly.

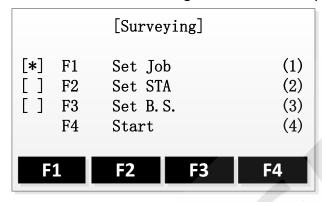


Open the thied page of Function Menu, press [F3] to open or close the mode of EDM tracking.

5. Applications

Prepare setting before measuring:

Before starting the application, there are some preparations needed to set up. The Pre-Settings screen will be shown after the user selects an application. User can select and set the content of the Pre-Settings menu successively.



- [*]: Setting has been done.
- []: Setting has not been done.

The details of every setting are as follows.

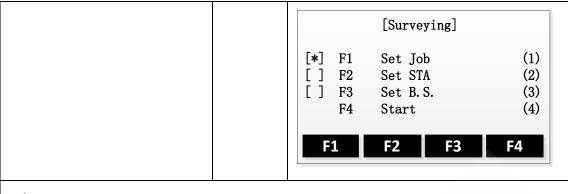
1. Setting the Job

The measured data and fix data are saved in the jobs which are shown as child directories. The job contains different types of data, such as fix points, measured points, station points, codes, etc. The datas in the job can be read, edited and deleted.

1.1 Create a new Job

[Surveying] [*] F1 Set Job (1) [*] F2 Set STA (2)	Step	Key	Display	
Pre-Settings screen. Then enter the Set Job function. [F1] [] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4	① Press [F1] in the Pre-Settings screen. Then	[F1]	[Surveying] [*] F1 Set Job (1) [] F2 Set STA (2) [] F3 Set B.S. (3) F4 Start (4))

② Press [F2](New) and then enter the Create a New Job screen. Press [F4](OK), the displayed job will be set as current job and then back to Pre-Settings screen.	[F1]	[Set Job] Job : DEFAULT Operator: Date : 20150515 Time : 14:10:20 List New OK
③ If the instrument is fitted with SDCard, there will firstly show the disk selection screen. In this screen, user can select the disk through Up or Down key. Then press [F4](OK) to confirm. A: Local Disk B: SD Card		[Select Disk] A:Local Disk B:SD Card Prop. OK
4 Continue to show New Job screen. Input the new job's name, operator, etc. Press [ENT] to finish one input item and the cursor moves to the next input item automatically at the same time. **	Input job's data + [ENT]	[New Job] Job : JOB1 Operator: Note1 : Note2 : date : 20150515 Time : 14:10:20 Back OK
⑤ Press [F4](OK) to complete setting a new job after finishing all the inputs. This job will be set as the current job. Then back to the Pre-Settings screen. The completed setting item is marked with [*].	[F4]	Job Setted!

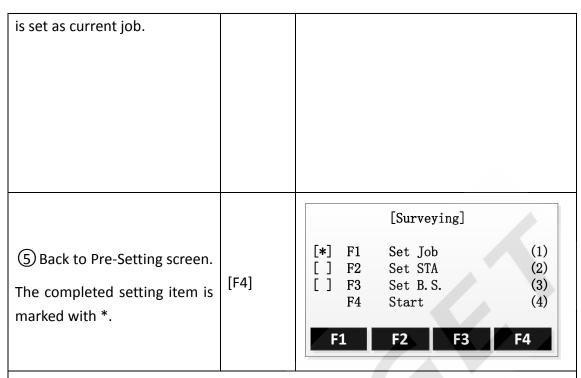


X: The instrument system will create and add date and time automatically.

1.2 Select an Existing Job from Memory

If there is any job existing in the memory, user can select this job and set it as the current job.

Step	Key	Display
① Press [F1] in the Pre-Settings screen. Then enter the Set Job function.	[F1]	[Surveying] [*] F1 Set Job (1) [] F2 Set STA (2) [] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4
② Press [F1](List) to enter Job list screen.	[F1]	[Set Job] Job : DEFAULT Operator: Date : 20150515 Time : 14:10:20 List New OK
3 All the existing jobs, including that stored on SDCard, will be shown as a list. The current job is marked with a *. Select the target job through Up and Down key and then press [F4](OK) to confirm the selection. The selected job		[Job list] JOB1 JOB2 JOB3 JOB4 [SD] Delete New View OK

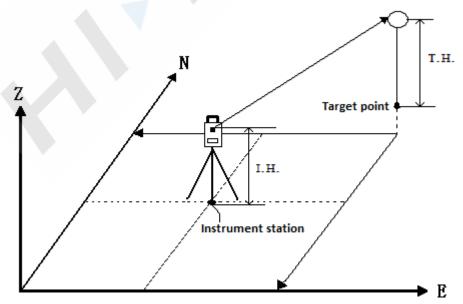


Note: Don't pull out the SDCard when it is in operating state., otherwise it will cause the SDCard's data loss or damage.

- All measured datas are stored in the current job.
- ➤ If start the application without setting the job, press ALL key or press REC key in the Q-Surveying screen, the instrument system will create a job which named DEFAULT automatically.

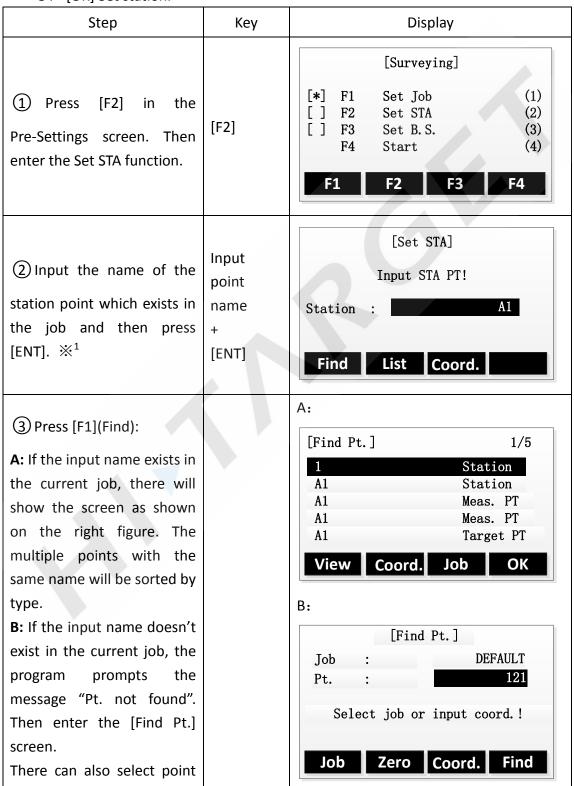
2. Setting the Station

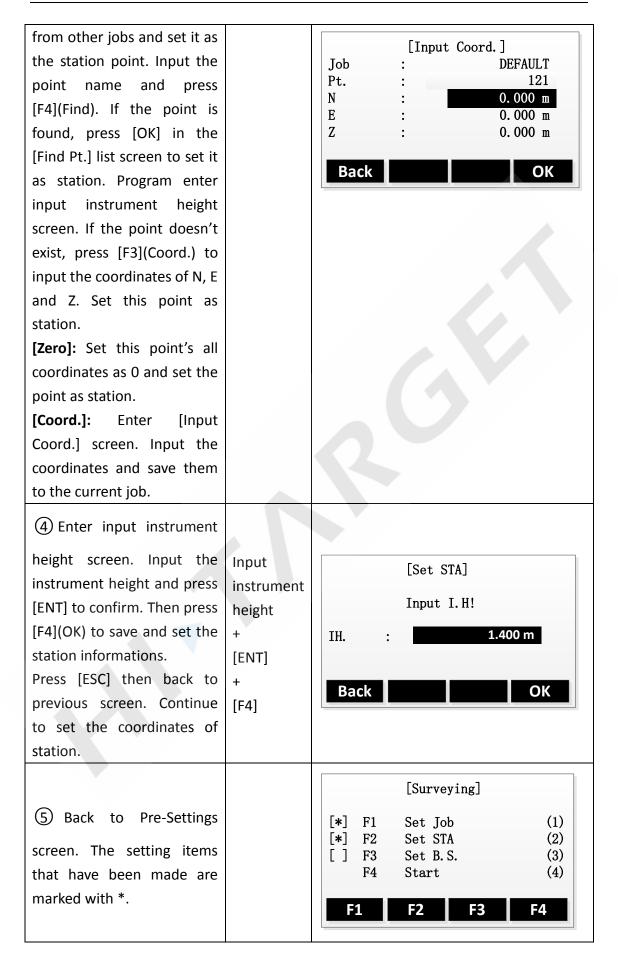
Every target coordinate's calculation is related to the position of the station. The station coordinate can be input manually or selected from the instrument memory.



2.1 Select the coordinate from memory [Find]

- 1. Select the coordinate from memory.
- 2. Input instrument height.
- 3、[OK] Set station.



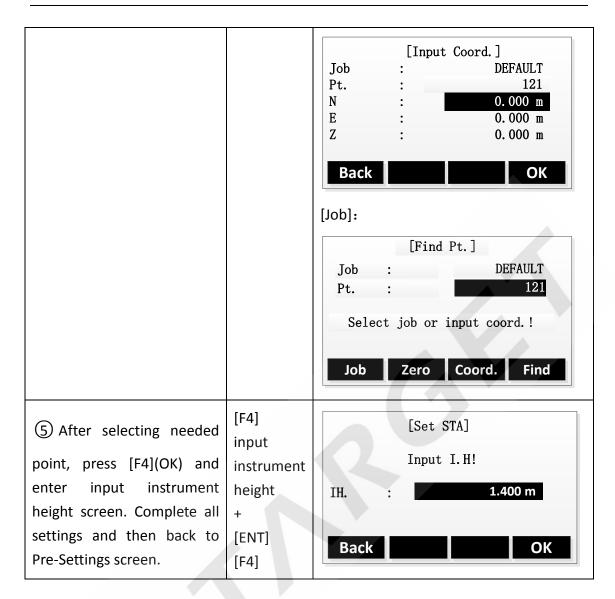


※¹: The details of [Find Pt.] can be found in the chapter "Find Point". You can also input the wildcard "*" to search all the points.

2.2 Select the Fix Point in the Memory [List]

User can select the fix point in the memory's jobs to set station without inputting the point name.

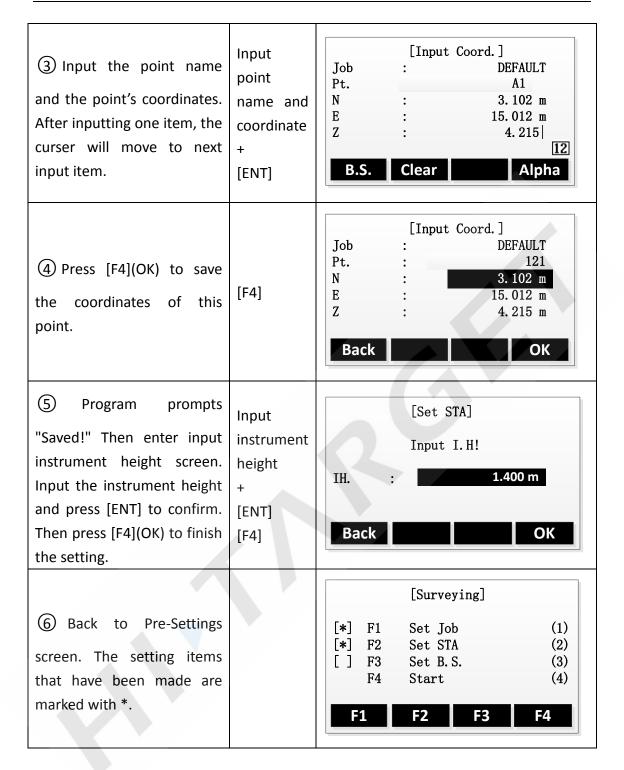
Step	Key	Display
② Press [F2](List) in the [Set STA] screen.	[F2]	[Set STA] Input STA PT! Station: A1 Find List Coord.
③ Show the point list all the fix points and measured points of the current job.		[Find Pt.] 1/5 DEFAULT Station STN1 Station 200007 Meas. PT 200008 Meas. PT 100 Target PT View Coord. Job OK
4 Select the needed point through Up and Down key. [View]: Show the informations of this point. [Coord.]: Input the coordinate datas manually. [Job]: Select datas from another job.	↑ ↓	[View]: [View Coord.] Job: DEFAULT Pt.: 121 X: 0.000 m Y: 0.000 m Z: 0.000 m Date: 20150515 [Coord.]:



2.3 Input the coordinates manually.

- 1. Press [Coord.], enter input coordinate screen.
- 2. Input the point name and coordinates.
- 3. [OK] Save the station coordinates. And then input the instrument height.

Step	Key	Display
		[Set STA]
② Press [F3](Coord.) in the [Set STA] screen.	[F3]	Input STA PT! Station: A1 Find List Coord.



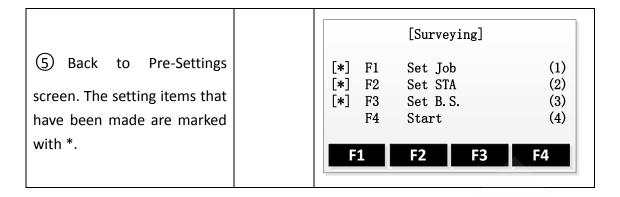
3. Setting the Orientation

The orientation can be input manually or determined from points that are either measured or selected from the memory.

3.1 Manual input orientation

- 1. Press [F1] and enter manual input screen.
- 2. Input the azimuth, prism height and point name.
- 3. Press [F1](ALL) to start measuring and set the orientation.
- 4. Press [REC] to record the angle and orientation.

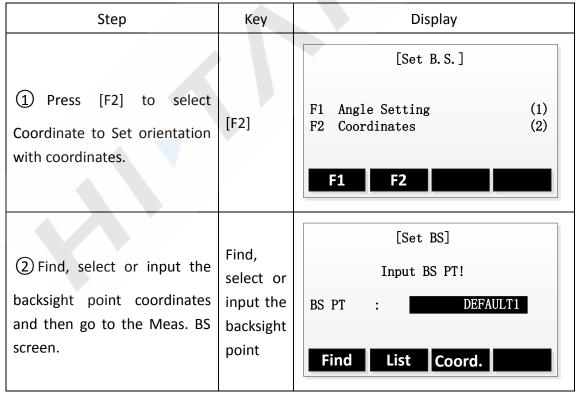
Step	Key	Display
① Press [F3] in the Pre-Settings screen. Then enter the Set STA function.	[F3]	[Surveying] [*] F1 Set Job (1) [*] F2 Set STA (2) [] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4
② Press [F1] and select the [Angle Setting] to input orientation manually.	[F1]	[Set B.S.] F1 Angle Setting (1) F2 Coordinates (2)
③ Aim B.S. point and then input the azimuth, prism height and backsight point name. Press [ENT] after finishing every input.	Input horizontal angle + [ENT]	[Angle Setting] Azimuth: 50 ° 00′ 00″ T.H.: 1.500 m BS PT: DEFAULT1 Aim BS. Then ALL/REC! ALL REC Zero EDM
4 Press [F1](ALL) to start measuring and set the orientation. [REC]: Press this key to finish setting orientation without measurement. [Zero]: Set the azimuth as 0.	[F1]	BS SET!

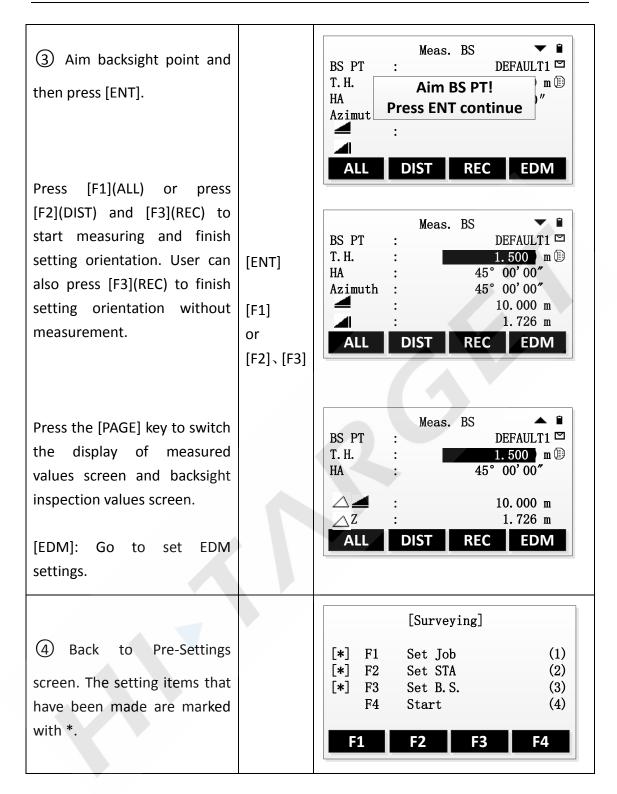


3.2 Set orientation with coordinates

The determination of the direction value can also be carried out using a point with a known coordinate.

- 1. Press [F2] to go to set orientation with coordinates
- 2. Input the name of orientation point and find the point.
- 3. Input the prism height and determine it.
- 4. Use this point to set orientation.
- The orientation point can be select from memory or inputted manually.





4. Starting the Applications

The preset applications covers a wide range of measurement tasks. That makes the daily field measurement easier and faster. The all applications can be selected to use are as follows:

Surveying

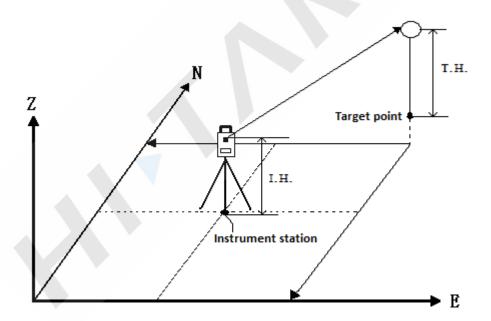
- Stakeout
- Free Station
- Tie Distance
- Area
- Remote Height
- COGO
- Road

Steps:

- 1. Go to the MAIN MENU.
- 2. Move the focus to [Program] or press the Numeric key 2 to select and go to the PROGRAM MENU.
- 3. Press [PAGE] to browse the application menu. Press [F1]-[F4] to select and start an application.

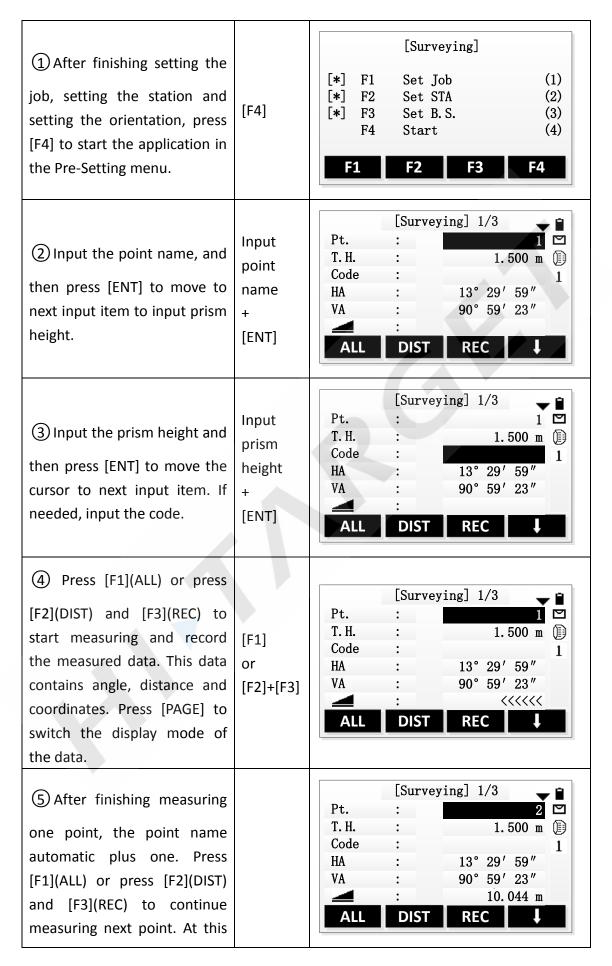
5. Surveying

Compared with the Q-Suveying, Surveying has different guides in setting station and set orientation.



Operation: Must first finish seting the station and orientation.

Step	Key	Display
------	-----	---------



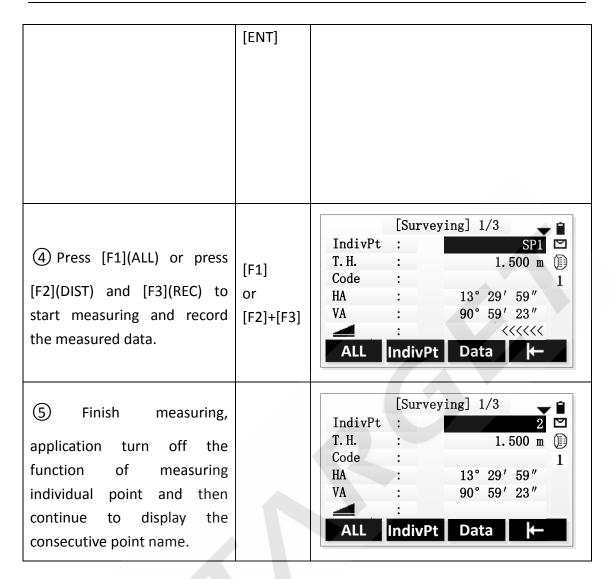
time, the screen remains the		
last measured data which can		
be looked over by pressing		
[PAGE].		

5.1 Individual Point

[IndivPt]:

In the data acquisition, point can be recorded individually. Press this key to switch the screens of Individual Point Measurement and Consecutive Point Measurement.

the screens of individual Point i	vieasureillei	nt and Consecutive Point Measurement.			
Step	Key	Display			
① Press [F4](↓) twice to display the last page of soft keys.	[F4]	[Surveying] 1/3 Pt. : 1			
② Press [F2](IndivPt) to start measuring individual point function.	[F2]	[Surveying] 1/3 IndivPt: 2 T. H.: 1.500 m Code: 1 HA: 13° 29′ 59″ VA: 90° 59′ 23″ ALL IndivPt Data			
③ Input the individual point's name and prism height and press [ENT] to move the cursor to next input item If needed, input the code.	Input point name, prism height and code	[Surveying] 1/3 IndivPt: SP1 T. H. : 1.500 m Code : 1 HA : 13° 29′ 59″ VA : 90° 59′ 23″ ALL IndivPt Data			

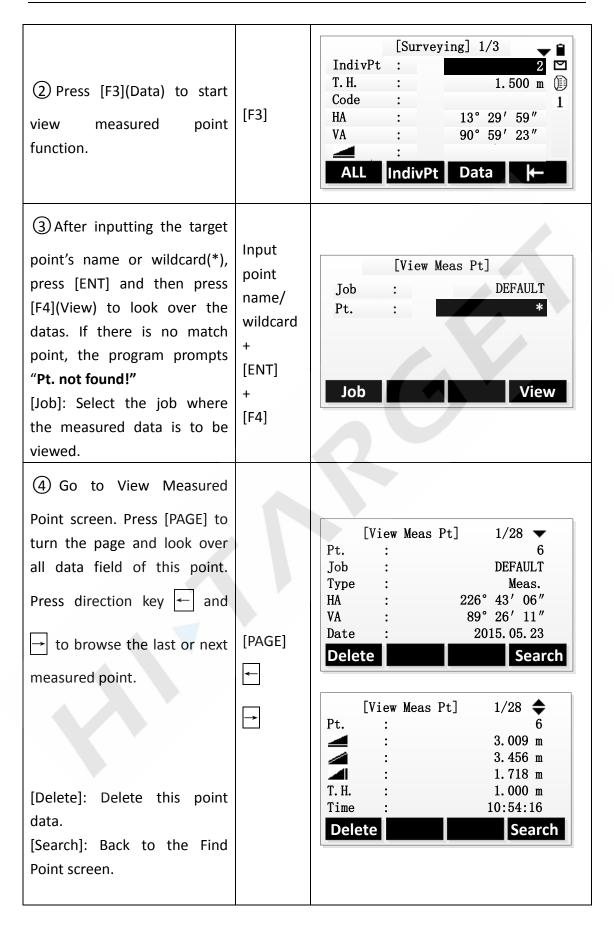


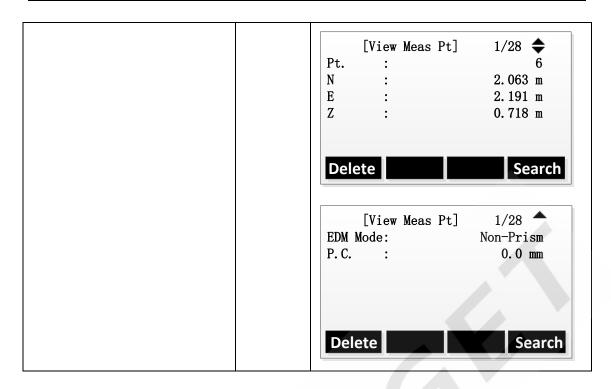
5.2 Data

[Data]:

Look over the measured datas which are saved in current job.

Step	Key	Display			
① Press [F4](↓) twice to display the last page of soft keys.	[F4]	Pt. T. H. Code HA VA ALL ALL	[Survey: : : : : : DIST Code IndivPt	13° 29′ 90° 59′ REC	





6. Stakeout

The Stakeout Application can calculate lofting elements base on lofting point's coordinate or manually input angle or horizontal distance. The application can continuously display differences, between current position and desired stake out position.

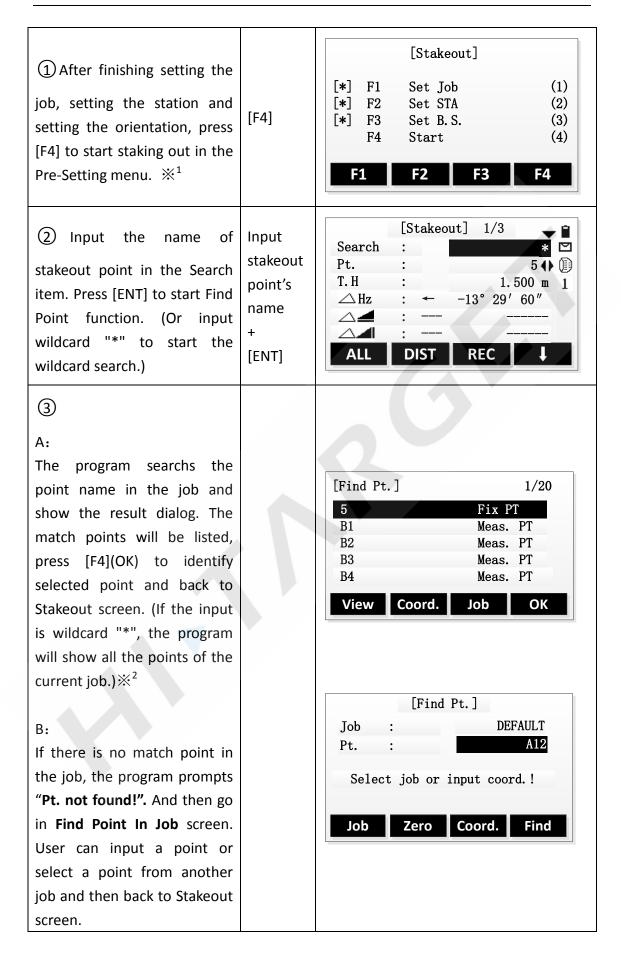
Steps of Stakeout:

- 1. Set the job.
- 2. Set the station
- 3. Set the orientation
- 4. Extracte coordinates from memory. The coordinates may be a measured point or a manually entered fix point.
- 5. Start staking out. There are three ways to choose: Polar Stakeout mode, Orthogonal to Station Stakeout mode, Cartesian Stakeout mode.

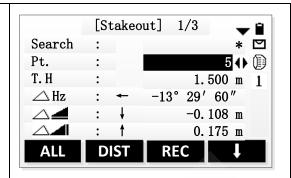
6.1 Set Stakeout Point

Extracte coordinates from job

Step	Key	Display
------	-----	---------



4 After finishing setting stakeout point, start staking out.



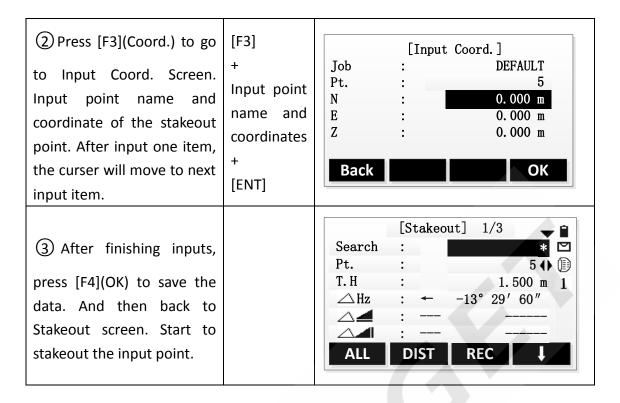
- **1: The settings of job, station and orientation have been elaborated in detail In the previous chapters, here is no longer repeat. Refer to chapters "Setting The Job."
 Setting The Station. Setting The Orientation".
- ※²: Unlike the other place's points list, the stakeout points are ordered by time. In the stakeout points list, the newest point is at the back and the fix point is in the front of measured point. But in the other points list, the newest point is at the back and the measured point is in the front of fix point.

Manual input stakeout point

Press key [Coord.] or [SO-PT] to manual input stakeout point coordinates and then continue staking out.

[Coord.]:
Press [Coord.] and then input a target point's coordinates. Saved this point into job and continue staking out.

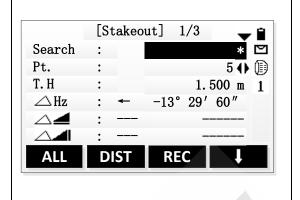
Step	Key	Display
① Press [F4] (↓) to view the second page of soft keys.	[F4]	Search : * ★ Pt. : 5 (1) (2) T. H : 1.500 m 1 △Hz : -13° 29′ 60″ △ :



[SO-PT]:
Press [SO-PT] to input a stakeout point without point name and being saved into job.

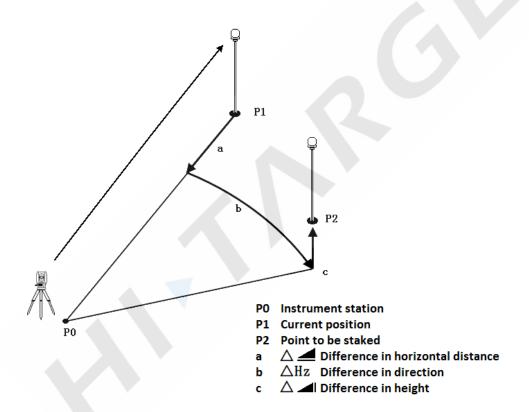
Step	Key	Display
① Press [F4] (↓) to view the third page of soft keys.	[F4]	[Stakeout] 1/3 Search : ★ □ Pt. : 5 ↑ □ T. H : 1.500 m 1 △ Hz : ← -13° 29′ 60″ △ □ : △ □ : ALL DIST REC ↓ EDM Coord. View ↓ Polar SO-PT
② Press [F2](SO-PT) to go to SO-Input data screen.	[F2] + Input point	[SO-Input data] N : 0.000 m E : 0.000 m
Input the coordinates of stakeout point. After input one item, the curser will move to next input item.	name and coordinates + [ENT]	Z : 0.000 m

③ After finishing inputs, press [F4](OK) to save the data. And then back to Stakeout screen. Start to stakeout the input point. The program will name this point **DEFAULT** automatically. ※¹



※¹: [SO-PT]: The input point won't be saved into job.

6.2 Polar Stakeout Mode



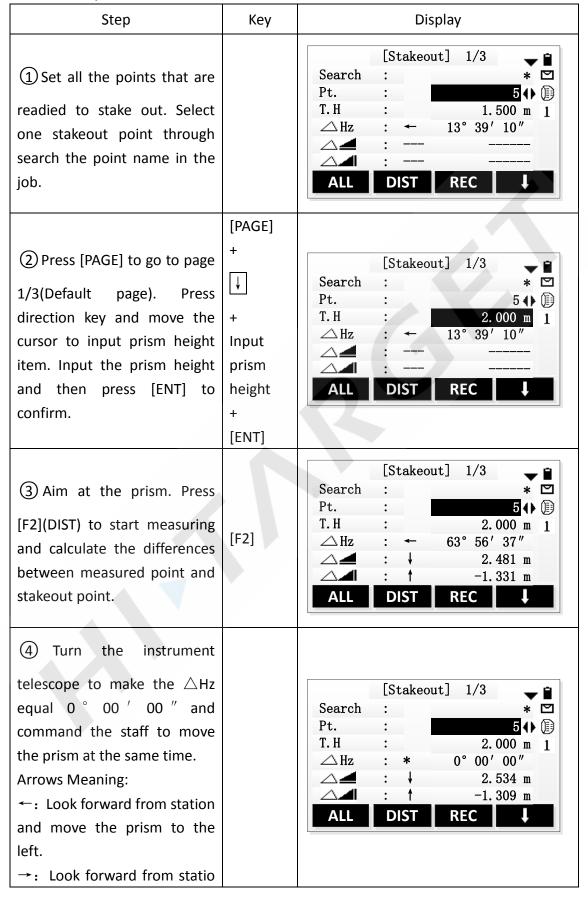
The meanings of the differences in the Polar Stakeout mode:

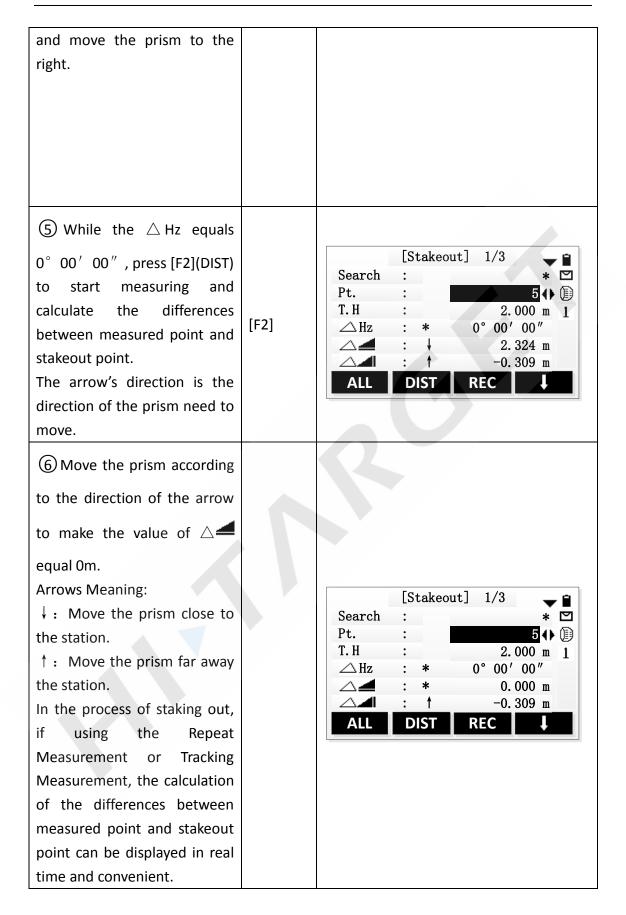
 \triangle Hz Difference in direction: If the measured point is located in the right side of stakeout point, the value is positive.

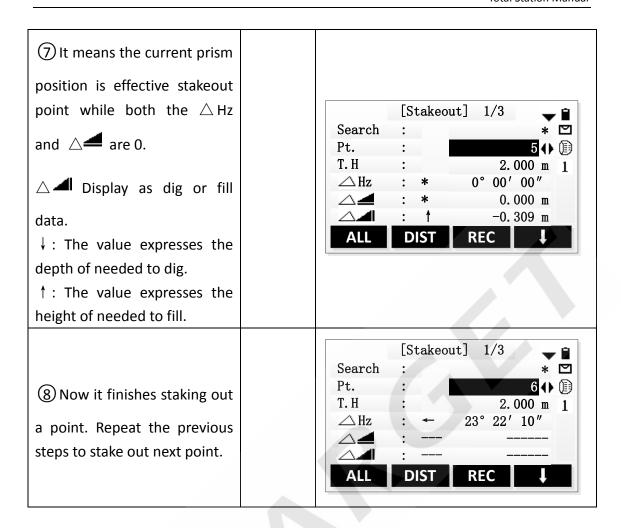
Difference in horizontal distance: If the measured point is farther than stakeout point, the value is positive.

△ Difference in height: If the measured point is higher than stakeout point,

the value is positive.

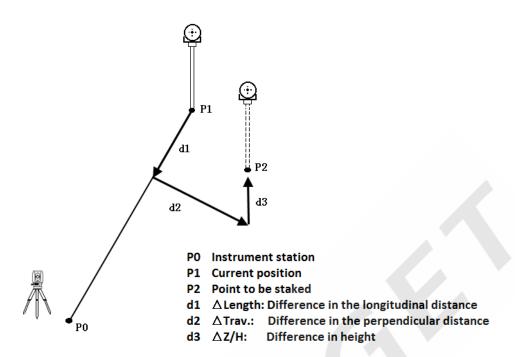






6.3 Orthogonal to Station Stakeout Mode

Use longitudinal difference and perpendicular difference to indicate the position differences of stakeout point and current prism position.

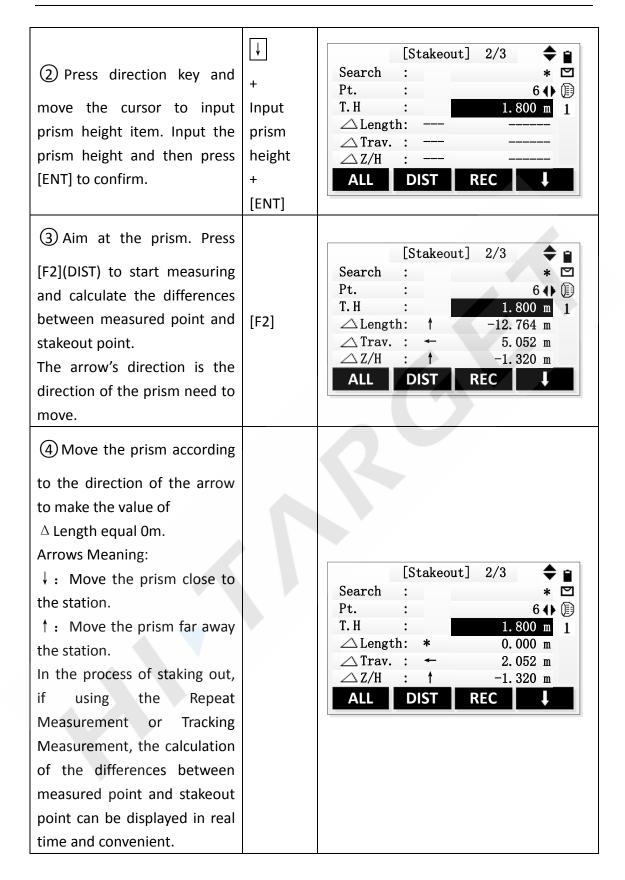


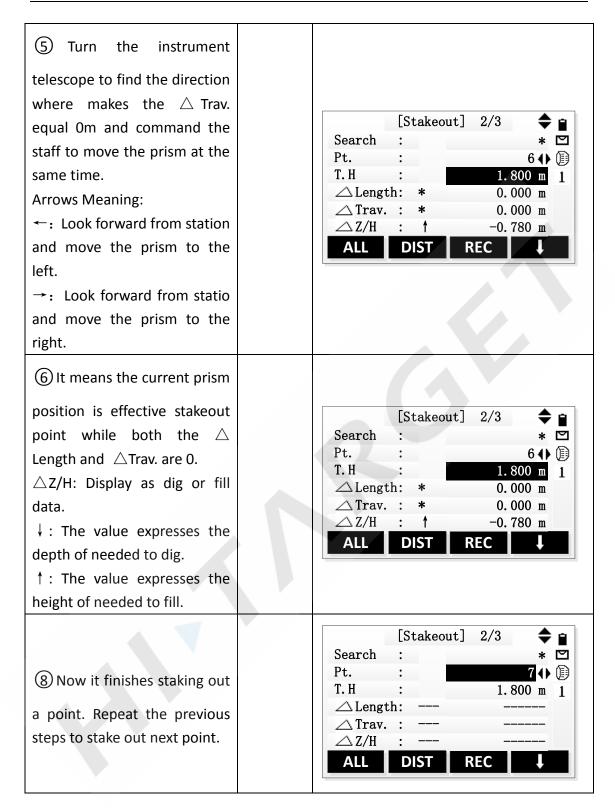
The meanings of the differences in the Orthogonal to Station Stakeout Mode:

 \triangle Length Difference in longitudinal distance: If the measured point is farther than stakeout point, the value is positive.

 \triangle Trav. Difference in perpendicular distance: If the measured point is located in the right side of stakeout point, the value is positive.

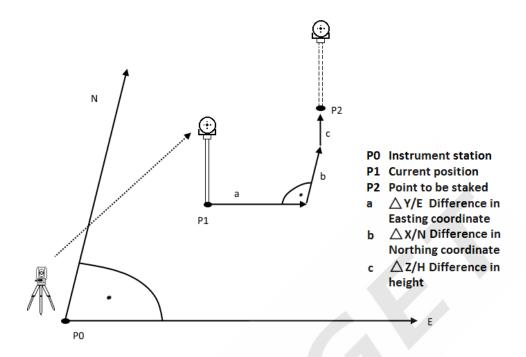
Step	Key	Display
① Press [PAGE] to show Orthogonal to Station Stakeout Mode in page 2/3. Set the stakeout point. The stakeout point can be found in the job through inputting point name in the search item.	[PAGE]	[Stakeout] 2/3 ♣ ♠ Search : * ♥ Pt. : 6 ♠ ♠ T. H : 1.500 m 1 △ Length: △ Trav. : △ Z/H : ALL DIST REC ↓





6.4 Cartesian Stakeout Mode

Stake out point based on the Cartesian coordinate system. The deviation values are the coordinate differences.

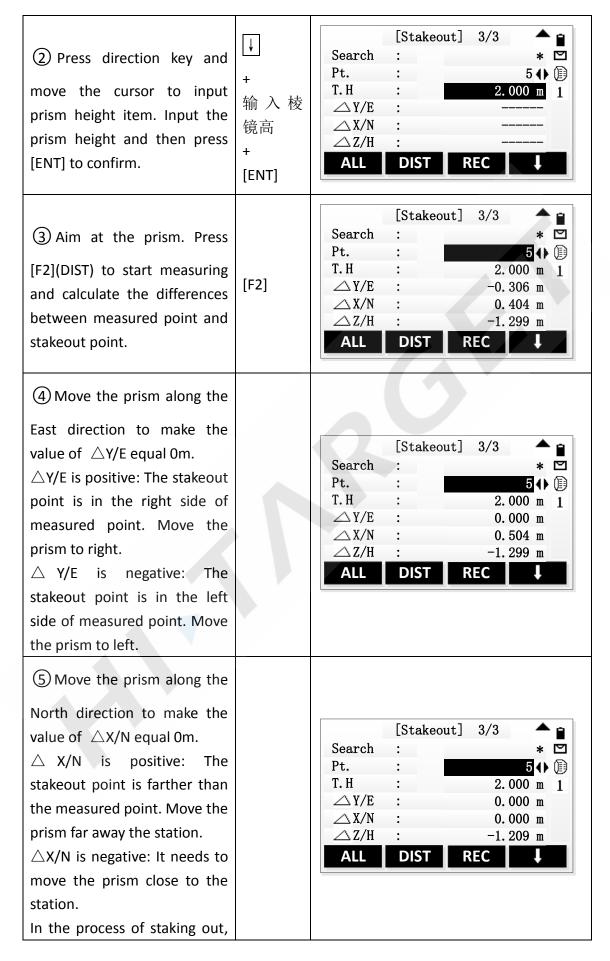


The meanings of the differences in the Cartesian Stakeout Mode:

 \triangle Y/E The difference in East coordinate between measured point and stakeout point.

 $\triangle {\rm X/N}$ The difference in North coordinate between measured point and stakeout point.

Step	Key	Display
1 Press [PAGE] to show Cartesian Stakeout Mode in page 3/3. Set the stakeout point. The stakeout point can be found in the job through inputting point name in the search item.	[PAGE]	Search : * □ Pt. : 5 ♠ □ T. H : 1.500 m 1 △Y/E : △X/N : △Z/H : ALL DIST REC ↓

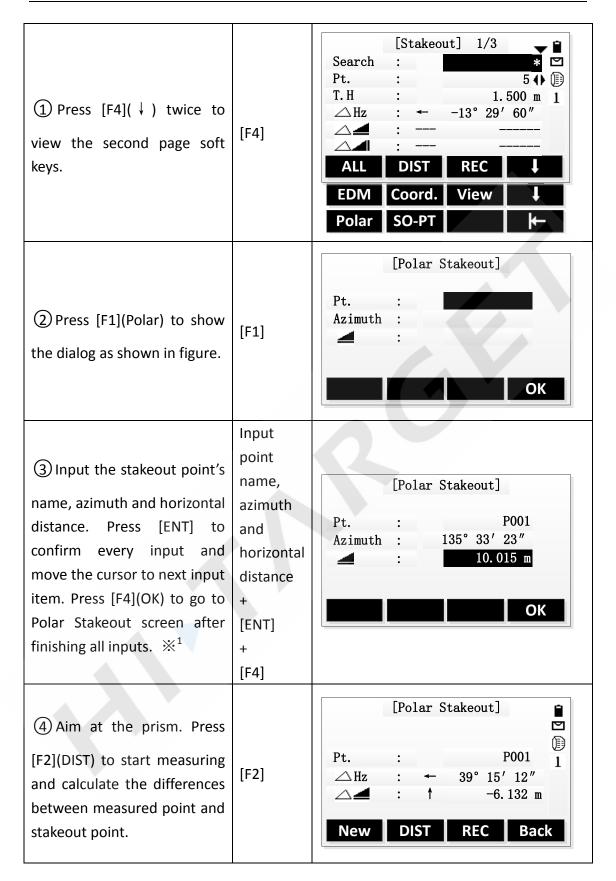


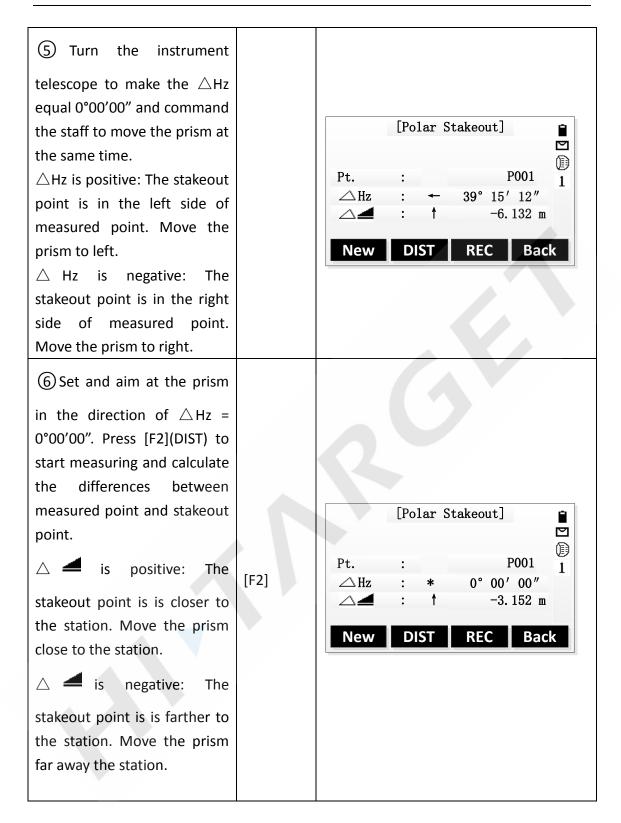
if using the Repeat Measurement or Tracking Measurement, the calculation of the differences between measured point and stakeout point can be displayed in real time and convenient.	
⑥ It means the current prism position is effective stakeout point while both the △Y/E and △X/N are 0. △Z/H: Display as dig or fill data. △Z/H is positive: The value expresses the depth of needed to dig. △Z/H is negative: The value expresses the height of needed to fill.	[Stakeout] 3/3
Now it finishes staking out a point. Repeat the previous steps to stake out next point.	Search : * □ Pt. : 6 ♠ ଢ T. H : 2.000 m 1 △Y/E :

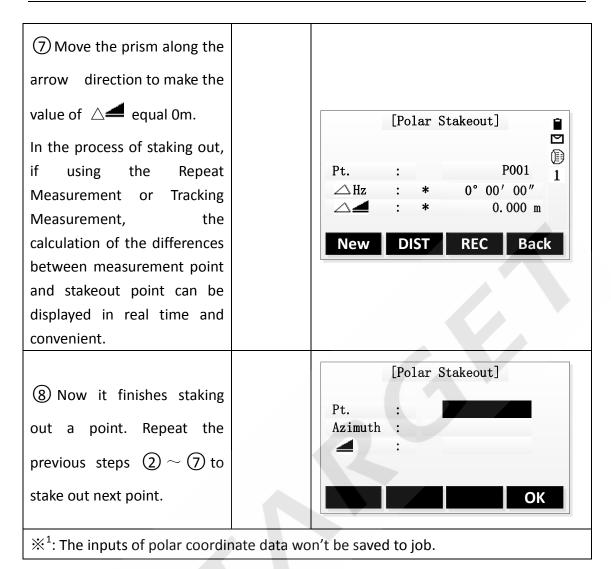
6.5 [Polar]

Press [Polar], then input the polar stakeout elements: Azimuth and Horizontal distance. Start to stake out after finishing inputs of Azimuth and Horizontal distance.

Step	Key	Display
------	-----	---------





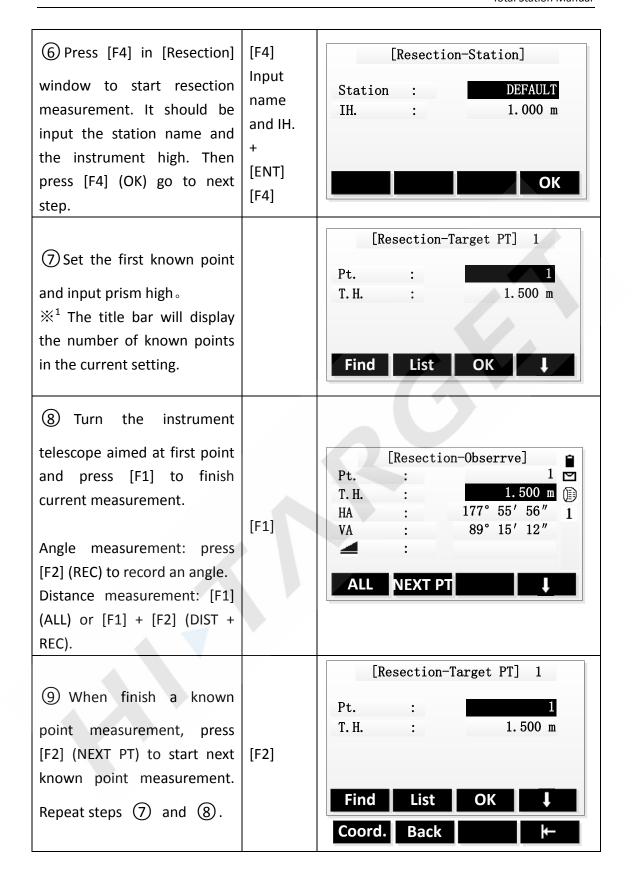


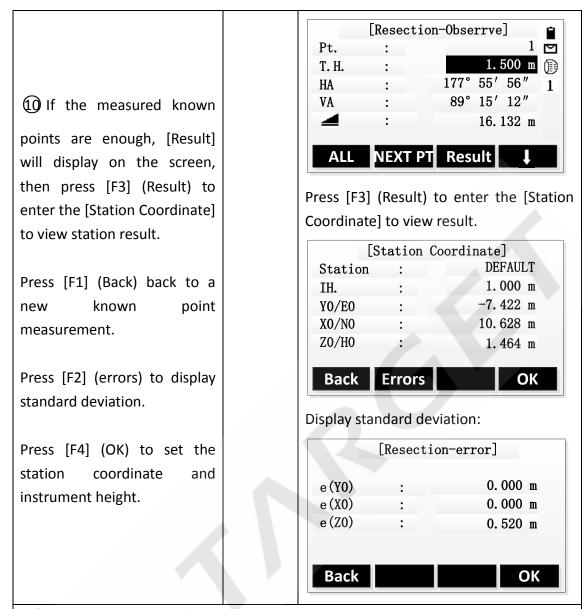
7. Resection

Resection measurement is an application used to determine the coordinate of the instrument station by measuring multiple known points. A minimum of 2 and a maximum of 5 known points can be used to determine the station. It should be used at least 2 known points by distance measurement or at least 3 known points by angle measurement.

Step Key Display

① Select "Program" from the [Main Menu] window, press [F3] or number key [3] to enter the Resection application.	[F3]	[Program] 1/2 ▼ F1 Surveying (1) F2 Stakeout (2) F3 Resection (3) F4 Tie Distance (4) F1 F2 F3 F4
② Press [F1] in the [Resection] window to set the job.	[F1]	[Resection] [] F1 Set Job F2 Set Error Limits F4 Start F1 F2 F4
③ In [Set Job] window, press [F1] (List) to select a job in memory or press [F2] (New) to new a job. Then press [F4] (OK) to next step.	[F4]	[Set Job] Job : DEFAULT Operator: Date : 20150515 Time : 14:10:20 List New OK
4) The window back to the [Resection] window, and press [F2] to set error limits.	[F2]	[Set Error Limits] Input error limits! Status : Off () e(Y/E) : 0.000 m e(X/N) : 0.000 m e(Z/H) : 0.000 m
⑤ Press [◄] \ [▶] to turn on the error limits status and use the key [▲] \ [▼] to move the focus down to input the every error limit. Then press [F4] (OK) to set and back to the [Resection] window.	Input error limits + [F4]	[Set Error Limits] Input error limits! Status :





**: The known points can be called from the memory through the [Find], [List] or manually entered used [Coord.].

8. Tie Distance

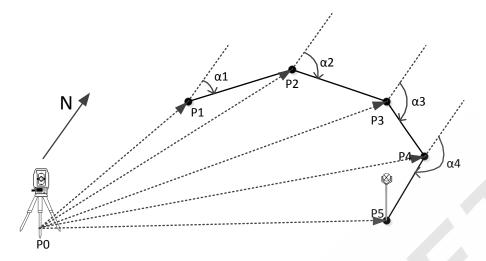
Tie Distance is an application used to compute slope distance, horizontal distance, height difference and azimuth of two target points which are either measured, selected from the memory, or input using the keypad.

The user can choose between two different methods:

- Polygonal: P1-P2, P2-P3, P3-P4.
- Radial: P1-P2, P1-P3, P1-P4.

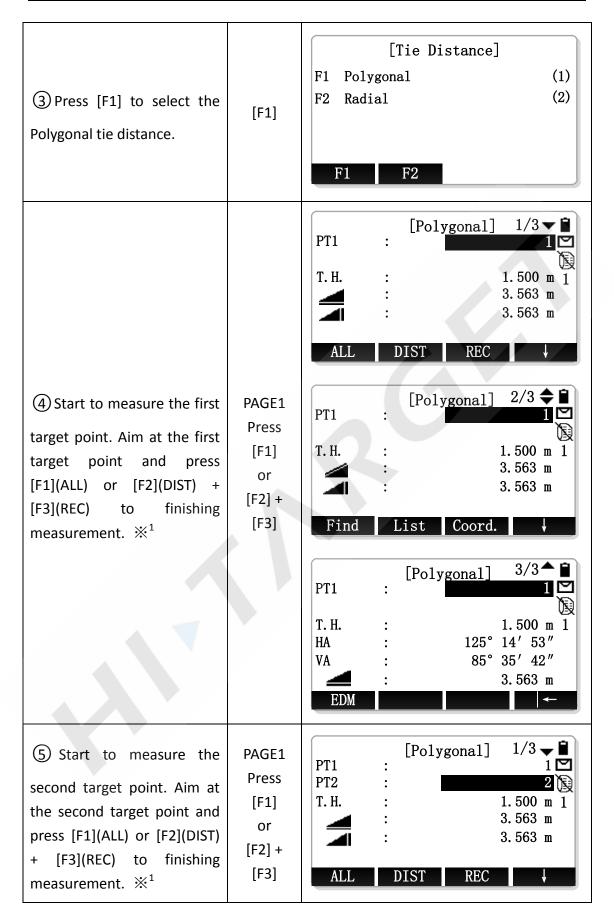
Start Tie Distance application through "Main Menu"→"Program"→"Tie Distance".

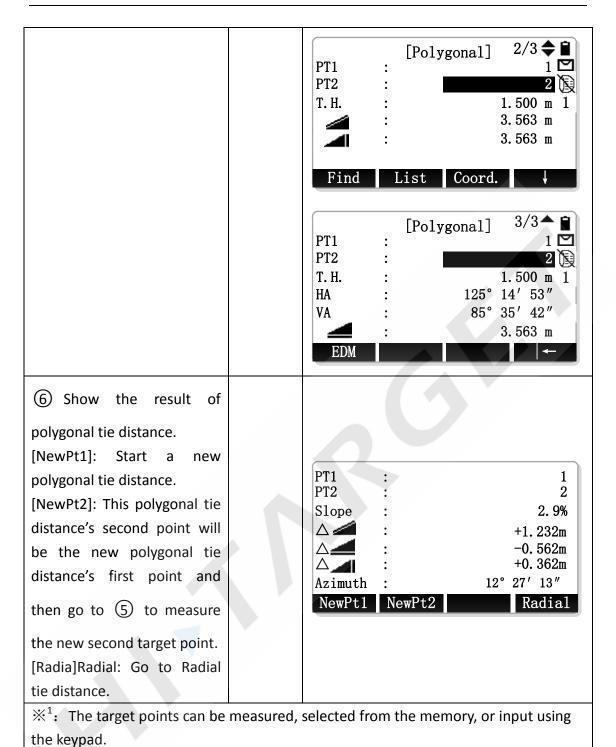
8.1 Polygonal



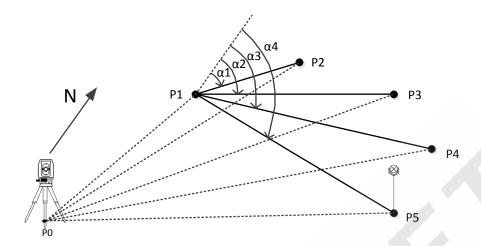
While Polygonal tie distance measuring continuous points, the new tie distance's first point will use the previous one tie distance's second point(P1-P2、P2-P3、P3-P4······).

Step	Key	Display
① Press [F4] in the Program Menu to go to Tie Distance application.	[F4]	[Program] 1/2 F1 Surveying (1) F2 Stakeout (2) F3 Resection (3) F4 Tie Distance (4) F1 F2 F3 F4
② After finishing setting job, station and orientation, press [F4] in the Pre-Setting menu to go to Select Tie Distance Mode screen.	[F4]	[Tie Distance] [*] F1 Set Job (1) [*] F2 Set STA (2) [*] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4



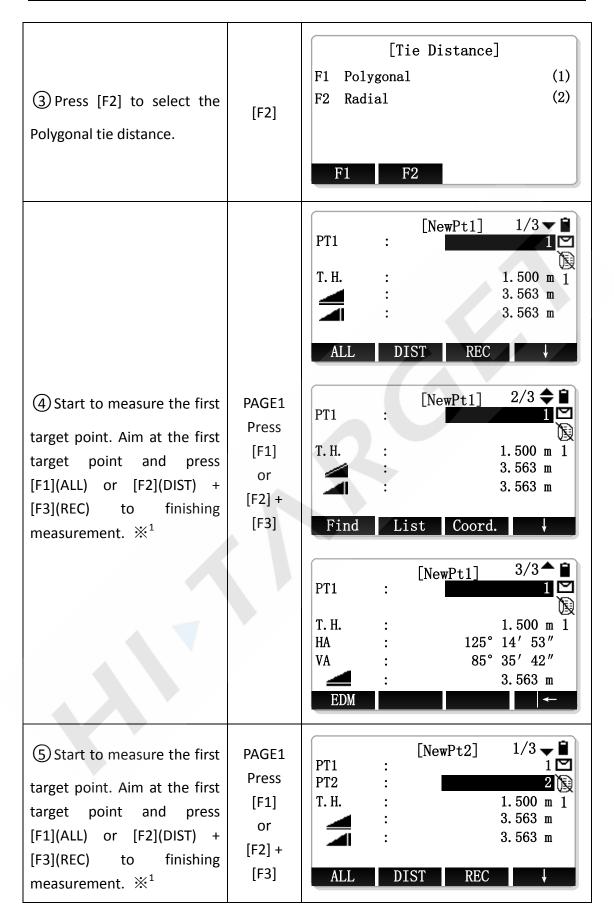


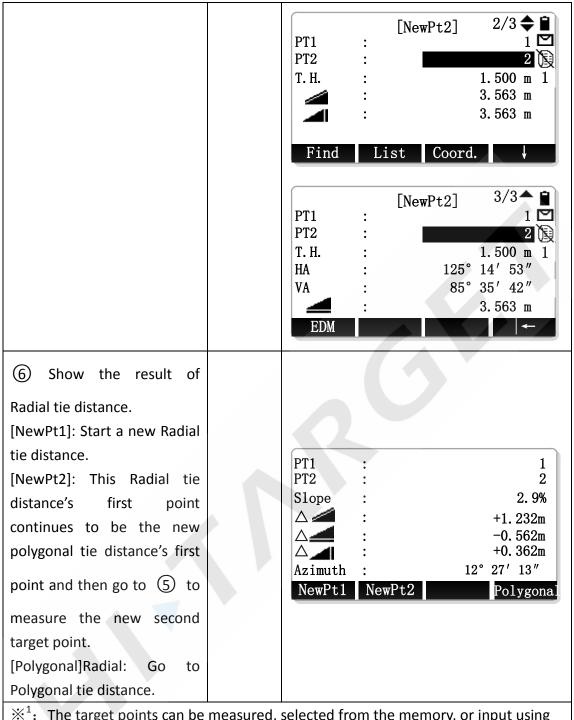
8.2 Radial



While Radial tie distance measuring continuous points, the new tie distance's first point continues using the previous tie distance's first point(P1-P2、P1-P3、P1-P4······).

Step	Key	Display
① Press [F4] in the Program Menu to go to Tie Distance application.	[F4]	[Program] 1/2 F1 Surveying (1) F2 Stakeout (2) F3 Resection (3) F4 Tie Distance (4) F1 F2 F3 F4
② After finishing setting job, station and orientation, press [F4] in the Pre-Setting menu to go to Select Tie Distance Mode screen.	[F4]	[Tie Distance] [*] F1 Set Job (1) [*] F2 Set STA (2) [*] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4





*: The target points can be measured, selected from the memory, or input using the keypad.

9. Area

Area is an application used to calculate the polygon areas to a maximum of 20 points which connected by straights. The target points coordinate can be measured, selected from memory or entered via keypad in same direction. And the following three methods can be alternately performed. The calculate area is projected onto the

horizontal plane (2D).

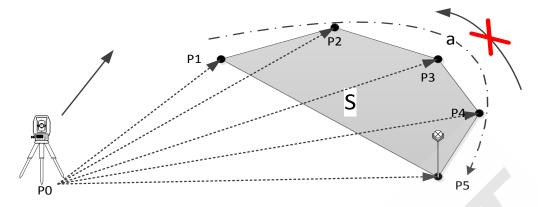
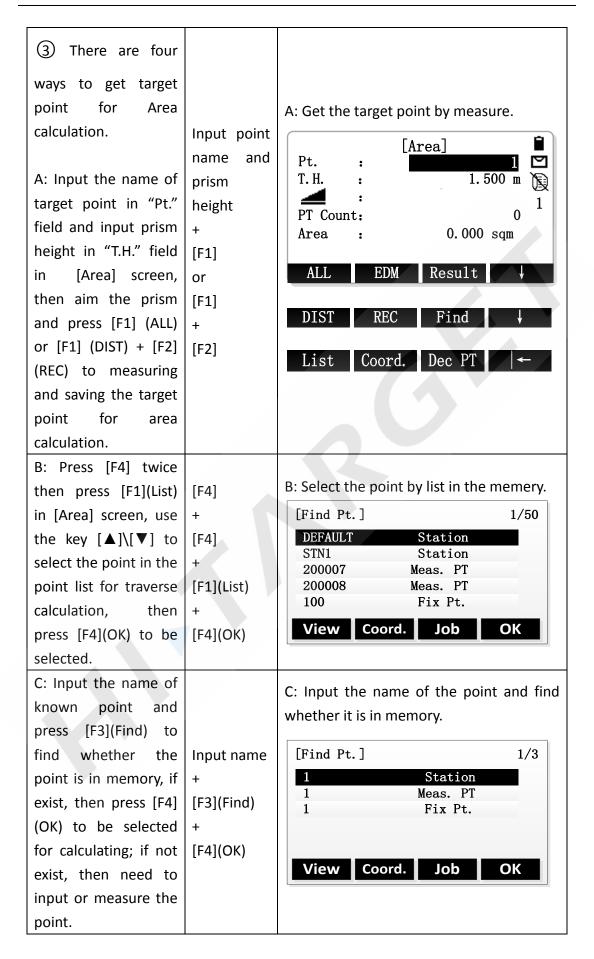
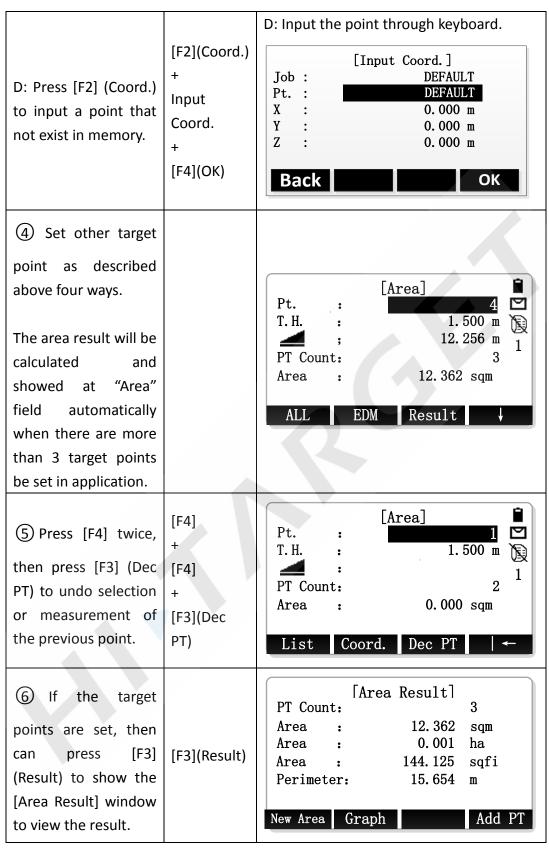


Figure 9.1 Area Diagram

- PO Instrument Point
- P1 Start Target Point
- P1~P5 Target Point
- a Perimeter, polygonal length from start point to the current measure point.
- S Calculated area always closed to the start point P1, projected onto the horizontal plane.

Step	Key	Display
① Select "Program" from the [Main Menu] window, then press [PAGE] switch	[PAGE]	[Program] 2/2 ▼ F1 Area (5) F2 Remote Height (6)
to second program list and press [F1] or number key [5] to enter the Area application.	[F1] or [5]	F3 C0G0 (7) F4 Road (8) F1 F2 F3 F4
2 After finishing the pre-settings (know more details at the beginning of chapter 5), press [F4] to start Area app.	[F4] or [4]	[Area] [*] F1 Set Job (1) [*] F2 Set STA (2) [*] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4





In [Area Result] window:

Press [F1] (New Area) to restart a new Area application.

Press [F2] (Graph) to show the area graph projected onto the horizontal plane.

Press [F4] (Add PT) to return the current Area application and continue

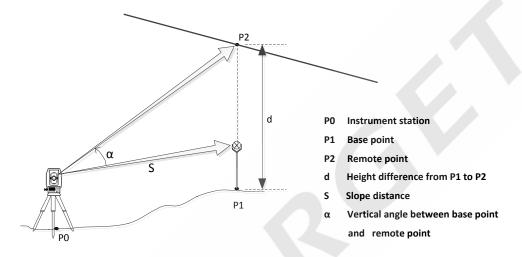
operation.

Press [ESC] to exit the Area application.

※ In all of the above operation, press [ESC] to return to the previous screen.

10. Remote Height

Remote Height is an application used to measure the height to the target (such as electric cable, bridge, etc.) where can't be set prism.



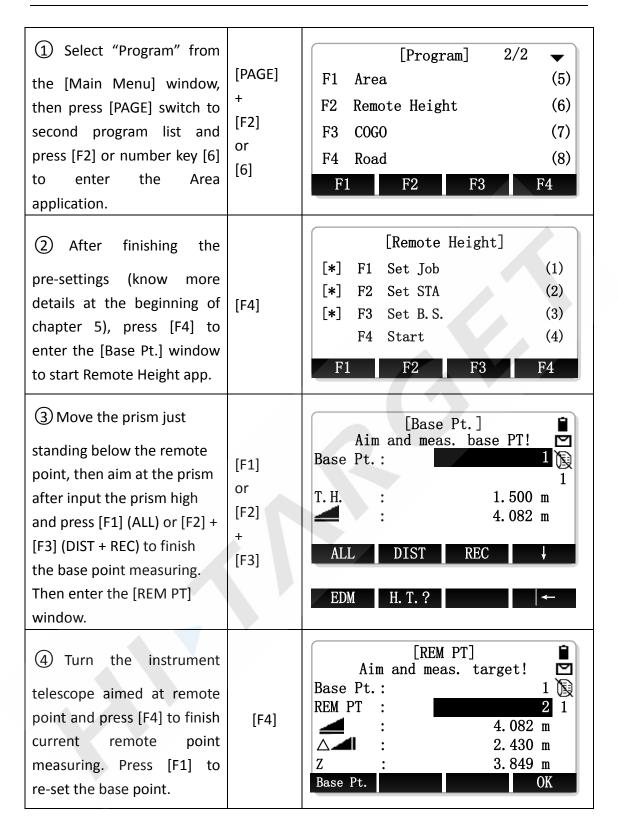
10.1 Prism High Known

If the high of prism is known, the calculation formula of the remote height is:

$$H = S * \cos \alpha_1 * \tan \alpha_2 - S * \sin \alpha_1 + V$$

- H Height difference between the base point and the remote point
- V Prism High
- α₁ Vertical angle to prism
- α₂ Vertical angle to target

Step	Key	Display
	•	• •

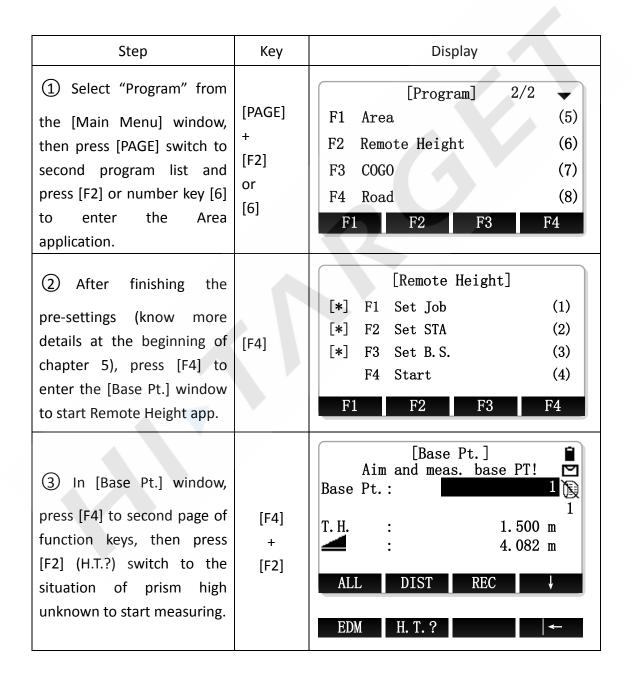


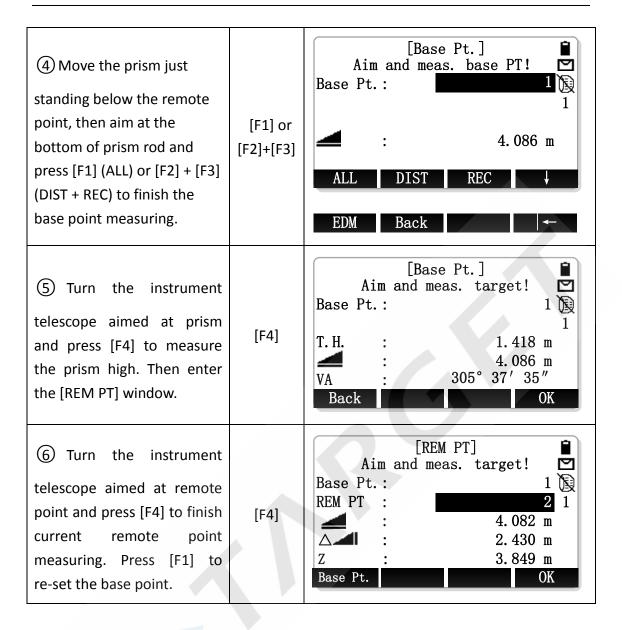
10.2 Prism High Unknown

If the high of prism is unknown, the calculation formula of the remote height is:

$$H = S * \cos \alpha_1 * \tan \alpha_2 - S * \sin \alpha_1 * \tan \alpha_3$$

- H Height difference between the base point and the remote point
- V Prism High
- S Slope distance between instrument and prism
- α₁ Vertical angle to prism
- α₂ Vertical angle to target point (remote point)
- α_3 Vertical angle to base point





11. COGO

COGO (Coordinate Geometry) is an application used to perform coordinate geometry calculations by the preset conditions such as , coordinates of points, bearings between points and distance between points.

The COGO calculation methods include:

- ♦ Inverse and Traverse
- ♦ Intersections
- ♦ Offset
- ♦ Extension

11.1 Traverse

Use the traverse subapplication to calculate the plane coordinate of a new point

using the bearing and distance from a known point. Offset is optional.

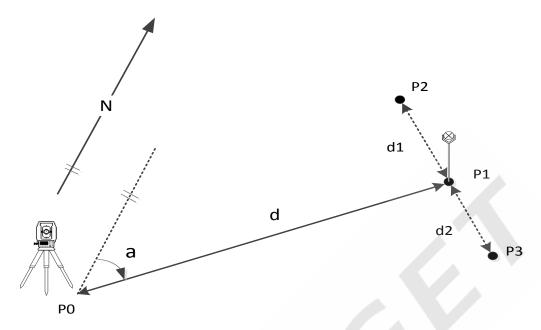


Figure 11.1 Traverse Diagram

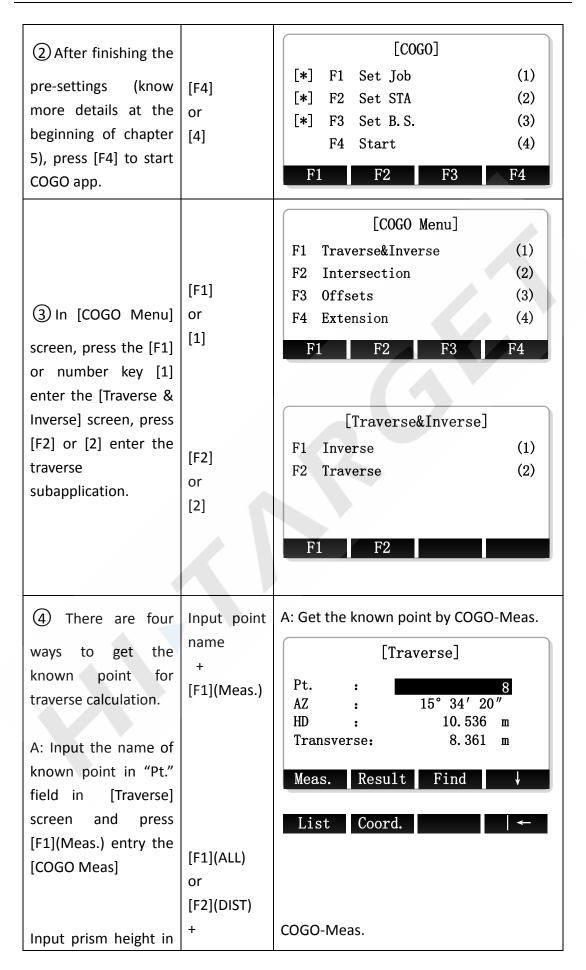
Κ	n	O	W	/r	١

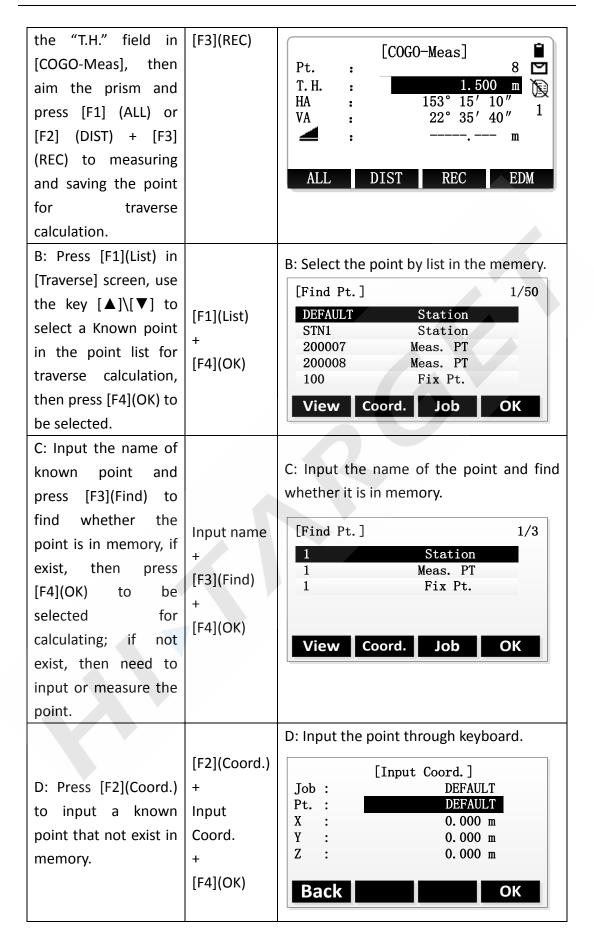
- PO known point
- a Direction from P1 to P2
- d Distance between P1 and P2
- d1 Positive offset to the right
- d2 Negative offset to the left

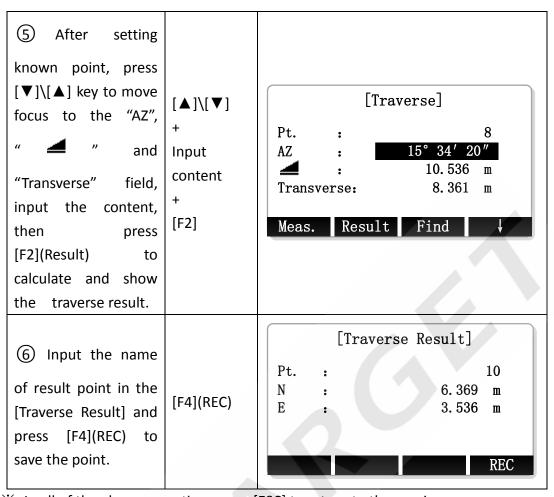
Unknown

- P1 COGO point without offset
- P2 COGO point with negative offset
- P3 COGO point with positive offset

Step	Key	Display			
① Select "Program"					
from the [Main		[Program] 2/2	▼)		
Menu] window, then	[PAGE]	F1 Area	(5)		
press [PAGE] switch	+	F2 Remote Height	(6)		
to second program	[F2]	F3 COGO	(7)		
list and press [F1] or	or	F4 Road	(8)		
number key [7] to	[7]	F1 F2 F3 F	74		
enter the COGO					
application.					







[※] In all of the above operation, press [ESC] to return to the previous screen.

11.2 Inverse

Use the inverse subapplication to calculate the distance, direction, height difference between two known points.

^{*} The result point is plane data.

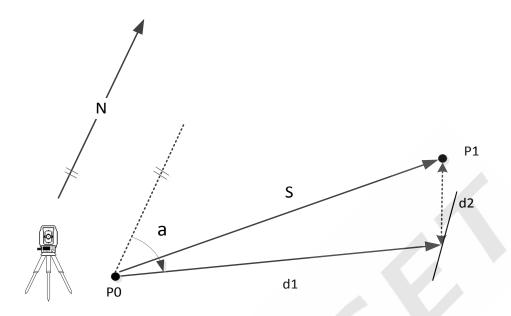


Figure 11.2 Inverse Diagram

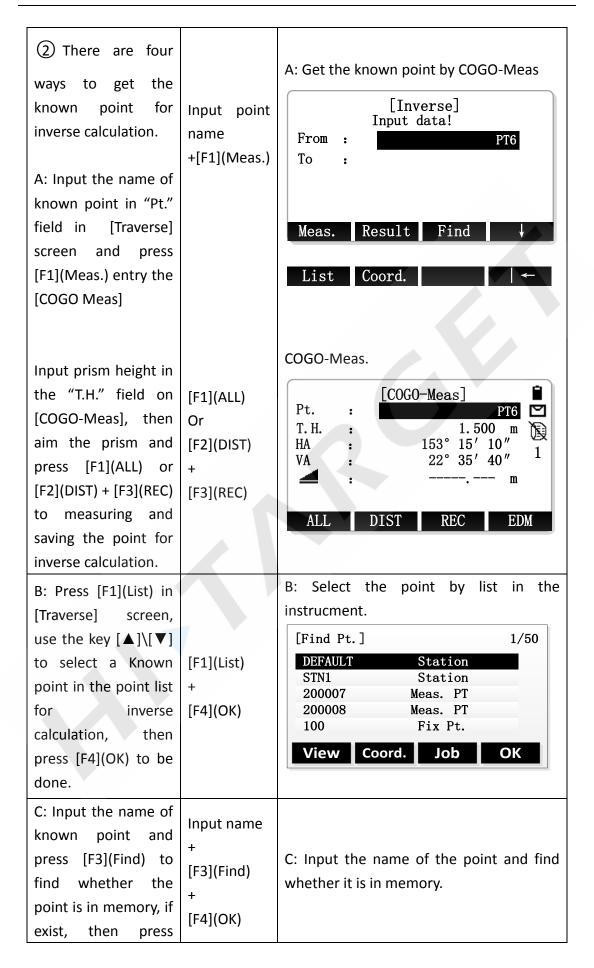
Known

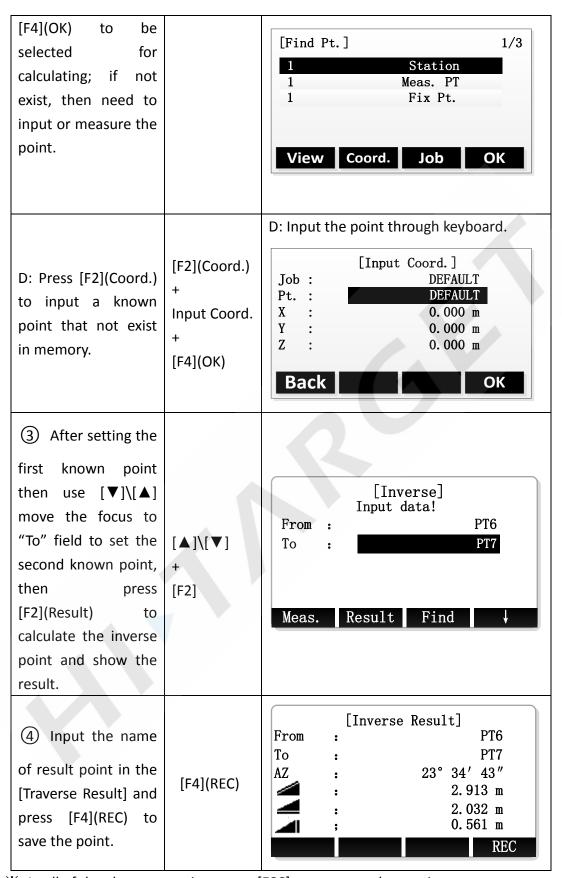
- PO First known point
- P1 Second known point

Unknown

- a Direction from P0 to P1
- S Slope distance between P0 and P1
- d1 Horizontal distance between P0 and P1
- d2 Height difference between P0 and P1

Step	key	Display
① In the [Traverse & Inverse] screen, press [F1] or [1] to enter the Inverse subapplication.	[F1] or [1]	[Traverse&Inverse] F1 Inverse (1) F2 Traverse (2) F1 F2





- ※ In all of the above operation, press [ESC] to return to the previous menu.
- * The result point is plane data.

11.3 Bearing-Bearing Intersection

Use the bearing-bearing (BRG-BRG) subapplication to calculate the intersection point of two lines. A line is defined by a point and a direction.

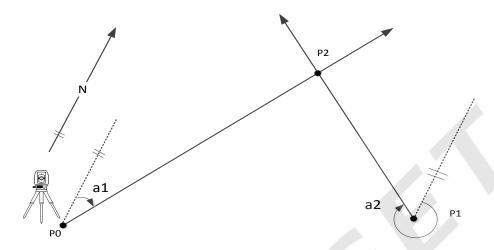


Figure 11.3 BRG-BRG Diagram

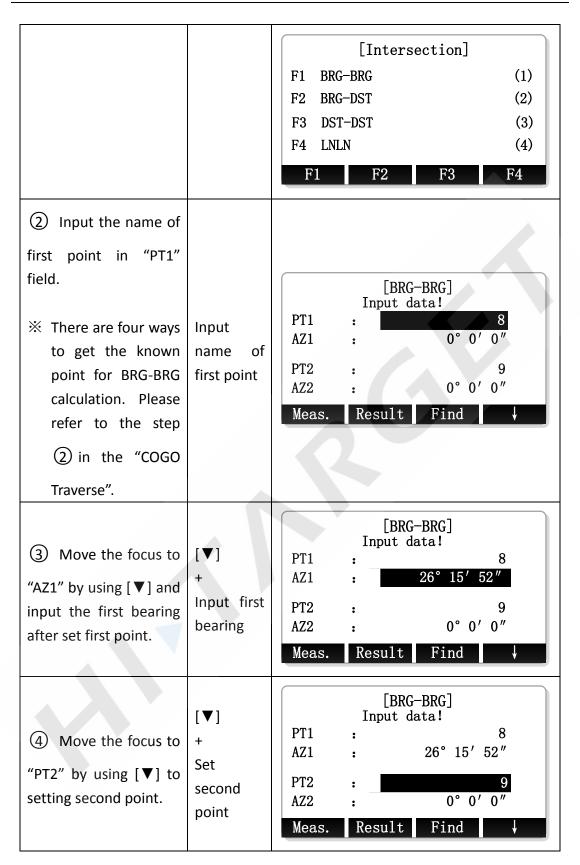
Known	K	n	o	W	7	n
-------	---	---	---	---	---	---

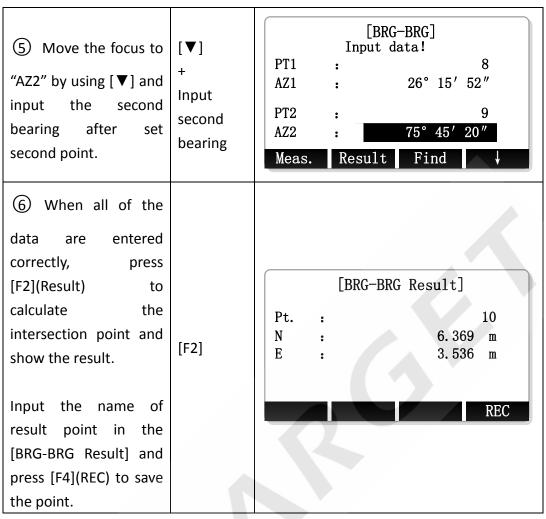
- PO First known point
- P1 Second known point
- a1 Direction from P0 to P2
- a2 Direction from P1 to P2

Unknown

P3 COGO point

Step	key	Display	
Step ① In [COGO Menu] screen, press the [F2] or number key [2] to enter the [Intersection] screen. Then press [F1] or [1] to enter the	[F2] or [2]	Display [COGO Menu] F1 Traverse&Inverse (1) F2 Intersection (2) F3 Offsets (3) F4 Extension (4) F1 F2 F3 F4	- 1
BRG-BRG	[F1] or		
subapplication.	[1]		





[※] In all of the above operation, press [ESC] to return to the previous menu.

11.4 Bearing-Distance Intersection

Use the bearing-distance (BRG-DST) subapplication to calculate the intersection point of a line and a circle. The line is defined by a point and a direction. The circle is defined by the center point and the radius. The result may be have 1 intersection point, may be have 2 points, or may be have no one.

^{*} The result point is plane data.

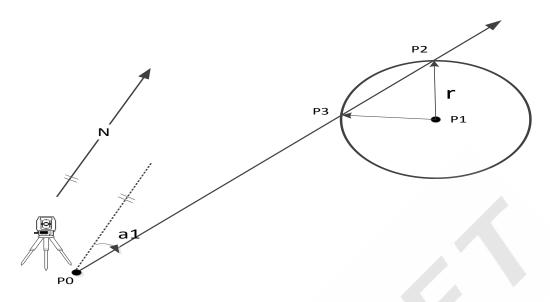


Figure 11.4 BRG-DST Diagram

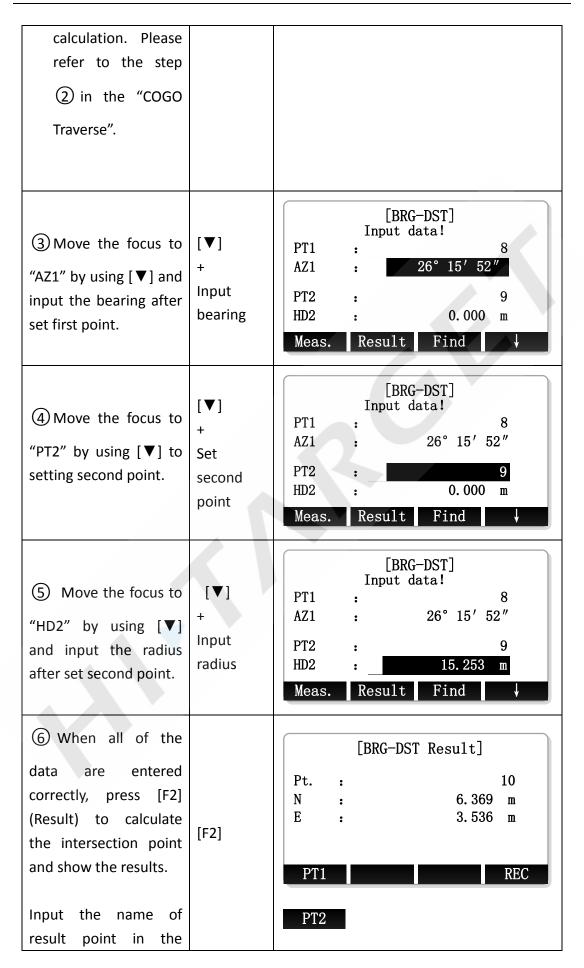
Known

- PO First known point
- P1 Second known point
- a1 Direction from P0 to P2 or P3
- r Radius, as the distance from P1 to P2 or P3

Unknown

- P2 First COGO point
- P3 Second COGO point

Step	key	Display
① In the [Intersection] screen, press [F2] or [2] to enter the BRG-DST subapplication.	[F2] or [2]	[Intersection] F1 BRG-BRG (1) F2 BRG-DST (2) F3 DST-DST (3) F4 LNLN (4) F1 F2 F3 F4
② Input the name of first point in "PT1" field. ※ There are four ways to get the known point for BRG-DST	Input name of first point	[BRG-DST] Input data! PT1 : 8 AZ1 : 0° 0′ 0″ PT2 : 9 HD2 : 0.000 m Meas. Result Find ↓



[BRG-DST Result] and		
press [F4](REC) to save		
the point.		
Press [F1] to switch to		
view results.		

[※] In all of the above operation, press [ESC] to return to the previous menu.

11.5 Distance-Distance Intersection

Use the distance-distance (DST-DST) subapplication to calculate the intersection point of two circles. The circles are defined by the known point as the center point and the distance from the known point to the COGO point as the radius. The result may be have 1 intersection point, may be have 2 points, or may be have no one.

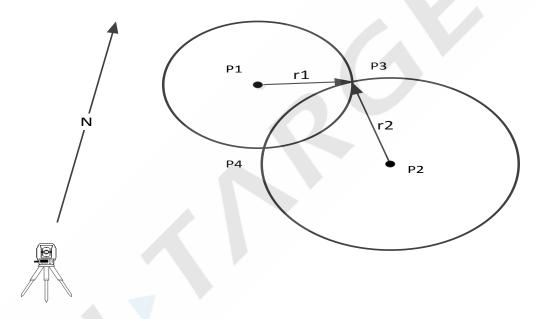


Figure 11.5 DST-DST Diagram

Known

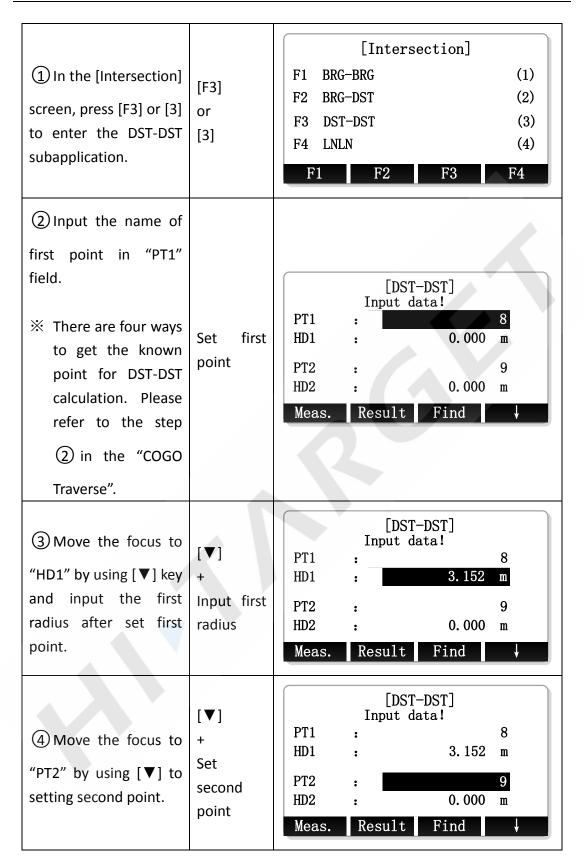
- P1 First known point
- P2 Second known point
- r1 Radius, as the distance from P1 to P3 or P4
- r2 Radius, as the distance from P2 to P3 or P4

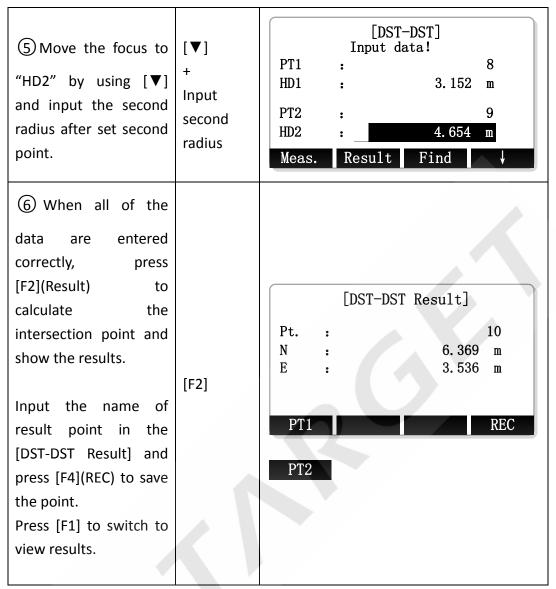
Unknown

P3 First COGO pointP4 Second COGO point

Step	key	Display

^{*} The result point is plane data.





[※] In all of the above operation, press [ESC] to return to the previous menu.

11.6 Line-Line Intersection

Use the line-line (LNLN) subapplication to calculate the intersection point of to lines. A line is defined by two points.

X The result point is plane data.

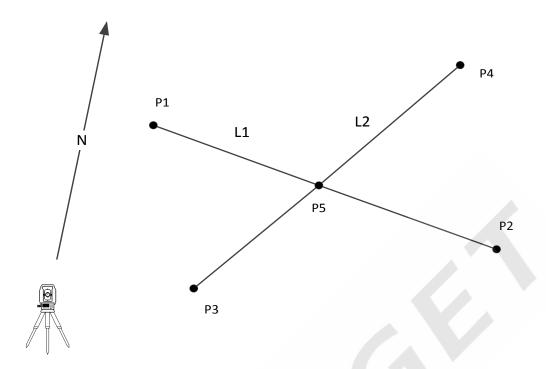


Figure 11.6 LNLN Diagram

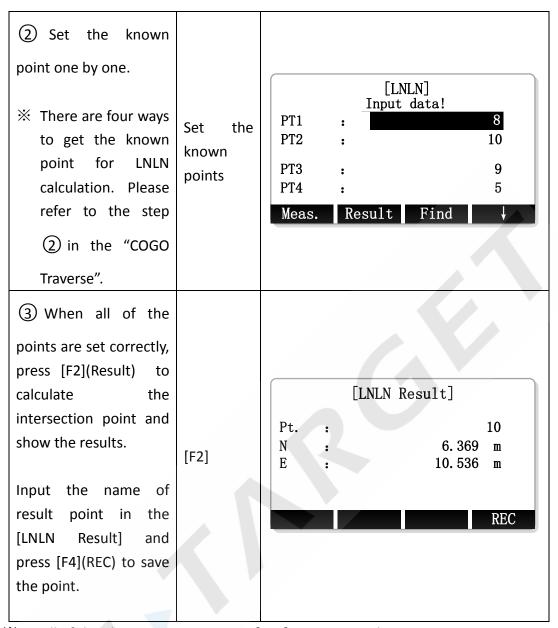
Known

- P1 First known point
- P2 Second known point
- P3 Third known point
- P4 Fourth known point
- L1 Line from P1 to P2
- L2 Line from P3 to P4

Unknown

P5 COGO point

Step	key	Display	
① In the [Intersection] screen, press [F4] or [4] to enter the LNLN subapplication.	[F4]	[Intersection] F1 BRG-BRG F2 BRG-DST F3 DST-DST F4 LNLN	(1) (2) (3) (4)
		F1 F2 F3	F4



- ※ In all of the above operation, press [ESC] to return to the previous menu.
- * The result point is plane data.

11.7 Distance-Offset

Use the distance-offset (DistOff) subapplication to calculate the foot point (COGO point) coordinates of offset point to baseline, the baseline is defined by two known points, and the longitudinal and offset distance of the offset point in relation to the line.

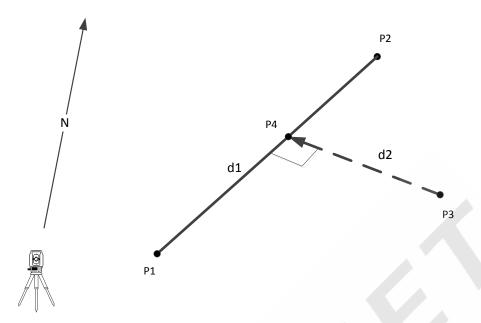


Figure 11.7 DistOff Diagram

Known

- P1 Start point
- P2 End point
- P3 Offset point

Unknown

- d1 \triangle Line
- d2 △Offset
- P4 COGO point (foot point)

Step	key	Display
① In [COGO Menu] screen, press the [F3] or number key [3] enter the [Offsets] screen, then press [F1] or [1] enter the DistOff subapplication.	[F3] or [3]	[COGO Menu] F1 Traverse&Inverse (1) F2 Intersection (2) F3 Offsets (3) F4 Extension (4) F1 F2 F3 F4 [Offsets] F1 DistOff (1) F2 Set Pt (2)
	[F1]	F1 F2

	or	
	[1]	
 ② Set the start point, end point and offset point one by one. ※ There are four ways to get the known point for DistOff calculation. Please refer to the step ② in the "COGO Trayerse". 	Set the known points	[Get Foot PT] Define baseline! PT1 : 8 PT2 : 9 Input Offset PT! PT3 : 10 Meas. Result Find ↓
③ When all of the		
points are set correctly, press [F2](Result) to calculate the intersection point and show the results. Input the name of result point in the [DistOff Result] and press [F4](REC) to save the point.	[F2] + [F4]	[DistOff Result] Pt. : 11 N : 6.369 m E : 10.536 m \$\Delta \text{Length:} 5.310 m \$\Delta \text{Trav.} : 2.249 m REC

- $\ensuremath{\mathbb{X}}$ In all of the above operation, press [ESC] to return to the previous menu.

11.8 Set Point

Use the Set Point (Set Pt) subapplication to calculate the coordinate of a new point in relation to a line from known longitudinal and offset distance.

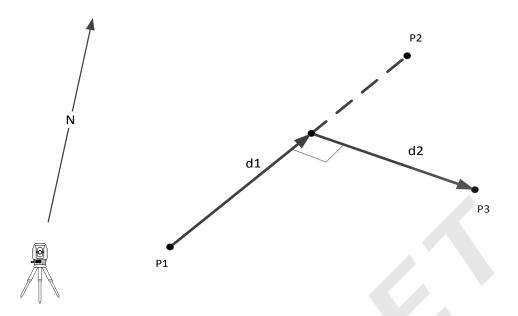


Figure 11.8 Set Point Diagram

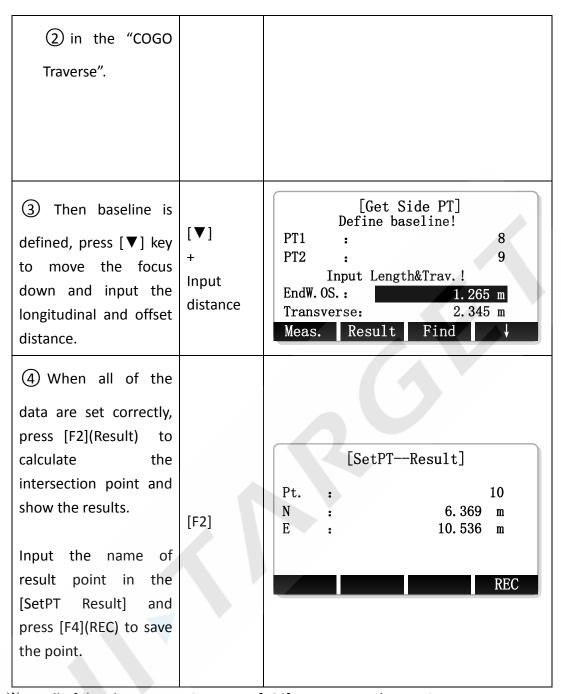
Known

- P1 Start Point
- P2 End Point
- d1 \triangle Line
- d2 △Offset

Unknown

P3 COGO point

Step	key	Display
① In the [Offsets] screen, press [F2] or [2] to enter the Set Point subapplication.	[F2] or [2]	[Offsets] F1 DistOff (1) F2 Set Pt (2) F1 F2
② Set the start point and end point.※ There are four ways to get the known point for Set Point calculation. Please refer to the step	Set known points	[Get Side PT] Define baseline! PT1 : 8 PT2 : 9 Input Length&Trav.! EndW. OS.: 0.000 m Transverse: 0.000 m Meas. Result Find ↓



- ※ In all of the above operation, press [ESC] to return to the previous menu.
- X The result point is plane data.

11.9 Extension

Use the Extension subapplication to calculate the coordinate of extended point from a known baseline.

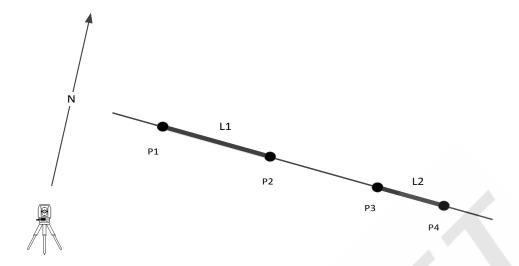


Figure 11.9 Extension Diagram

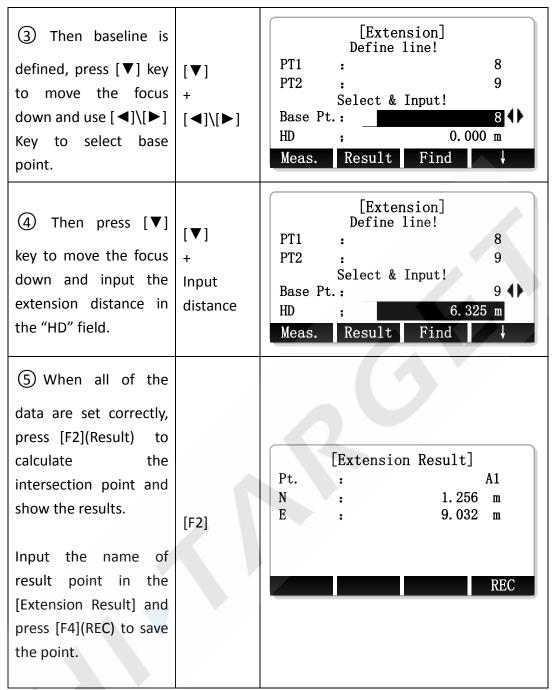
Known

- P1 Baseline Start Point
- P2 Baseline End Point
- L1, L2 Extension Distance

Unknown

P2, P4 Extended COGO Point

Step	Key	Display
① In the [COGO Menu] screen, press the [F4] or number key [4] enter the [Extension] screen.	[F4] or [4]	[COGO Menu] F1 Traverse&Inverse (1) F2 Intersection (2) F3 Offsets (3) F4 Extension (4) F1 F2 F3 F4
2 Set the baseline start point and end point. ** There are four ways to get the known point for Extension calculation. Please refer to the step 2 in the "COGO Traverse".	Set known points	[Extension] Define line! PT1: PT2: Select & Input! Base Pt.: HD; 0.000 m Meas. Result Find

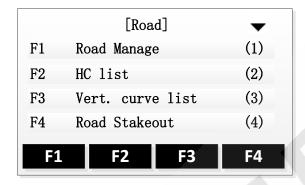


- In all of the above operation, press [ESC] to return to the previous menu.
- * The result point is plane data.

12. Road

Using this program, user can simplely define a straight line, circular curve or transition curve as reference, to do surveying or staking out.

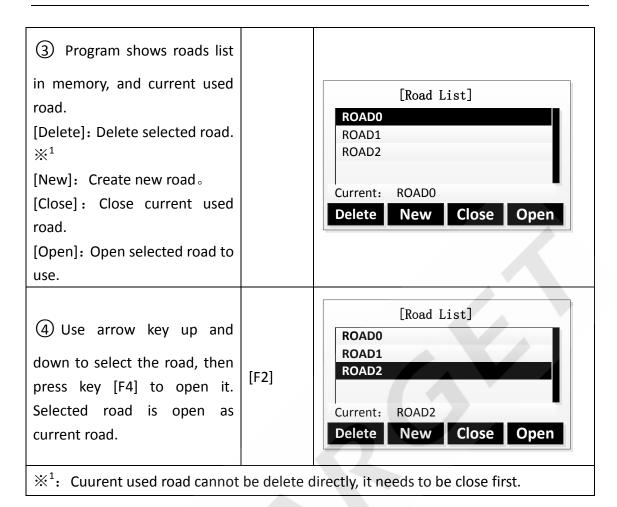
Setting job, setting station and setting backsight must be done before road define and staking out.



12.1 Road Manage

User can create some different roads. The data between different roads is individual.

Step	Key	Display
① Pressing key [F4] enter road function menu. For job setting, station setting and BS setting can refer early content.	[F4]	[Road] [*] F1 Set Job (1) [*] F2 Set STA (2) [*] F3 Set B. S. (3) F4 Start (4) F1 F2 F3 F4
② Pressing key [F1] enter road manage.	[F1]	[Road]



12.2 Horizontal curve definition

There are two ways to define the horizontal curve: one is 'elements method', another is 'intersection method'.

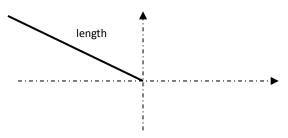
NOTE: Max amount of items of horizontal curve is 30.

Using elements method define horizontal curve.

Elements method constists of the following elements: start point, straight line, curcular curve and transition curve.

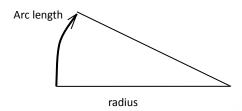
Straight line

The straight line can be defined when start point or other type of element have been defined.



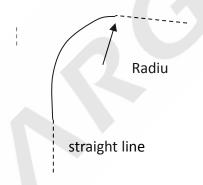
Straight line includes azimuth and distance, and the distance should no be negative.

Circular curve



Curcular curve includes radius and arc length. The rules of radius definition: Along the arc direction, radius is positive if arc is clockwise; radius is negative if arc is anti-clockwise. Arc length should not be negative.

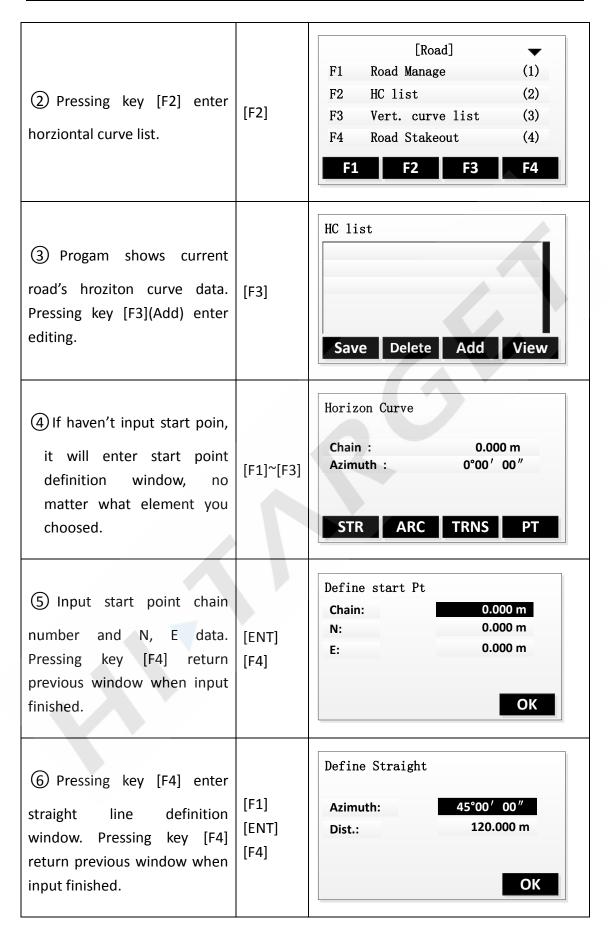
> Transition curve

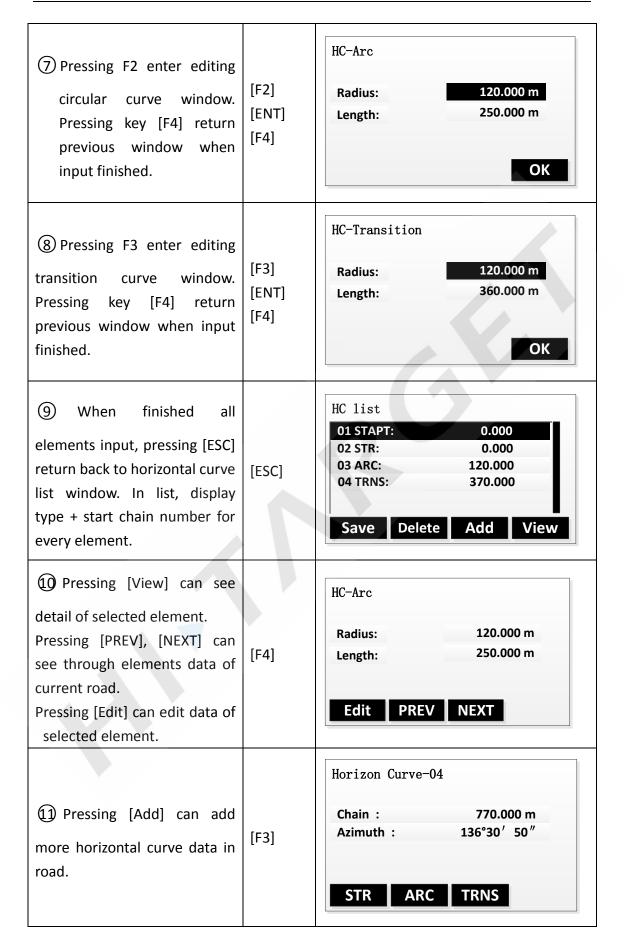


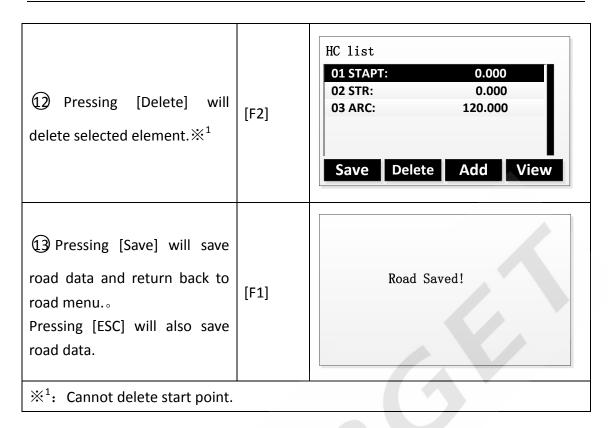
Transition curve includes the minimum radius and arc length. The rules of radius is same to curcular curve radius. Arc length should no be negative.

Steps:

Step	Key	Display	
① Pressing key [F4] enter Road functions menu.	[F4]	[Road] [*] F1 Set Job [*] F2 Set STA [*] F3 Set B.S. F4 Start F1 F2 F3	(1) (2) (3) (4)



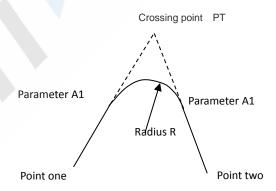




Using intersection method define horizontal curve.

The intersection point includes coordinate, radius, parameter A1 and A2 of transition curve. The radius and A1, A2 should not be negative. If radius not being zero, it will insert an arc with input radius between current point and next point. If A1, A2 not being zero, it will insert and transition curve with sepecified length between straight line and the arc.

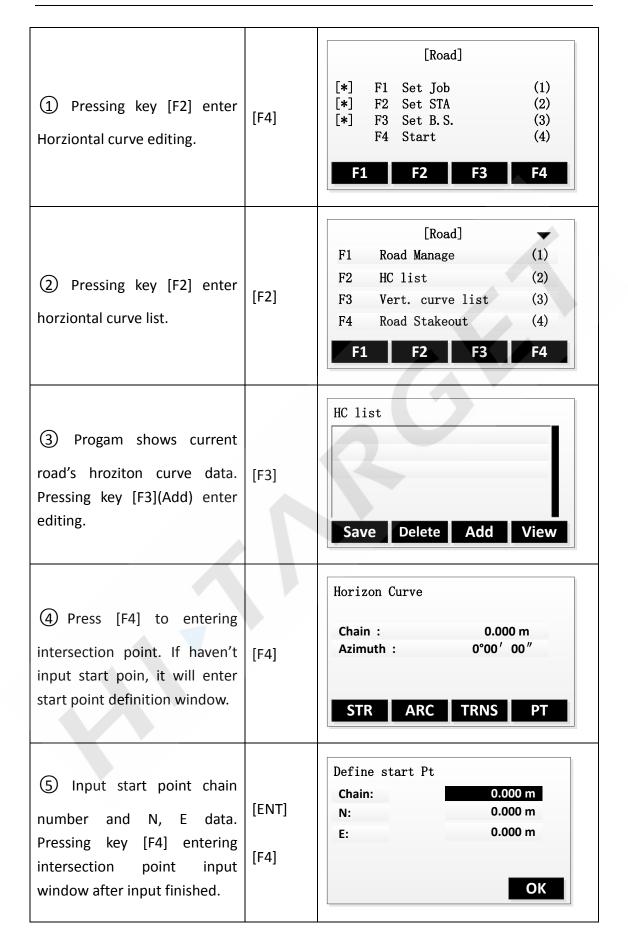
Don't mix the intersection point with straight line, circular curve or transition curve, otherwise the calculation will not be correct.



Follow is the intersection method for definition of horizontal curve steps.

Steps:

Step	Key	Display
------	-----	---------



\bigcirc Entering intersection point data, pressing [OK] go to next one input. $\%^1$	[ENT] [F4]	HC-Pt 1 N: E: 3457.345 m Radius: 450.000 m A1: 230.000 m A2: 350.000 m
7 When finished all points input, pressing [ESC] return back to horizontal curve list window. In list, display type + N value for every point.	[ESC]	HC list 01 START: 250.000 02 PT: 4524.897 03 PT: 5467.876 04 PT: 6784.362 Save Delete Add View
(8) Pressing [View] can see detail of selected point. Pressing [PREV], [NEXT] can see through points data of current road. Pressing [Edit] can edit data of selected point.	[F4]	HC-Pt N: 4524.897 m E: 3457.345 m Radius: 450.000 m A1: 230.000 m A2: 350.000 m Edit PREV NEXT
Pressing [Add] can add more horizontal curve data in road.	[F3]	Horizon Curve-04 Chain: 0.000 m Azimuth: 0°00′00″
① Pressing [Delete] will delete selected element. $\%^2$	[F2]	HC list O1 START: 250.000 O2 PT: 4524.897 O3 PT: 5467.876 Save Delete Add View

road data and return back to road menu...

Pressing [ESC] will also save road data.

[F1]

Road Saved!

※¹: When input A1, A2 according to curve length L1, L2, use follow formula to calculate A1, A2:

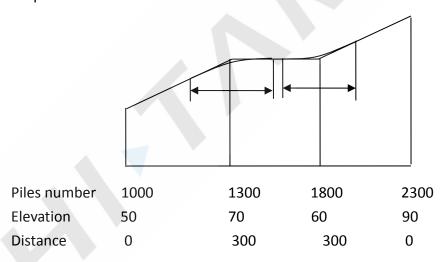
$$A_1 = \sqrt{L_1 \cdot R}$$

$$A_2 = \sqrt{L_2 \cdot R}$$

X²: Cannot delete start point.

12.3 Vertical curve definition

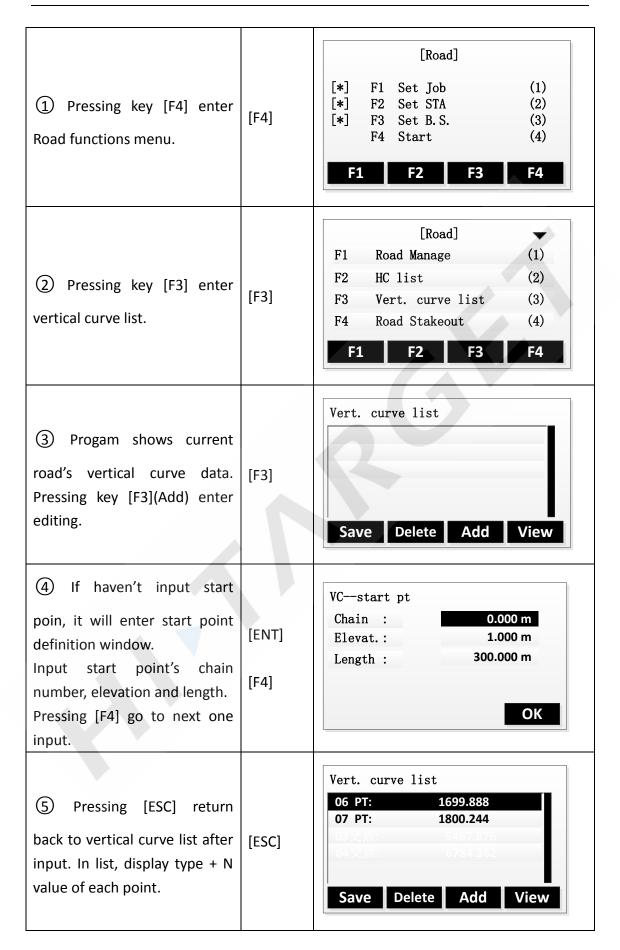
Vertical curve consist of a set of intersection points. Intersection point includes chain number, elevation and curve length. The curve length of start point and last point must be zero.

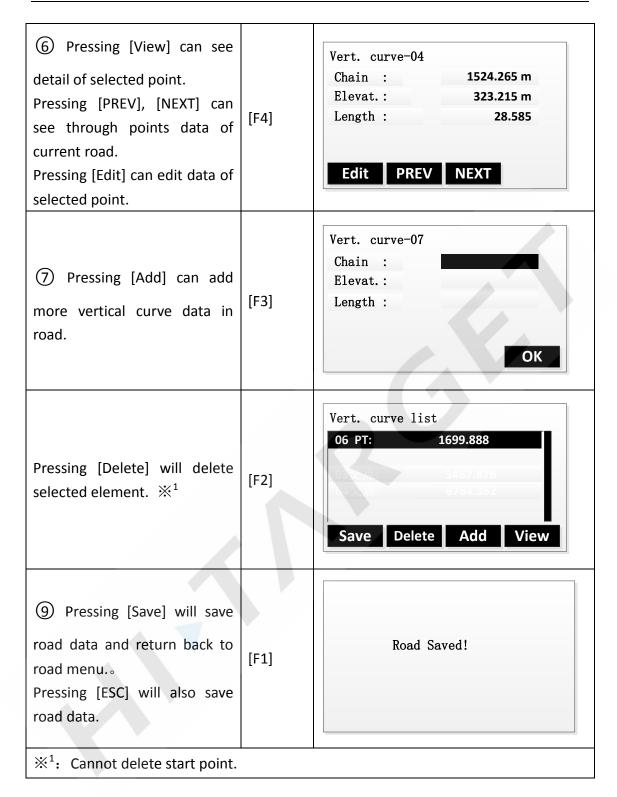


NOTE: Max amount of items of vertical curve is 30.

Steps:

	l	
Step	Key	Display





12.4 Road Stakeout

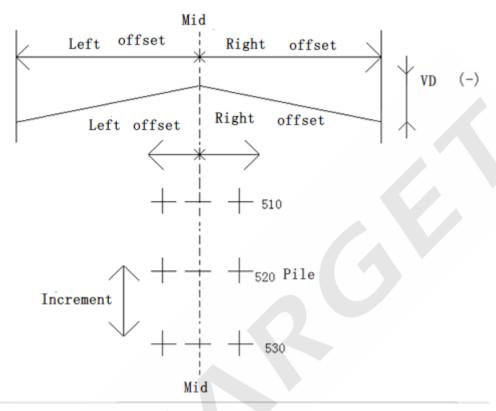
User can do road stakeout according to specific chain number and offset.

Before doing stakingout, user must define horizontal curve. If need calculating elevation, user must define vertical curve either.

The rules of stakeout data are defined as shown below:

Offset left: the horizontal distance between left pile and center line; Right: the horizontal distance between right pile and center line.

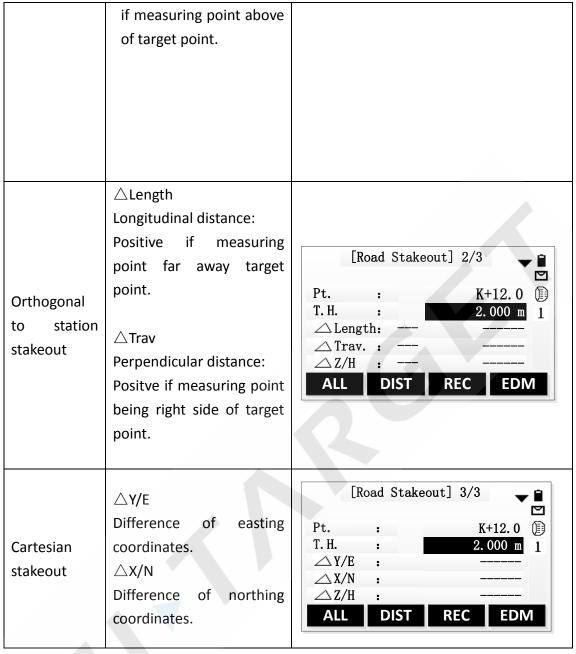
Elevation left(right): the vertical distance between lefit(right) pile and center line.



In doing stakeout, center pile should be done first, then left and right pile.

Like point stakeout, there are three methods to do stakeout:

Method	Definition	Display
Polar staketou	 △Hz Direction difference: Positve if measuring point being right side of target point. △ Horizontal distance difference: Positive if measuring point far away target point. △ Height difference: Positive 	[Road Stakeout] 1/3 Pt. : K+12.0 □ T. H. : 2.000 m 1 △ Hz : ← 13° 39′ 10″ △ ■ : △ ■ : ALL DIST REC EDM



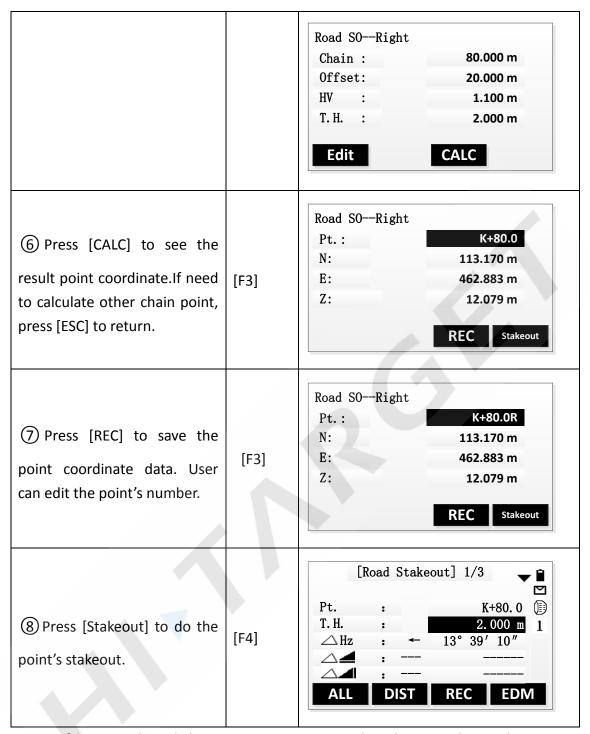
User can use [PAGE] key to switch method between these 3 methods.

Doing stakeout can refer to Point stakeout.

Steps

Step	Key	Display
------	-----	---------

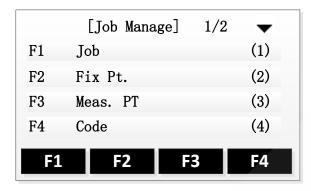
① Pressing key [F4] enter Road functions menu. Before doing stakeout, job seting, station seting, BS seting should be done.	[F4]	[Road] [*] F1 Set Job (1) [*] F2 Set STA (2) [*] F3 Set B.S. (3) F4 Start (4) F1 F2 F3 F4
② Pressing [F4] enter road stakeout.	[F4]	[Road] F1 Road Manage
③ Input road parameters and press [F4] entering chain parameters editing window.	[F4]	Road SO para. 1/2 StartC.: 0.000 m Incre.: 20.000 m
4 Input chain parameters and press [F4] to next window.	[F4]	Road SO para. 2/2 OffsL: OffsR: TgthL: TgthR: TgthR: OK
⑤ Program shows chain's paramters that user has input. Press [←][→] to left or right pile. Press [↓][↑] to increase or decrease chain number. Press [Edit] to edit the parameters.	[F4]	Road S0—Center Chain: 0.000 m Offset: 0.000 m HV: 0.000 m T. H.: 2.000 m



Note: If has saved road data, next time user can directly go to the road program witout input road data again.

6. File manage

File manager contains all functions of input data, edit data and view data.





1. Job

- All kinds of measurement data are saved in the selected job. Such as Fix Pt., Meas. PT and so on.
- The function can new a job, select a job and delete a job.
- > The definition of the job contains the inputing of Job's name and Operator.

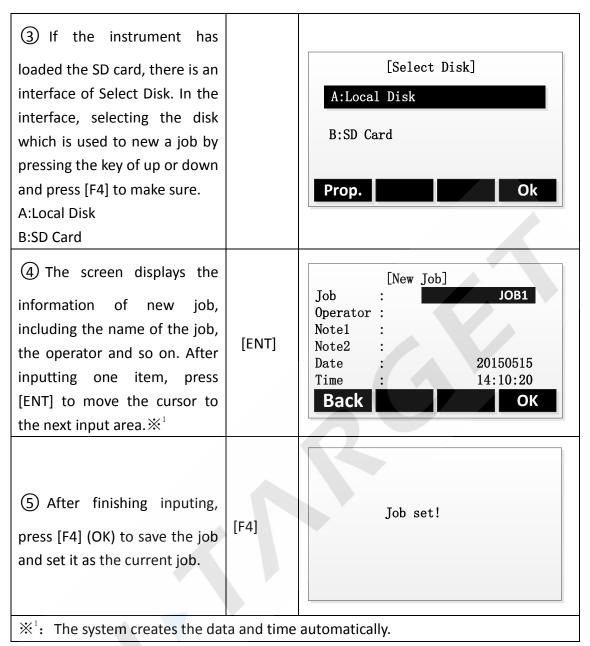
1.1 Select a Job

Steps	Key	Display		
① Press [F1] in the menu of Job Manager to enter menu of job function.	[F1]	F1 F2 F3 F4	[Job Manage] 1/2 Job Fix Pt. Meas. PT Code F2 F3	(1) (2) (3) (4)

[Job list] 2) The interface displays the J0B1 J0B2 job list in the current storage. [SD] JOB3 The jobs in the SD card have JOB4 [SD] the mark of "[SD]" and the current job have the mark of New View Delete "*". 3 Using the direction keys to [Job list] JOB1 select a job, when the [1]、 J0B2 needed job is selected, press [↓] JOB3 [SD] J0B4 [SD] the key of [F4], the program gives a prompt of "Job Set" [F4] Delete New View and open the job as the current job.

1.2 New a Job

Steps	Key	Display
① In the menu of Job Manager, press [F1] to enter the menu of job function.	[F1]	[Job Manage] 1/2 ▼ F1 Job (1) F2 Fix Pt. (2) F3 Meas. PT (3) F4 Code (4) F1 F2 F3 F4
2 The interface displays the job list in the current storage. The jobs in the SD card have the mark of "[SD]" and the current job have the mark of "*". Press [F2] (New) to enter the function of newing a job.		[Job list] JOB1 * JOB2 JOB3 [SD] JOB4 [SD] Delete New View OK



[Job]: The name of job inputted arbitrarily by the operator and saving data to the file after this.

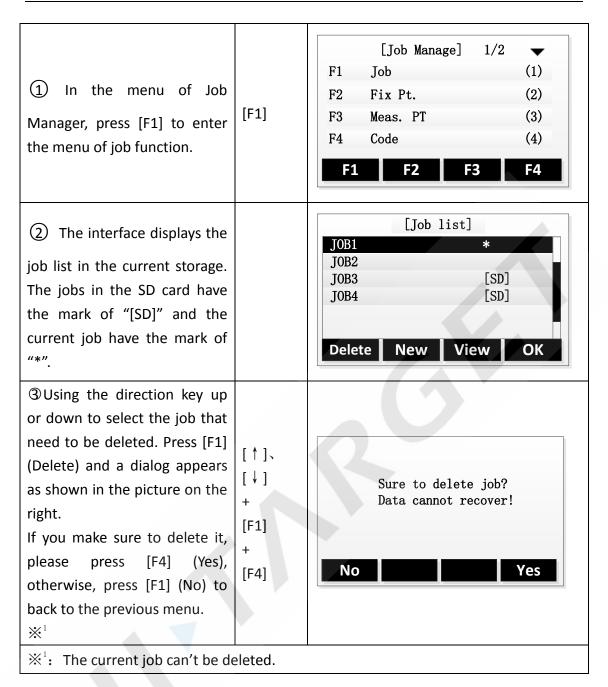
[Operator]: The name of operator and it can have the default value.

[Note1] and [Note2] describe the situation of the project and they can have the default values.

If the job name you inputted exists, the program will give a prompt that Job exists, use another job name.

1.3 Delete a job

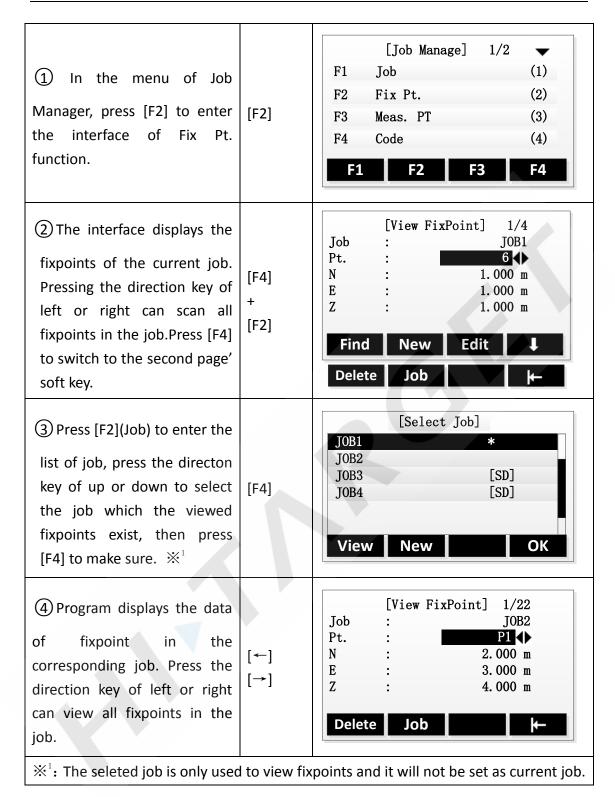
Operating Steps K	Display
-------------------	---------



2. Fix Pt.

The function can view, edit and delete the fixpoints in all jobs.

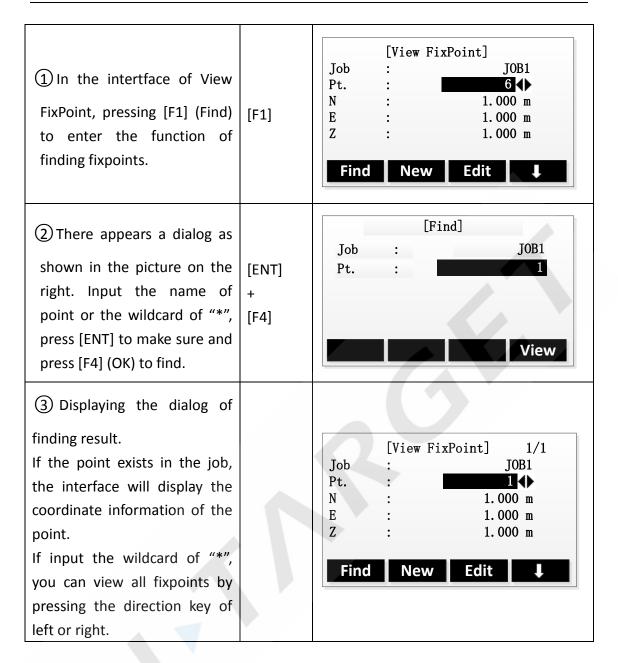
Steps	Key	Display
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2.1 Search Fix Pt.

Input the name of point or "*" to view the fixpoints in the selected job.

Steps	Key	Display
-------	-----	---------



2.2 Add Fix Pt.

Steps	Key	Display
① In the interface of View FixPoint, pressing [F2] (New) to enter the function of newing fixpoint. If you want to change the job which need to new points, you can press [Job] to select the target job.	[F2]	[View FixPoint] Job : JOB1 Pt. : 6 ← N : 1.000 m E : 1.000 m Z : 1.000 m Find New Edit Continuous

(2) There appears a dialog as [New FixPoint] JOB1 Job Pt. shown in the picture on the N right. If want to back to the E previous menu, you can press [F1] (Back). Back (3) Input the new name and coordinate of fixpoint, press [New FixPoint] JOB1 Job [Ent] to finish inputing and Pt. 100.000 m N press [F4] (OK) to save the 100.000 m Ε fixpoint. 100.000 m Back If the inputted point name exists in the memory, the PT exists! program will give a prompt of If overwrite? whethe to overwrite, press [F4](Yes) to overwrite or press [F1](No) to cancle the operation. (4) After finishing newing a [New FixPoint] fixpoint, the program makes Job JOB1 Pt. the point plus 1 automatically 100.000 m N and you can continue to input E 100.000 m 100.000 m other fix points, as shown in the picture on the right. Back OK Press [F1] (Back) or [ESC] to go back.

2.3 Edit Fix Pt.

The function can edit the fixpoints in the memory.

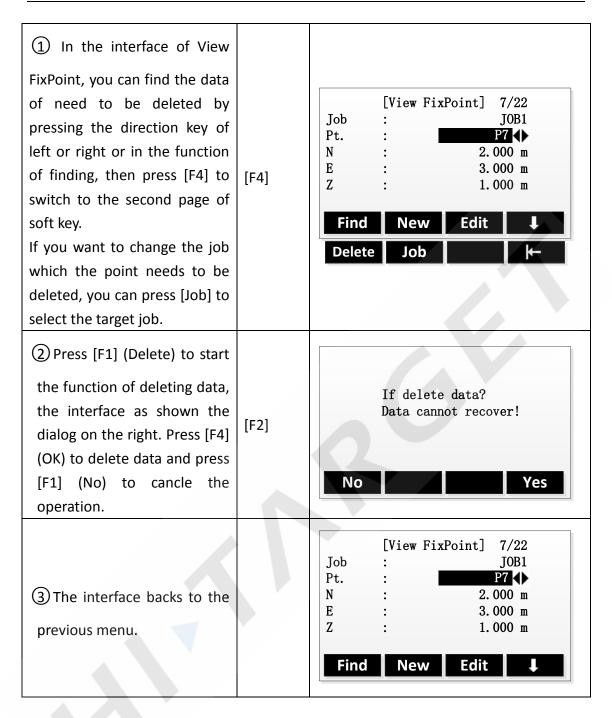
Steps Key	Display
-----------	---------

1) In the interface of View FixPoint, you can find the data [View FixPoint] 7/22of need to be edited by Job JOB1 Pt. P7 **♦** pressing the direction key of N 2.000 m left or right or in the function E 3.000 m 1.000 m of finding. If you want to change the job which the Find New Edit point needs to be edited, you can press [Job] to select the target job. 2) Press [F3] (Edit) to enter the interface of Edit Fixpoint. [Edit FixPoint] The screen displays the point JOB1 .Tob Pt. data. Input the new point's 2.000 m N name and coordinate and 3.000 m E Z 1.000 m press [ENT] to move the cursor to the next row. When the Back OK data doesn't need to be edited, you can press [ENT] directly. [Edit FixPoint] ③ Press [F4] (OK) to save the JOB1 Job Pt. P7 edited data after finishing 12.000 m N inputing. Program gives a 13.000 m 5.000 m prompt wheter to overwrite or not and press [F4] (OK) to Back overright and save.

2.4 Delete Fix Pt.

Delete the selected fixpoint from the job.

Operating Steps	Key	Display
-----------------	-----	---------

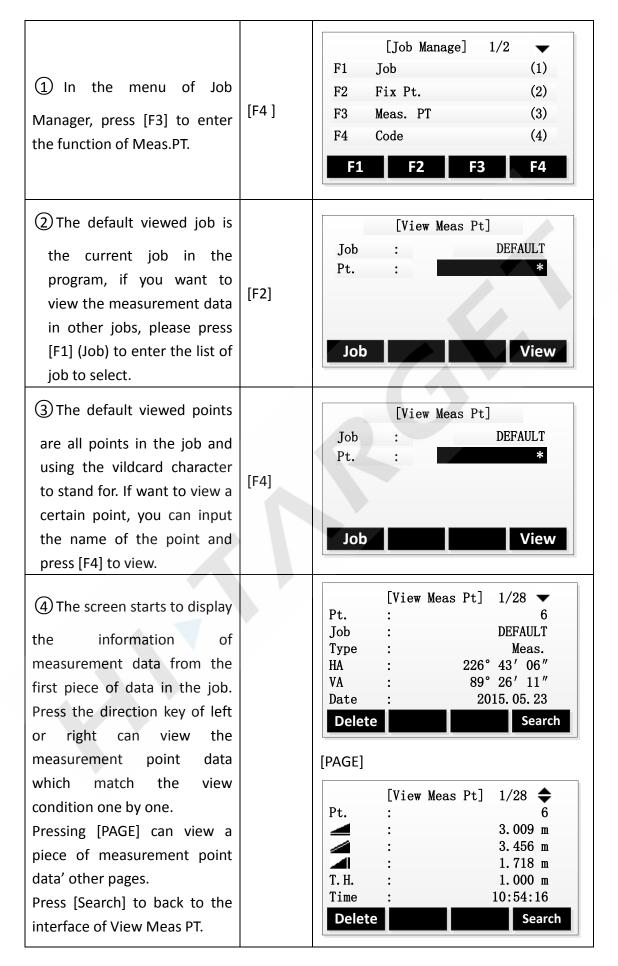


3. Meas. Pt.

The measurement data in the job can be searched, displayed, and part of them can be deleted.

3.1 View the measurement data

Steps	Key	Display
-------	-----	---------



3.2 Delete measurement data

The not good and the repeating measurement data can be deleted.

The station data and the last piece of data in the data items can not be deleted.

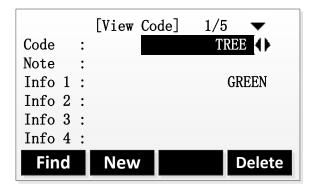
Steps	Key	Display
① After finding the measurement point data which need to be deleted, press [F1] to delete.	[F1]	[View Meas Pt] 1/28 ▼ Pt. : 6 Job : DEFAULT Type : Meas. HA : 223° 44′ 06″ VA : 88° 20′ 11″ Date : 2015.05.23 Delete Search
② The window of program prompts whether to delete or not. Press [F4] to make sure to delete and press [F1] to cancle the operation.	[F4]	If delete data? Data cannot recover!
③ After the data is deleted, the screen displays the next piece of data.	[F4]	[View Meas Pt] 1/27 ▼ Pt. : 7 Job : DEFAULT Type : Meas. HA : 220° 40′ 06″ VA : 90° 20′ 11″ Date : 2015. 05. 23 Delete Search

4. Code.

Here can make operations on the code library, such as newing, finding and deleting.

4.1 Input Code

Every code has a note and up to 8 characters attributes.



GSI-The introduction of code' attributes:

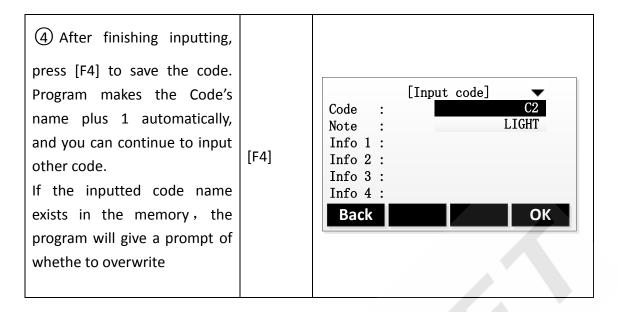
Code: Name of the code
Note: Additional annotation

Info1: The other editable information

••••

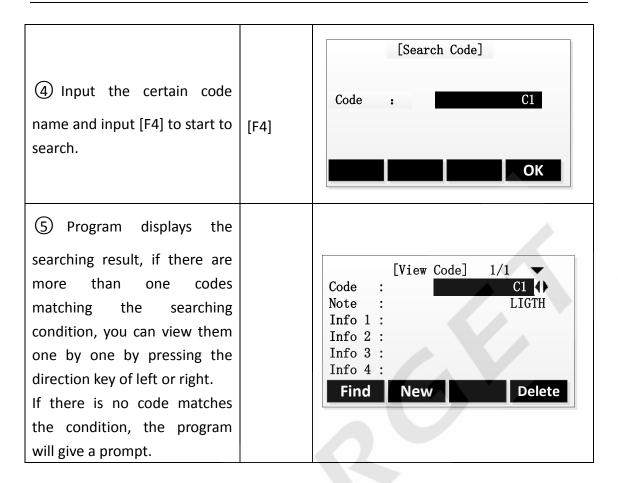
Info8: Other information

Steps	Key	Display
① In the menu of Job Manage, pressing [F4] to enter the function of Code.	[F4]	[Job Manage] 1/2 ▼ F1 Job (1) F2 Fix Pt. (2) F3 Meas. PT (3) F4 Code (4) F1 F2 F3 F4
② In the interface of View Code, pressing [F2] to enter the function of newing code.	[F2]	[View Code] 1/5 ▼ Code : TREE () Note : Info 1 : GREEN Info 2 : Info 3 : Info 4 : Find New Delete
③ Input the name of code and the code information in the interface of Input code.		[Input code]



4.2 View Code

Steps	Key	Display
① In the menu of Job Manage, pressing [F4] to enter the function of Code.	[F4]	[Job Manage] 1/2 F1 Job (1) F2 Fix Pt. (2) F3 Meas. PT (3) F4 Code (4) F1 F2 F3 F4
② Press the direction key of left or right, you can view all codes one by one.		[View Code] 1/5 ▼ Code : TREE () Note : Info 1 : GREEN Info 2 : Info 3 : Info 4 : Find New Delete
③ Press [F1] to enter the interface of Search Code. The default vaue is wildcard character, it stands for all codes.		[Search Code] Code : *



4.3 Delete Code

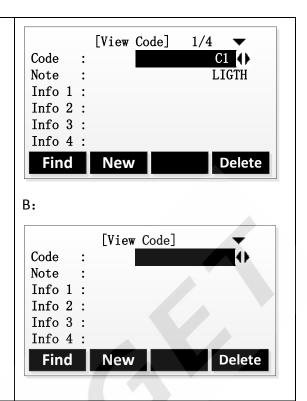
Operating Steps	Key	Display
① After entering the dialog of code function, press the direction key of left or right to delete the code which need to be deleted. You can also press the key of [Find] to find the corresponding code.		[View Code] 1/5
② After finding the code need to be deleted, press [F4] and program will give a prompt whether make sure to delete.	[F4]	A:

Α:

If the deleted code is finded by pressing the direction keys, after the code is deleted, the screen will display the next code.

В:

If the deleted code which finded by press the key of [Find], after the code deleted, the interface displays an empty code, it means that all fields are empty. If there is more than one code matching the finding condition, it will display the next code.



5. Memory Statistics

Display the information of the memory usage and format the memory.

Format the memory can delete all data of job, code and road. The setting of application also can be reset, please operate carefully.

Steps	Key	Display
① In the menu of Job Manage, press [PAGE] and display the second page of the menu, press [F1] to enter the function of memoty statistics.	[F1]	[Job Manage] 2/2
2 Program displays the disk list of the instrument, the default are "A: Local Disk", if instrument has loaded the SD card, it will display the additional disk of "B: SD".	7	[Disk List] A:Local Disk B:SD Prop. Format OK
③ Press [F1] (Prop.) can view the properties of the disk, including free space.	[F1]	[Disk Info.] Disk Name: A:Local Disk Disk Space: 2036 KB Used Space: 48 KB Free Space: 1988 KB Format OK
4 Press [F2] (Format) can format the disk, program will give a prompt to make sure to format or not, press [F4] to make sure to format and press [F1 to cancle the operation.]	[F2]	Sure to format? Data cannot recover! No Yes
\mathbb{X}^1 : SD card does not support the formatting operation in the instrument.		

7. Data Transfer

This function is doing data transmission between instrument and computer, or between instrument and removable device. This function includes 2 parts, import and export.

The data transmission between instrument and removable device must have UDisk plugged in.

1. Data Import

User can use this function to transfer fixed points data or code data to instrument from computer via RS232 cable. User can also transfer fixed points data to instrument via UDisk.

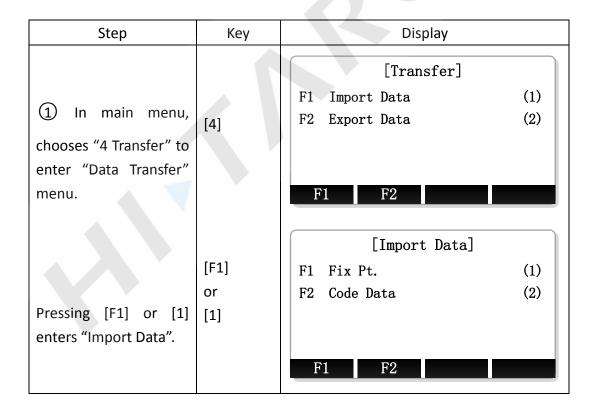
Import: Fixed Points, Code

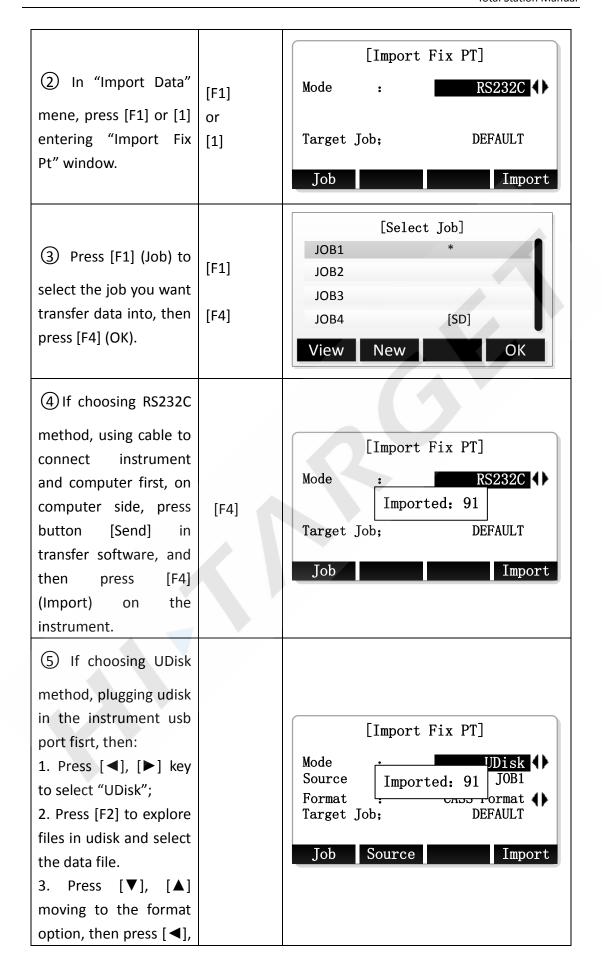
Method: RS232, UDisk

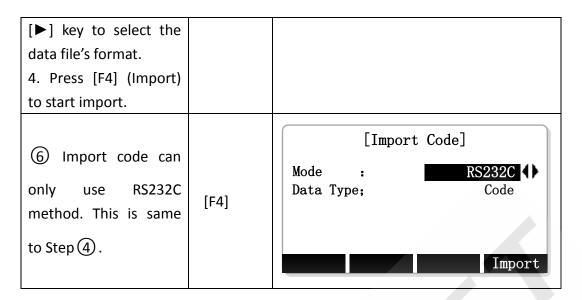
Format: CASS, GTS-7 (For UDisk)

Source: Data file in UDisk (For UDisk)

Job: Target job that data been transfer to.







2. Data Export

User can use this function to transfer internal data (fixed points, measurement data, and code) from instrument to computer or udisk.

Export: Fixed points, measure data, and code.

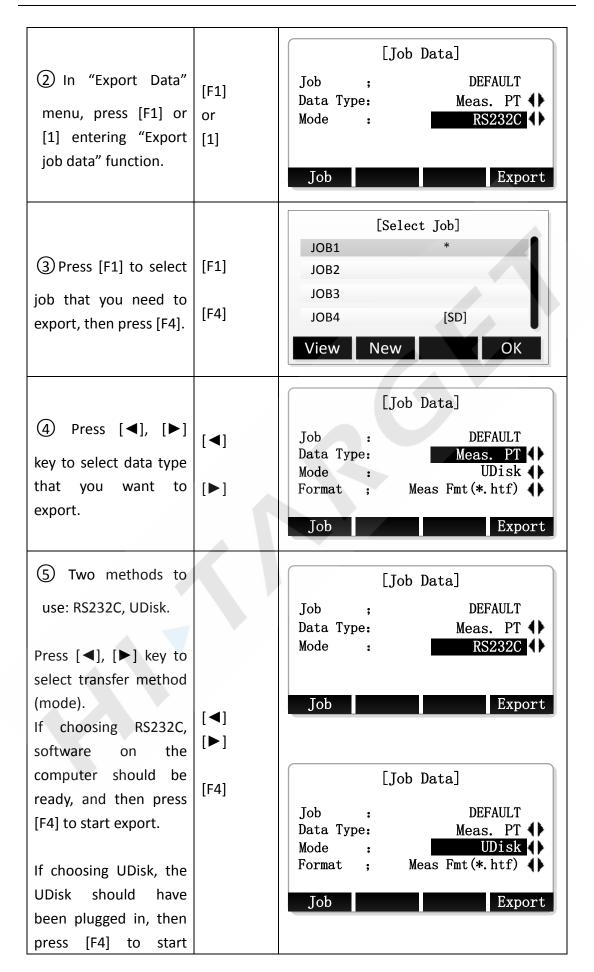
Method: RS232C, UDisk.

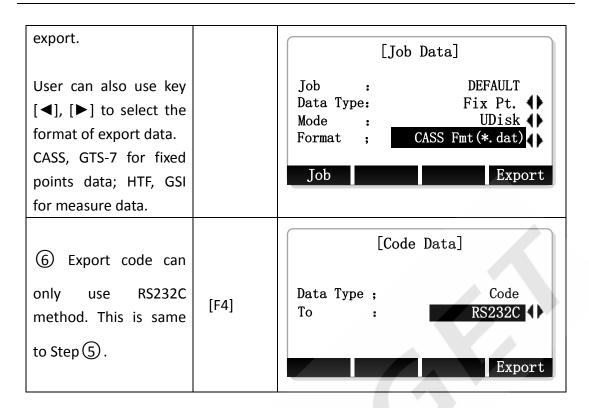
Format: CASS, GTS-7 (For fixed point, UDisk)

HTF format, GSI format (For measure data, UDisk)

Job: Job needs to export.

Step	Key	Display
① In main menu, chooses "4 Transfer" to enter "Data Transfer"	[4]	[Transfer] F1 Import Data (1) F2 Export Data (2)
Pressing [F2] or [2] enters "Export Data".	[F2] or [2]	[Export Data] F1 Job Data (1) F2 Code Data (2)
enters Export bata .		F1 F2

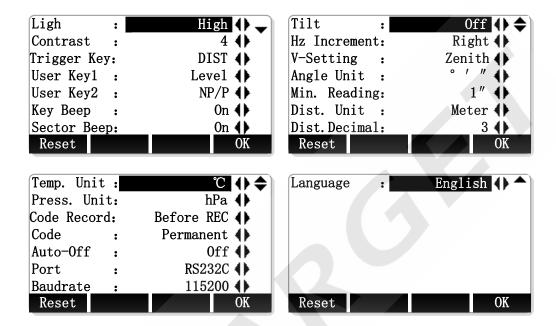




8. Instrument Setting

1. General Setting

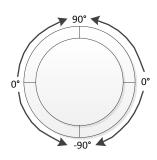
In Setting Menu, choose "1 General" to enter "General Setting".



Fields of General Setting

Field	Description			
Light	Hight, Medium, Low, Off. 4 Levels of background light.			
Contrast	1~9. Set the display contrast.			
Trigger Key	Off: Disable trigger key.			
	ALL: Disting and record.			
	DIST: Only disting.			
User Key 1	Configures with a function from the FNC menu.			
User Key 2	Configures 2 with a function from the FNC menu.			

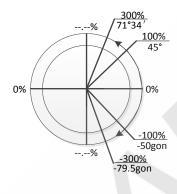
Key Beep	The beep is an acoustic signal after each key stroke.			
Rey Beep	The beep is an acoustic signal after each key stroke.			
	On: Enable beep.			
	Off: Disable beep.			
Sector Beep	On: Sector Beep sounds at right angles (0 $^{\circ}$, 90 $^{\circ}$, 180 $^{\circ}$, 270 $^{\circ}$ or 0, 100, 200, 300 gon).			
	Off: Sector Beep diabled.			
Tilt	On: Tilting compensation enable.			
	Off: Tilting compensation disable.			
Hz increment	Right: Set horizontal angle to clockwise direction measurement.			
	Left: Set horizontal angle to counter-clockwise direction measurement.			
V-Setting	Zenith: Zenith = 0° ; Horizon = 90° .			
	270° 90° 180°			
	Horiz.0: Zenith = 270°; Horizon = 0°. Vert90: Zenith = 90°; Horizon = 0°; Positive above horizon, negative below horizon.			



Slope: Zenith $45^{\circ} = 100\%$; Horizon = 0%.

Positive above horizon, negative below horizon.

Exceed 300% shows "--.--%".



Angle Unit

Sets The units shown for all angular fields.

 $^{\circ}$ $^{\prime}$ $^{\prime\prime}$ Degree sexagesimal, 0° to 359 $^{\circ}$ 59'59".

Gon, 0 gon to 399.999 gon.

Mil, 0 to 6399.99mil.

The setting of the angle units can be changed at any time. The actual displayed values are converted according to the select unit.

Mini. Reading

Sets the number of decimal places shown for all angular fields. This is for data display and does not apply to data export or storage.

° ′ ″ 0° 00' 01" /0° 00' 05"/0° 00' 10"

Gon 0.0002/ 0.001 / 0.002

	Mil 0.005 / 0.02 / 0.05			
DIst. Unit	Sets the units shown for all distance and coordinate related fields.			
	Meter Meters [m].			
	US-ft US feet [ft].			
	INT-ft International feet [fi].			
	ft-in1/8 US feet-inch-1/8 inch [ft].			
Dist.Decimal	Setes the number of decimal places shown for all distance fields. This is for data display and does not apply to data export or storage.			
	3 Display distance with three decimals.			
	4 Display distance with four decimals.			
Temp. Unit	Sets the units shown for all temperature fields.			
	℃ Degree Celsius.			
	T Degree Fahrenheit.			
Press.Unit	Sets the units shown for all pressure fields.			
	hPA Hecto Pascal.			
	mmHg Millimeter mercury.			
	inHg Inch mercury.			
Code Record	Sets if the codeblock is saved before or after the measurement.			
Code	Sets if the code will be used for one, or many, measurements.			
	Rec/Reset The code is cleared after ALL or REC.			
	Permanent The code remains after measurements.			
Auto-Off	30min Auto poweroff after 30min's no operation.			

	Off Disable auto-off.				
Port	RS232C Use serialport as communication interface.				
	Bluetooth Use Bluetooth as communication interface.				
	If instrument does not support Bluetooth, there will be no Bluetooth option here.				
Baudrate	Sets the serialport baudrate.				
	9600/19200/115200				
Language	Changes the software's interface language.				

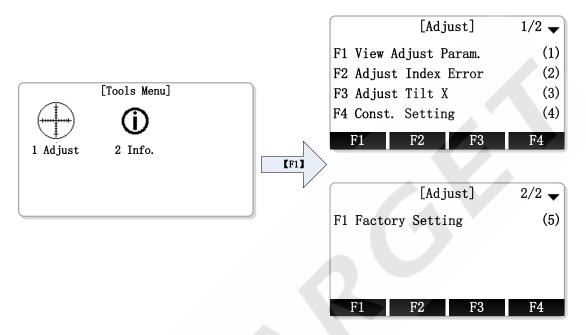
2. EDM Setting

See Chapter "3.2 EDM Setting".

9. Adjust and Tools

1. Adjust

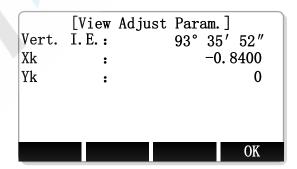
Through Main Menu \rightarrow "6 Tools" \rightarrow "1 Adjust", entering adjust menu,. Like below:



1.1 View adjust parameters

In Tools Menu, choose "1 Adjust", and then press [F1] to enter "View adjust parameters".

Parameters include Vert.I.E and tilt sensor parameters.

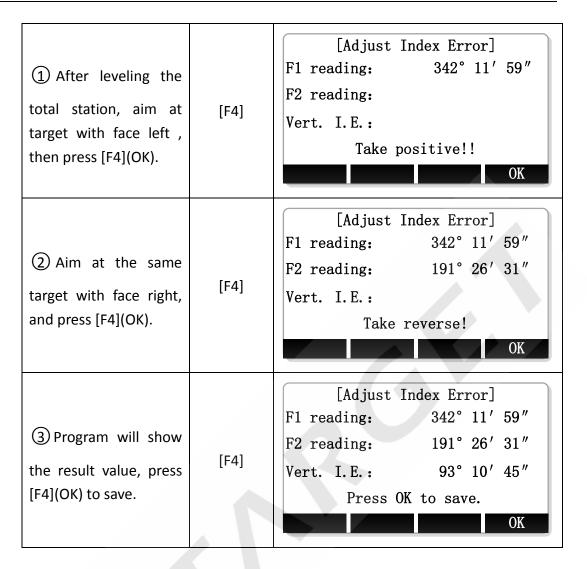


1.2 Adjust Index Error

In Tools Menu, choose "1 Adjust", then press [F2] to enter "Adjust Index Error".

Steps:

_		
Sten	l Kev	l Disnlav l
Jicp	I IC	Display



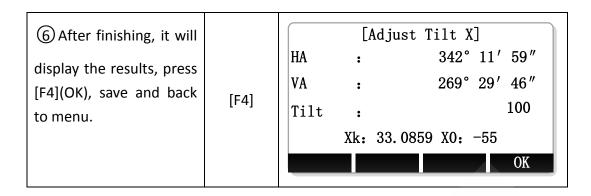
1.3 Adjust Tilt X

In Tools Menu, choose "1 Adjust", and then press [F2] to enter "Adjust Tilt X".

These are the calibaration of x-diretion of compensator's vertical axis.

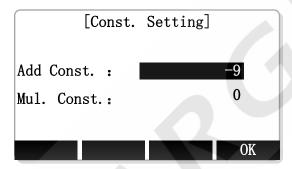
Step	Key	Display
① Level instrument, focus on the reticle of collimator, record the vertical angle V0. Use fine tuning to set vertical angle to V0+3', focus on the reticle center accurately, wait	[F4]	[Adjust Tilt X] HA : 10° 12′ 02″ VA : 81° 53′ 49″ Tilt : -117 F1 up 3′ OK

for stable value, press [F4](OK). ② Use fine tuning to set the vertical angle to V0-3', focus on the reticle center accurately, wait for stable value, press [F4](OK).	[F4]	[Adjust Tilt X] HA : 10° 12′ 02″ VA : 81° 59′ 50″ Tilt : -86 F1 down 3′
3 Use fine tuning to set the vertical angle as V0, focus on the reticle center accurately.		
4 Reverse the telescope, use face right to focus on the reticle of collimator, record the vertical angle V1. Use fine tuning to set the vertical angle as V1-3', focus on the reticle center accurately, wait for stable value, press F4(OK).	[F4]	[Adjust Tilt X] HA : 190° 25′ 38″ VA : 269° 23′ 45″ Tilt: 96 F2 up 3′ OK
(5) Use fine tuning to set the vertical angle as V1+3', focus on the reticle center accurately, wait for stable value, press [F4](OK).	[F4]	[Adjust Tilt X] HA : 342° 11′ 59″ VA : 269° 29′ 46″ Tilt: 91 F2 down 3′ OK



1.4 Instrument constant setting

In Tools Menu, choose "1 Adjust", and then press [F4 to enter "Const. Setting". Press [F4](OK) to save after editing the constants.



1.5 Factory setting

In Tools Menu, choose "1 Adjust", and then press [5] to enter "Factory Setting". If you need to reset the instrument parameters to factory state, you can use this function, press key [F4] (Yes) and then the instrument will auto power off.

2. System infomation

2.1 View System Information

In Tools Menu, choose "2 Info." to enter "Info".

In this window, user can view detail information about the instrument, includes instrument type and SN, firmware version and date time.

Inst. Type: Inst. No.: FW. Ver.: Time:		nfo.] HTS-420 series 648164 V1.0 (20151103) 13:42:28	
Date :		2015. 11. 12	
Date	Time	Upgrade	Back

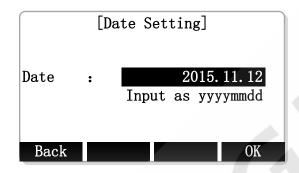
System Infomation

2.2 Set System Date

In system information window, press [F1] (Date) to enter "Date Setting" window.

To set the date, input the new date string that in the format of tips, then press [F4] (OK) to save the new date.

For example: To set date "2015-11-11", input string "20151111", then press [F4] (OK) to save.



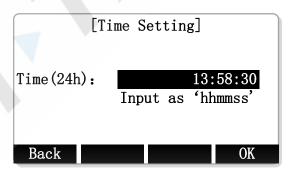
Date Setting

2.3 Set System Time

In system information window, press [F2] (Time) to enter "Time Setting" window.

To set the time, input the new time string that in the format of tips, then press [F4] (OK) to save the new time.

For example: To set time "13:58:30", input string "135830", then press [F4] (OK) to save.

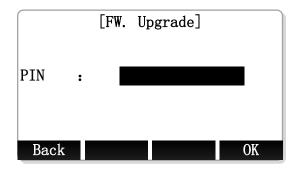


Time Setting

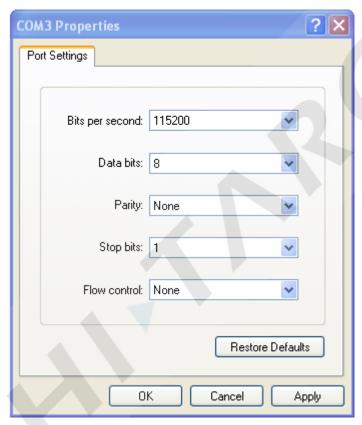
2.4 Firmware Upgrade

This function is prepared for the users to upgrade the instrument software.

1. Input PIN code(82543), and then press key ENT, the instrument will be turned off.

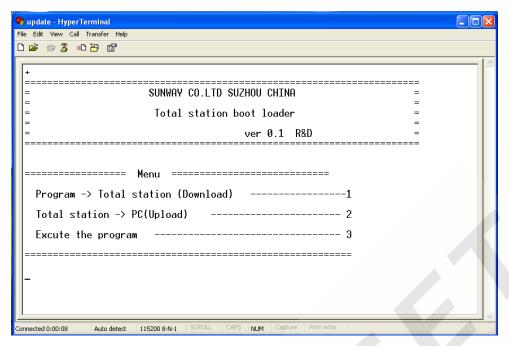


 Connected to the computer through a serial cable, after installing the correct driver premise, open a HyperTerminal software, configure the correct serial port, it will "bits / sec" is set to 115200, "Data Flow Control" is set to "None" and press OK.

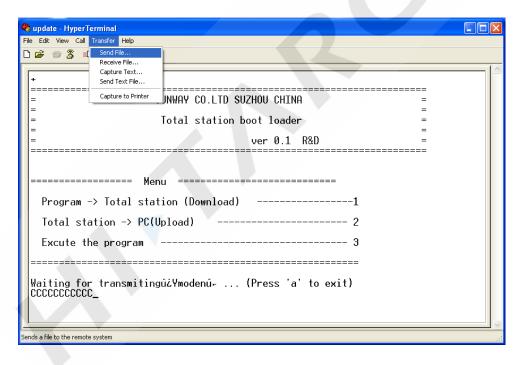


3. Press the power key of the instrument in Hyper Terminal, shown as follows:

Note: Software upgrade operation must be careful once you select the instrument into the upgrade status; if press "3" in the picture below, you can also resume running the previous program.



4. Press 1 button on the keyboard into waiting to send program state, and then select "send file".



5. Select the new edition total station software, click on "send" button.

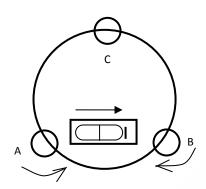


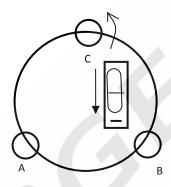
6. It will display the sending application process, and then close the super terminal, starting up after removing the instrument battery and then putting in again. The current software is the new version updated previously.

3. Checkout and calibration

The instrument at the factory has to undergo a rigorous inspection and correction, meeting the quality requirements. However, after long transport or environmental change, its internal structure will be some impact. Therefore, the new purchased instruments should be checked and calibrated before surveying to ensure the precision.

3.1 Tube level





Checkout

Refer to the chapter "Leveling instrument accurately by tube level "of" Setting up the instrument"

Calibration

- In the calibration, if the leveling bulbs diverge from the center, use the foot spiral which parallels the leveling tube to adjust to make the bubble move half of the distance to the center. For the remaining, use the calibration needle to turn the level calibration screw (in the right of the water-level) to adjust the bubble to the center.
- 2. Turn the instrument for 180°, check that whether the bubble is in the center. If the bubble is not centered, repeat Step (1) until the bubble to the center.
- 3. Turn the instrument for 90°, use the third foot screw to adjust the bubble to the center.
- Repeat the Steps of checkout and calibration until the bubble in the center in every direction.

3.2 Circular level

Checkout

After the level tube calibrated correct, if the circular level bubble also in the center, so there is no need to calibrate

Calibration

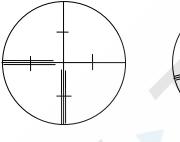
If the bubbles is not in the center, use the correction needle or six angle wrench to adjust the correction screw which under the bubble to make the buble to the center. For calibration, you shall first loosen the calibration screw (1 or 2) which opposite to the direction of the bubble offset, then tighten the other correction screw in the offset direction to make the bubble in the center. When the bubble is in center, make sure the pressures of the three calibration screws are consistent.

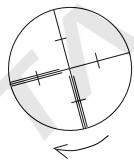
3.3 Telescope reticle

Checkout

After leveling the instrument find a target A with the telescope, make the center of the crosshair focused on target A and fixed horizontal and vertical brake handwheel.

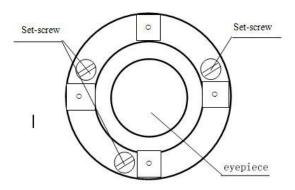
- 1. Rotate telescope vertical micrometer handwheel, move A point to the edge of the field of view (A 'points).
- If A moves along the vertical line of the crosshair, but A point is still in the vertical line, as the left picture, the crosshair doesn't need to calibrate. If A point deviate from vertical line center, as the right pictured, the crosshair is slant, so need to calibrate the reticle.





Calibration

- 1. First, take down the reticle cover between telescope eyepiece and focusing handwheel, and you can see four fixed screw of the reticle bed (sees attached figure).
- 2. Unscrew the three fixed screw evenly with screwdriver, rotate the reticle around collimation axis, to make A point on the vertical line of the reticle.
- 3. Tighten the screw evenly, test the calibration results with the above methods.
- 4. Put the protective cover back.



3.4 The verticality of collimation axis and horizontal axis (2C)

Checkout

- 1. Set a target A in about 100m away, and make sure the vertical angle of the target is within \pm 3°. Precisely level the instrument and switch on it.
- 2. Make the telescope focused on target A in face left, and read the horizontal angle.

For example: horizontal Angle L = 10°13 '10".

3. Loosen the vertical and horizontal brake handwheel, turn the telescope, rotate the alidade to face right and focus on the same target A. Before aiming please tighten the horizontal and vertical brake handwheel and read the horizontal angle.

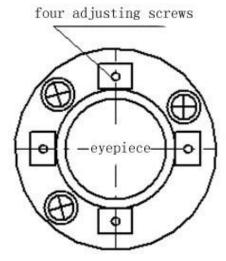
For example: level Angle R = 190°13 '40".

4. 2 C = L-(R \pm 180°) = -30 " \geq \pm 20, need to calibrate.

Calibration

1. Use the horizontal micrometer handwheel to adjust the horizontal angle to the right reading which has eliminated the C.

- 2. Take down the reticle bed cover between the telescope eyepieces and focusing handwheel, adjust the calibration screw of the crosshair on the left and right. First, loosen the screw on one side, and screw up the screw on the other side, move the reticle and focus on target A.
- 3. Repeat the test Steps, calibrate it to | 2 C | < 10.
- 4. Tighten the calibration screws, put the protective cover back.



Notice: Check the photoelectric coaxiality after calibrating.

3.5 Vertical plate index zero automatic compensation

Checkout

- 1. Set up and level the instrument, make the direction of the telescope consistent with the line between the center of the instrument and any of the foot screw.
- 2. The vertical plate index change to zero after switching on, tighten the vertical brake handwheel, the instrument display the current telescope vertical angle.
- 3. Slowly rotate feet X to 10 mm around in one direction, the display of the vertical Angle will change from changing until disappear to appear "compensation beyond!" correspondingly, it indicate that the dip angle of the verticalaxis is bigger than 3', beyond the range of vertical plate compensator design. When rotating the feet spiral recovery in the opposite direction, instruments shows vertical Angle again, if you can see the change when testing it again and again in critical positions, it says that vertical plate compensator works normally.

Calibration

When you find that instrument compensation is useless or abnormal, it should be sent to the factory for checking.

3.6 Vertical collimation error (I Angle) and vertical collimation zero value setting

Checkout

1. Boot after settling and leveling the instrument, focus the telescope on a clear goal A, get the face left reading of vertical Angle L.

- 2. Turn the telescope to aim A and get the reading R for face right.
- 3. If the vertical zenith angle is 0 °, then i = (L + R-360 °) / 2, if the vertical Angle level is 0. Then i = (L + R-180 °) / 2 or (L + R-540 °) / 2.
- 4. If | i |≥10", may be you need reset the zero value of vertical index.
- 5. Operation refers to chapter "Adjust index error". Note: repeat the checkout steps to retest the index error again (i Angle). If the index error still can not accordance with requirements, it should check the three Steps of calibration index zero setting (in the course of zero setting, the vertical angle showed is not compensated and corrected, it is just for reference) to see whether it is incorrect, whether the focusing of target is correct, reset according to the requirements.
- 6. If it still can not accordant with the requirements after repeated operation, it should be sent to the factory for checking.

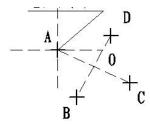
3.7 Plummet

Checkout

- 1. Set up the instrument to the tripod, draw a cross on a white paper and put it on the ground below the instrument.
- 2. Adjust the focal length of the optical plummet (for the optical plummet) or switch on laser plummet, move the white paper to make the cross in the center in the field of view (or laser flare).
- 3. Turn the feet screw, make the center mark of the plummet coincide with the cross center.
- 4. Rotate alidade, every turn of 90 °, observe the contact ratio of the optical plummet and cross center.
- 5. When rotate the alidade, the center of the optical plummet always coincide with the cross center, there is no need to calibrate. Otherwise you should calibrate as the following methods.

Calibration

- 1. Take down the screw cover between the optical plummet eyepiece and the focusing handwheel.
- 2. Fix the white paper with a cross, and mark the points when the instrument rotates 90 °, as the figure shows A, B, C, D points.
- 3. Connect the diagonal points A、C and B、D with a straight line, the intersection name of the two line is O.
- 4. Use the calibration needle to adjust the four calibration screw, to make the center mark of the plummet coincide with point O.



- 5. Repeat Step 4, check and calibrate until it meet the requirements.
- 6. With the laser plummet, unbolt the laser cover, using 1 # hex wrench to adjust the three screws, fasten one side and loosen the other side, and adjust the laser flare to point O.
- 7. Put the cover back in place.

3.8 Instrument additive constant (K)

The instrument constant is inspected when it out, and correct it inside the machine, make K = 0. Instrument constant change rarely, but we suggest that check it this way for one or two times each year. The checkout should be done in the standard baseline, or you can take the following simple method.

Checkout

- Choose a flat field A to set up and level the instrument, mark three points A
 B
 C in the same line, their interval is 50m, and set up the reflection prism accurately.
- 2. After setting the temperature and pressure data, accurately measure the horizontal distance of AB, AC.
- 3. Setting up and centering the instruments accurately, measure the horizontal distance of BC accurately.
- 4. You can get the instrument ranging constant:

$$K = AC - (AB + BC)$$

K should be close to 0, if |K| > 5 mm, it should be send to standard baseline field for strict checking, then calibrate it based on the checking value.

Calibration

If it turns out the instrument constant does not close to 0 but changing after strict inspection, you need to calibrate it, set the instrument additive constant according to the comprehensive constant K value. Such as: the K has been measured as -5 according to the method above, and the original instrument constant is -20,so the new value should be set as -20-(5) =-15; Input-15 through "menu-> 6-> 3" and then confirm .

Use the vertical line of the reticle to orientate, make A, B and C at the same line accurately. There must be a clear mark for point B the ground to focus on.

Whether the prism center of B coincide with the instrument centers is the guarantee of checking the accuracy, so, you had better use tripod and all-purpose tribrach, for example, if you change the three hand type prism connector with tribrach, keep the tripod and tribrach stable, just change the prism and the part above tribrach of instrument, and it can reduce the error of misalignment.

3.9 The parallelism of collimation axis and photoelectricity axis

Checkout

- 1. Set up the reflecting prism 50 meters long from the instrument.
- 2. Focus on the reflecting prism center with telescope crosshair accurately.
- 3. Open EDM signal, observe maximum value of the signal, and find the center of the launch axis.
- 4. Check whether the telescope crosshair center coincide with the emission photoelectricity axis center, if they coincide on the whole we can say it qualified.

Calibration

If the telescope crosshair center deviates from emission photoelectricity axis center largely, send it to professional repair and calibration department.

3.10 No prism ranging

The red laser beam is coaxial with the telescope, used for no prism ranging, and it is sent by telescope. If the instrument has been calibrated, red laser beams will coincide with the line of sight. External influence such as the vibration, the larger temperature change and other factors may make laser beam and viewing not overlap.

➤ Before precise ranging, you should check whether the direction of the laser beam is coaxial. Otherwise, it could lead to inaccuracy.

Warning:

Looking straightly at the laser is dangerous.

Prevention:

Don't look laser beams directly, or focus on others.

Checkout

Put the gray side of the reflector towards the instrument, and put it 5 meters and 20 meters away. Start laser direction function. Focus on the reflector center by the telescope crosshair center, and then check the position of the red laser point. Generally speaking, the telescope is equipped with special filter, human eyes cann't see laser point through the telescope, you can see the offset between the red laser

point and the reflector crosshair center, you can observe this above the telescope or at the side face of reflector . If laser center coincide with the crosshair center, it indicate that the adjustment meet required accuracy. If the offset between the points position and the mark of crosshair is out of limitless, it need to send it to professional department for adjustment.

10. Technical parameters

Model	HTS-420R
Angle measurement	
Angle measuring method	Absolutely code
Minimum readout	1"
Angle accuracy	2"
Telescope	
Magnification	30X
Field of view	1° 30′
Minimum sight	1.5m
Reticle	illuminated
Compensator	
System	Single-axis liquid-electric (Dual-axis Optional)
Working range	±3'
Setting Accuracy	1"
Distance Measurement	
Reflector (IR)	
Single Prism	3000m
(Atmosphere general/good)	3000111
Reflector (60mm×60mm)	800m
Accuracy (Fine/Coarse/Tracking)	2mm+2ppm
Measuring Time	2.46/16/0.66
(Single/Repeat/Traking)	2.4s/1s/0.6s
No Prism ranging (RL)	
Odometry Using a white target board	350m
Ranging Accuracy (Short Distance/Tracking/Prism)	3mm+2ppm
Measurement Time (Short Distance/Tracking/Prism)	2-6s
Communication	
Memory data capacity	20000 points (Except for the SD card)
Interface	Standard RS232 serial port (Blutooth optional)
Data format	ASCII
Operation	
Operation System	Real-time English Operation System

Display	Graphics:280*160 Pixels 3.2 inch
Keyboard(Second Keyboard)	Alphanumeric Keyboard
Laser Plummet	
Туре	Laser spot, step brightness Adjustment
Beam Accuracy	1 mm(1.5m instrument height)
Environmental	
Operation Temperature	-20°C~ + 50°C
Storage Temperature	-40°C∼ + 70°C
Dust &Water proof(IEC60529)	IP54
Weight	
Incl.Battery&Tribrach	5. 5kg
Power supply	
Battery Type	High capacity Lithium battery
Voltage/Capacity	7.4V 3000mAh
	16 hours (Optimal,new battery,measure one time at 30 seconds 25 °C,24
Working Time	hours
Measure Times	Around 12000

11. Attachment A Road calculation example

Horizontal Curve

1. Element

(1) Input elements

NO.	Element	Start X	Start Y	Azimuth	Length	Radius
1	Line	1099877.123	4578452.654	120.30250	88.12	
2	Tran.Curve				100	200
3	Circular Curve				80	200
4	Tran.Curve				50	200
5	Tran.Curve				45	-150
6	Circular Curve				125	-150
7	Tran.Curve				62	-150
8	Line				30	

(2) Calculate Middle pile coordinate interval: 25 Calculated value

NO.	Pile	X	Y
1	0.000	1099877.123	4578452.654
2	25.000	1099864.432	4578474.193
3	50.000	1099851.741	4578495.732
4	75.000	1099839.050	4578517.272
5	88.120	1099832.390	4578528.575
6	100.000	1099826.347	4578538.804
7	125.000	1099813.310	4578560.134
8	150.000	1099799.305	4578580.839
9	175.000	1099783.746	4578600.395
10	188.120	1099774.794	4578609.984
11	200.000	1099766.173	4578618.155
12	225.000	1099746.535	4578633.600
13	250.000	1099725.125	4578646.476
14	268.120	1099708.688	4578654.087
15	275.000	1099702.279	4578656.588
16	300.000	1099678.498	4578664.280

17	318.120	1099661.029	4578669.092
18	325.000	1099654.388	4578670.891
19	350.000	1099630.474	4578678.158
20	363.120	1099618.263	4578682.949
21	375.000	1099607.584	4578688.147
22	400.000	1099586.640	4578701.745
23	425.000	1099568.243	4578718.630
24	450.000	1099552.901	4578738.333
25	475.000	1099541.041	4578760.307
26	488.120	1099536.325	4578772.546
27	500.000	1099532.962	4578783.937
28	525.000	1099528.087	4578808.446
29	550.000	1099524.876	4578833.238
30	550.120	1099524.862	4578833.357
31	575.000	1099521.947	4578858.066
32	580.120	1099521.347	4578863.151

2. Intersection

(1) Input element

NO.	Х	Υ	A1	Radius	A2	Mileage
1	126595.622	326532.868				
2	127029.195	328544.441	711.09	2528.248	711.09	2057.769
3	126270.297	330165.767	550.05	2017.0340	0	0
4	126797.134	331957.950	0	1699.1193	504.844	0
5	129306.674	332294.008	636.169	2023.5527	550.938	0
6	130014.424	334370.388	0	0	0	0

(2) Calculate Middle pile coordinate Interval: 500

Calculated value

NO.	Pile	Х	Υ
1	0.000	126595.622	326532.868
2	500.000	126700.972	327021.643
3	1000.000	126806.322	327510.418
4	1105.563	126828.565	327613.611
5	1305.563	126868.121	327809.646

6 1500.000 126894.146 328002.286 7 2000.000 126892.623 328501.469 8 2500.000 126793.052 328990.623 9 2749.107 126707.910 329224.621 10 2949.107 126625.526 329406.849 11 3000.000 126604.016 329452.973 12 3099.107 126563.629 329543.472 13 3500.000 126444.885 329925.686 14 4000.000 126406.074 330422.894 15 4483.815 126485.817 330898.918 16 4500.000 126490.455 330914.423 17 5000.000 126703.815 331364.622 18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 23 6516.206 127965.099 332114.301 23 6516.206 127965.099 332114.355	_		T	
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10 2949.107 126625.526 329406.849 11 3000.000 126604.016 329452.973 12 3099.107 126563.629 329543.472 13 3500.000 126444.885 329925.686 14 4000.000 126406.074 330422.894 15 4483.815 126485.817 330898.918 16 4500.000 126490.455 330914.423 17 5000.000 126703.815 331364.622 18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 12887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998	8	2500.000	126793.052	328990.623
11 3000.000 126604.016 329452.973 12 3099.107 126563.629 329543.472 13 3500.000 126444.885 329925.686 14 4000.000 126406.074 330422.894 15 4483.815 126485.817 330898.918 16 4500.000 126490.455 330914.423 17 5000.000 126703.815 331364.622 18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.301 23 6516.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 12887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998	9	2749.107	126707.910	329224.621
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15 4483.815 126485.817 330898.918 16 4500.000 126490.455 330914.423 17 5000.000 126703.815 331364.622 18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129917.564 334086.224	13	3500.000	126444.885	329925.686
16 4500.000 126490.455 330914.423 17 5000.000 126703.815 331364.622 18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	14	4000.000	126406.074	330422.894
17 5000.000 126703.815 331364.622 18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	15	4483.815	126485.817	330898.918
18 5500.000 127038.580 331733.585 19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	16	4500.000	126490.455	330914.423
19 6000.000 127465.969 331989.592 20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	17	5000.000	126703.815	331364.622
20 6365.804 127816.349 332092.209 21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	18	5500.000	127038.580	331733.585
21 6500.000 127949.036 332112.201 22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	19	6000.000	127465.969	331989.592
22 6515.804 127964.700 332114.301 23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	20	6365.804	127816.349	332092.209
23 6516.206 127965.099 332114.355 24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	21	6500.000	127949.036	332112.201
24 6716.206 128162.844 332144.159 25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	22	6515.804	127964.700	332114.301
25 7000.000 128437.402 332215.044 26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	23	6516.206	127965.099	332114.355
26 7500.000 128887.275 332430.323 27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	24	6716.206	128162.844	332144.159
27 8000.000 129270.830 332749.096 28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	25	7000.000	128437.402	332215.044
28 8500.000 129564.769 333151.998 29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	26	7500.000	128887.275	332430.323
29 8785.668 129685.352 333410.708 30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	27	8000.000	129270.830	332749.096
30 8935.668 129735.494 333552.069 31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	28	8500.000	129564.769	333151.998
31 9000.000 129756.249 333612.961 32 9500.000 129917.564 334086.224	29	8785.668	129685.352	333410.708
32 9500.000 129917.564 334086.224	30	8935.668	129735.494	333552.069
	31	9000.000	129756.249	333612.961
33 9800.219 130014.424 334370.388	32	9500.000	129917.564	334086.224
	33	9800.219	130014.424	334370.388

Theoretical value

NO.	Pile	Х	Υ
1	0.000	126595.622	326532.868
2	500.000	126700.972	327021.643
3	1000.000	126806.323	327510.419
4	1105.563	126828.565	327613.611
5	1305.563	126868.121	327809.646
6	1500.000	126894.146	328002.286

7	2000.000	126892.623	328501.469
8	2500.000	126793.051	328990.623
9	2749.107	126707.910	329224.621
10	2949.107	126625.526	329406.849
11	3000.000	126604.016	329452.974
12	3099.107	126563.629	329543.472
13	3500.000	126444.885	329925.686
14	4000.000	126406.074	330422.895
15	4483.815	126485.817	330898.918
16	4500.000	126490.455	330914.424
17	5000.000	126703.815	331364.622
18	5500.000	127038.580	331733.585
19	6000.000	127465.969	331989.592
20	6365.804	127816.349	332092.209
21	6500.000	127949.037	332112.201
22	6515.804	127964.700	332114.301
23	6516.206	127965.099	332114.355
24	6716.206	128162.844	332144.159
25	7000.000	128437.402	332215.044
26	7500.000	128887.275	332430.323
27	8000.000	129270.830	332749.096
28	8500.000	129564.769	333151.999
29	8785.668	129685.352	333410.708
30	8935.668	129735.494	333552.069
31	9000.000	129756.249	333612.961
32	9500.000	129917.564	334086.224
33	9800.219	130014.424	334370.388

Vertical Curve

Input Intersection

Intersectio	Mileage	Elevation	Length
n	Of Slope changing PT	of Slope changing PT	
Start	0	324.325	0
1	508.36	329.247	84.560
2	1000.48	325.689	52.806
3	1320.236	320.563	120.000
4	1524.265	323.215	28.585
5	1699.888	324.585	31.445

End	1800.244	325.999	0
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Piles elevation

NO.	Mileage (Pile)	Calculated	Theoretical
		Value	Value
1	0.000	324.325	324.325
2	100.000	325.293	325.293
3	200.000	326.261	326.261
4	300.000	327.230	327.230
5	400.000	328.198	328.198
6	500.000	329.051	329.051
7	600.000	328.584	328.584
8	700.000	327.861	327.861
9	800.000	327.138	327.138
10	900.000	326.415	326.415
11	1000.000	325.636	325.636
12	1100.000	324.094	324.094
13	1200.000	322.490	322.491
14	1300.000	321.079	321.079
15	1400.000	321.600	321.600
16	1500.000	322.900	322.900
17	1600.000	323.806	323.806
18	1700.000	324.611	324.611
19	1800.000	325.996	325.996
20	1900.000	0.000	0.000
21	2000.000	0.000	0.000
22	2100.000	0.000	0.000

12. Attachment B File format introduction

These following example to instruct exported file format:

STA ST001,1.205,AD XYZ 100.000,100.000,10.000 BKB BS001,45.2526,50.0000 BS BS001,1.800 **HVD** 98.2354,90.2314,10.235 SC A1,1.800,CODE1 NEZ 104.662,99.567,10.214 SD A2,1.800,CODE1 HVD 78.3628,92.4612,4.751 A3,1.800,CODE1 SA ΗV 63.2349,89.2547

The first record consists of two lines:

this note

NOTE

SA

The information of first line: record type, name, elevation, code Such as:

STA refers to test site

BKB refers to back sight Angle data

BS refers to back sight

SC refers to coordinate data

SD refers to distance measurement data

The second line information: data types, data records Such as:

refers to Angle measurement data

NEZ refers that the following data are coordinates
 ENZ refers that the following data are coordinates
 HVD refers that the following data are horizontal Angle and vertical Angle and slope distance

HV refers that the following data are horizontal Angle and vertical Angle